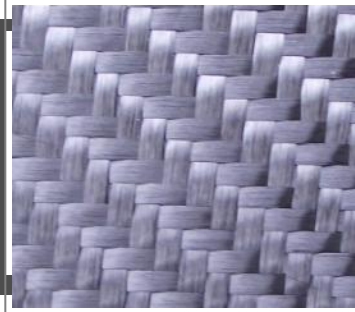


AFBW Fellbach



Die Simulationsprozesskette für faserbasierte Werkstoffe: Von der Herstellungssimulation zu Aussagen der Gebrauchstauglichkeit



Dr. Andre Haufe, Dr. Thomas Klöppel, Christian Liebold

DYNAmore GmbH
Stuttgart



DYNAmore GmbH

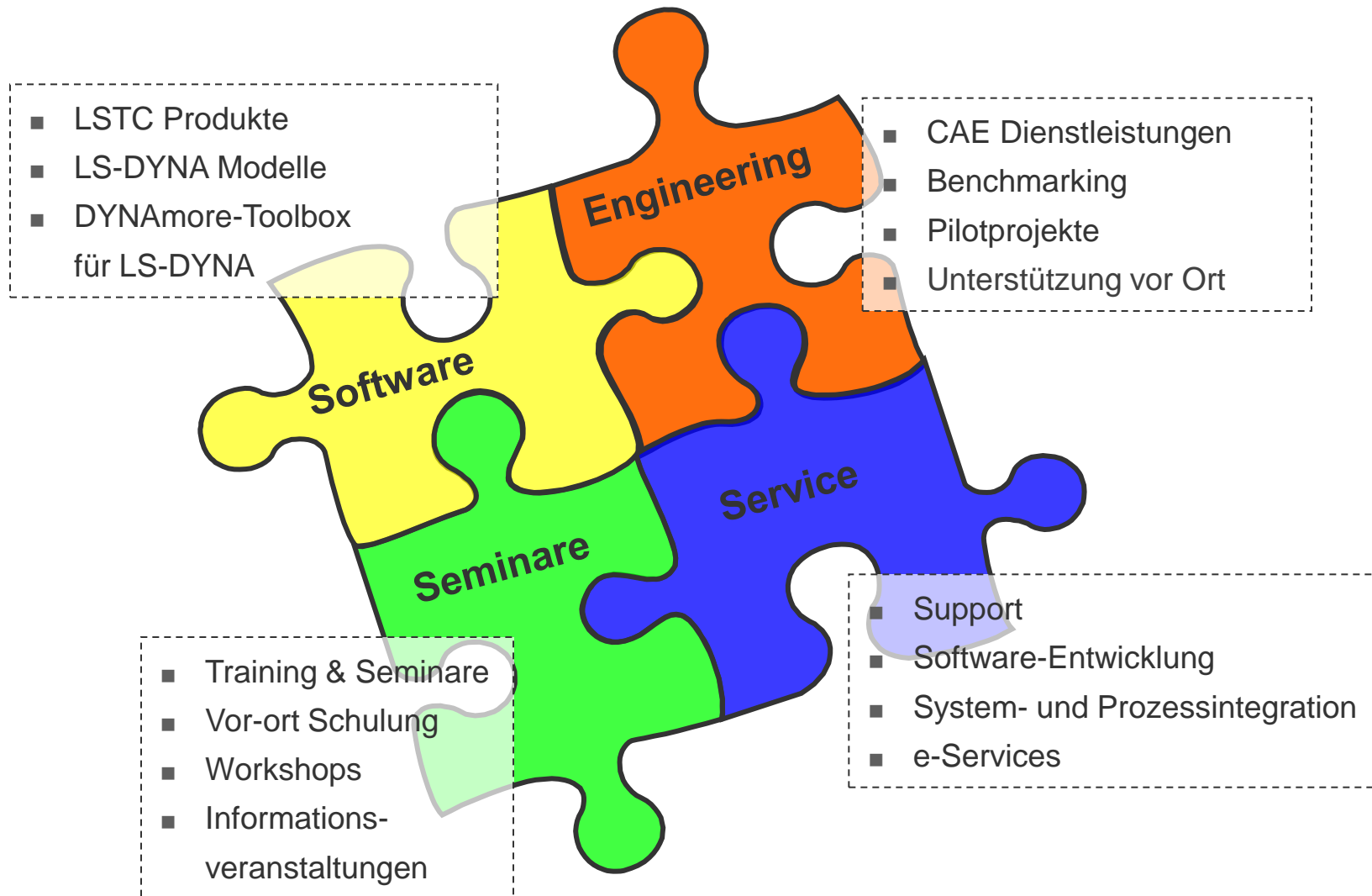
Gesellschaft für
FEM-Ingenieurdienstleistungen

**Stuttgart - Karlsruhe - Ingolstadt - Langlingen - Berlin
Dresden - Linköping - Götheburg - Zürich - Turin**

Industriestraße 2
D-70565 Stuttgart

Tel. 07 11 - 45 96 00 - 0
Fax 07 11 - 45 96 00 - 29
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Internet: www.dynamore.de

Portfolio



LS-DYNA 2013

9th European Users' Conference

2.-4. Juni 2013 in Manchester, UK

Themen:

- Crash
- Insassensicherheit
- Optimierung
- Airbag, Dummy
- Metallumformung
- Impact und Falltest
- Herstellungsprozesse
- Fluid-Struktur-Interaktion
- Automotive
- Schiffbau
- Luft- und Raumfahrt
- Offshore
- Transportation
- Biomechanik
- Bauwesen
- ...

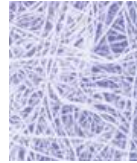
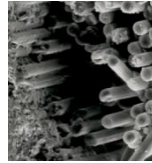


Courtesy of Dr. Ing. h.c. F. Porsche AG

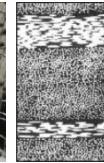
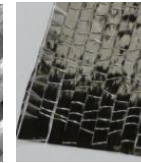
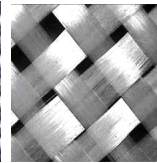
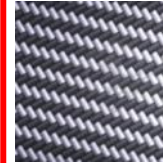
Introduction



Concrete
(cement/stone/steel)



**Short/long fiber
reinforced polymers**
(glass/PP)



**Endless fiber
reinforced polymers**
(glass/carbon/PA/PP/EP)



Sandwich/Laminates
(alloy/polymer/..glass/PVB/...)



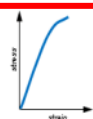
Weight & CO₂



Production issue



Part complexity



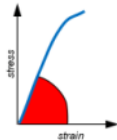
Stiffness & strength



Economic issue

Target: Predict serviceability in crashworthiness

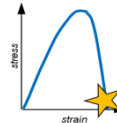
Status:



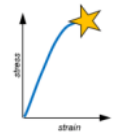
Mostly shell like structures.

Stiffness and/or deformation prediction possible

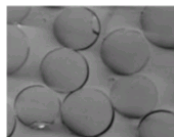
IF fiber content and/or orientation is known.



Failure prediction may be possible if failure mode can be engineered to be **ductile**.

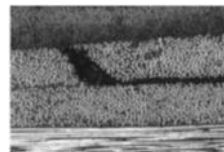


Brittle failure is hard to predict, because many different failure modes may exist due to mechanisms on different length scales:

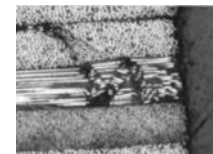


[μm]

micro



sub-ply



meso



[cm]

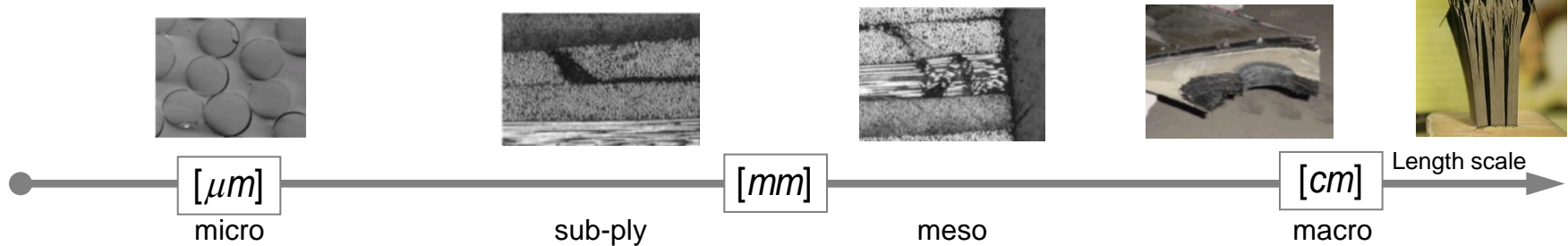
macro



Length scale

Target: Predict serviceability in crashworthiness

➡ Crushing/cracking/delamination/buckling on different length scales...



➡ Optimal product design? New approaches in CAE necessary!



Steel/Alloy

Isotropic
Elasto plastic
Ductile



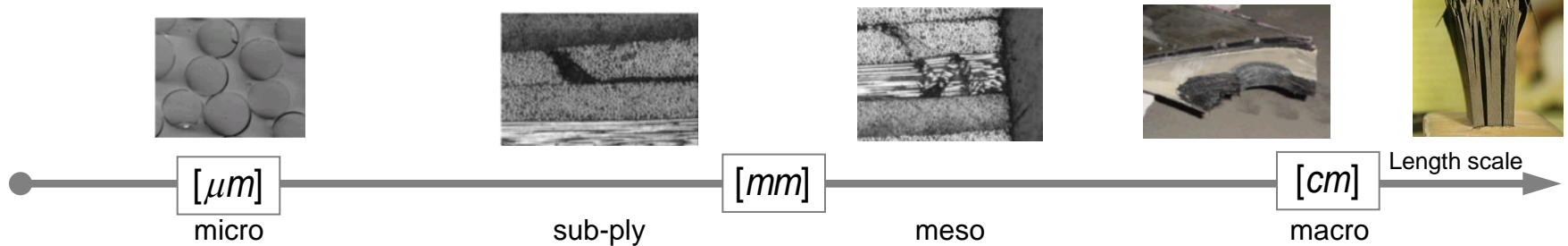
CFRP

Anisotropic
Stacked laminate
Elastic
Brittle failure

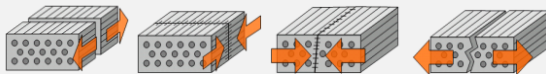


Target: Predict serviceability in crashworthiness

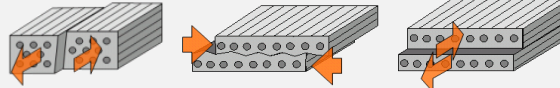
➔ Crushing/cracking/delamination/buckling on different length scales...



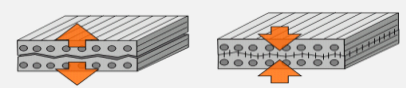
T/C in plane



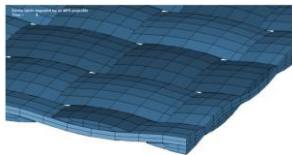
Shear



T/C out of plane

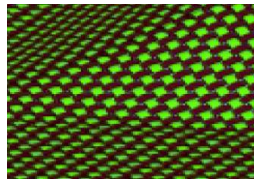


Meso-model to capture structural effects

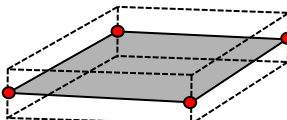


Solid elements

Shell elements

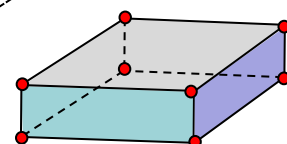


Macro-model (smeared out properties)



Shell element

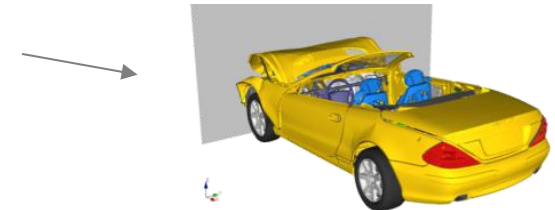
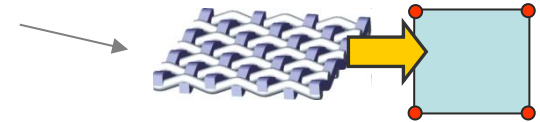
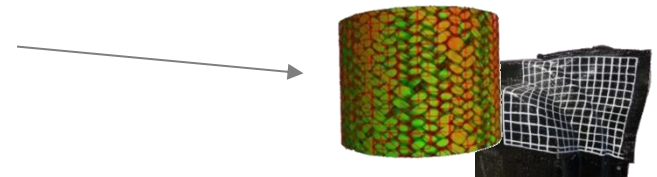
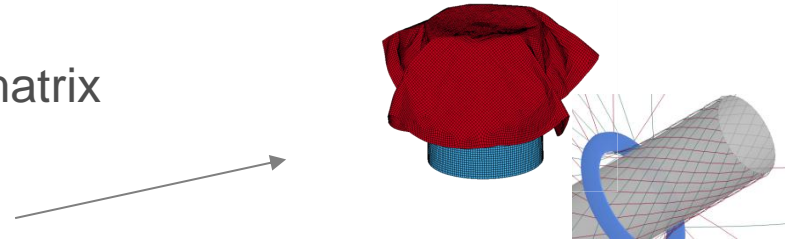
Solid element



Charact. element length: 3mm

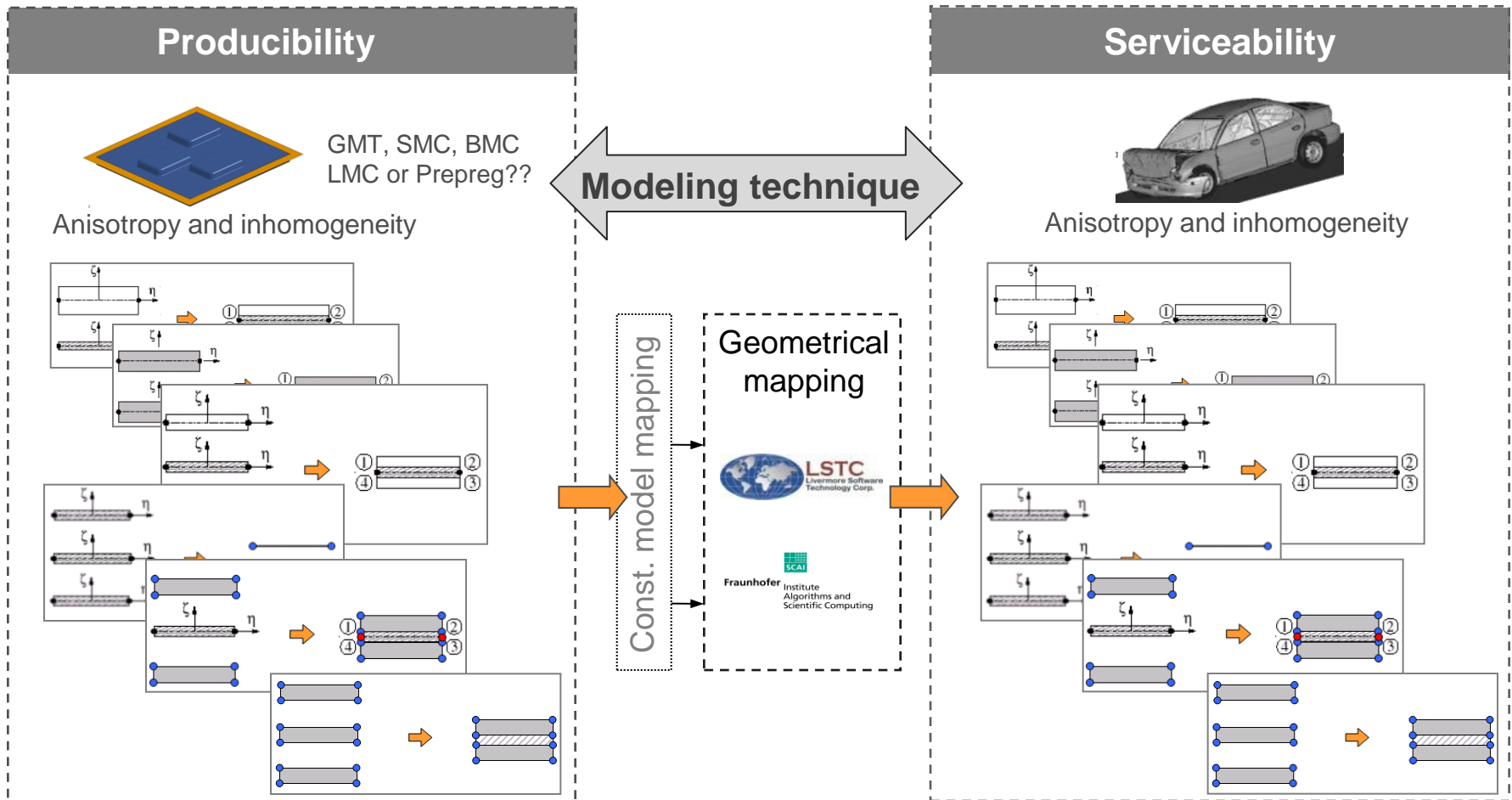
Main issues to solve:

- Know fiber influence (orientation) and matrix properties on relevant length scale
 - producibility simulation
 - Measurements
- Homogenize and map data to target length scale
- Find suitable (predictive) models on that scale!



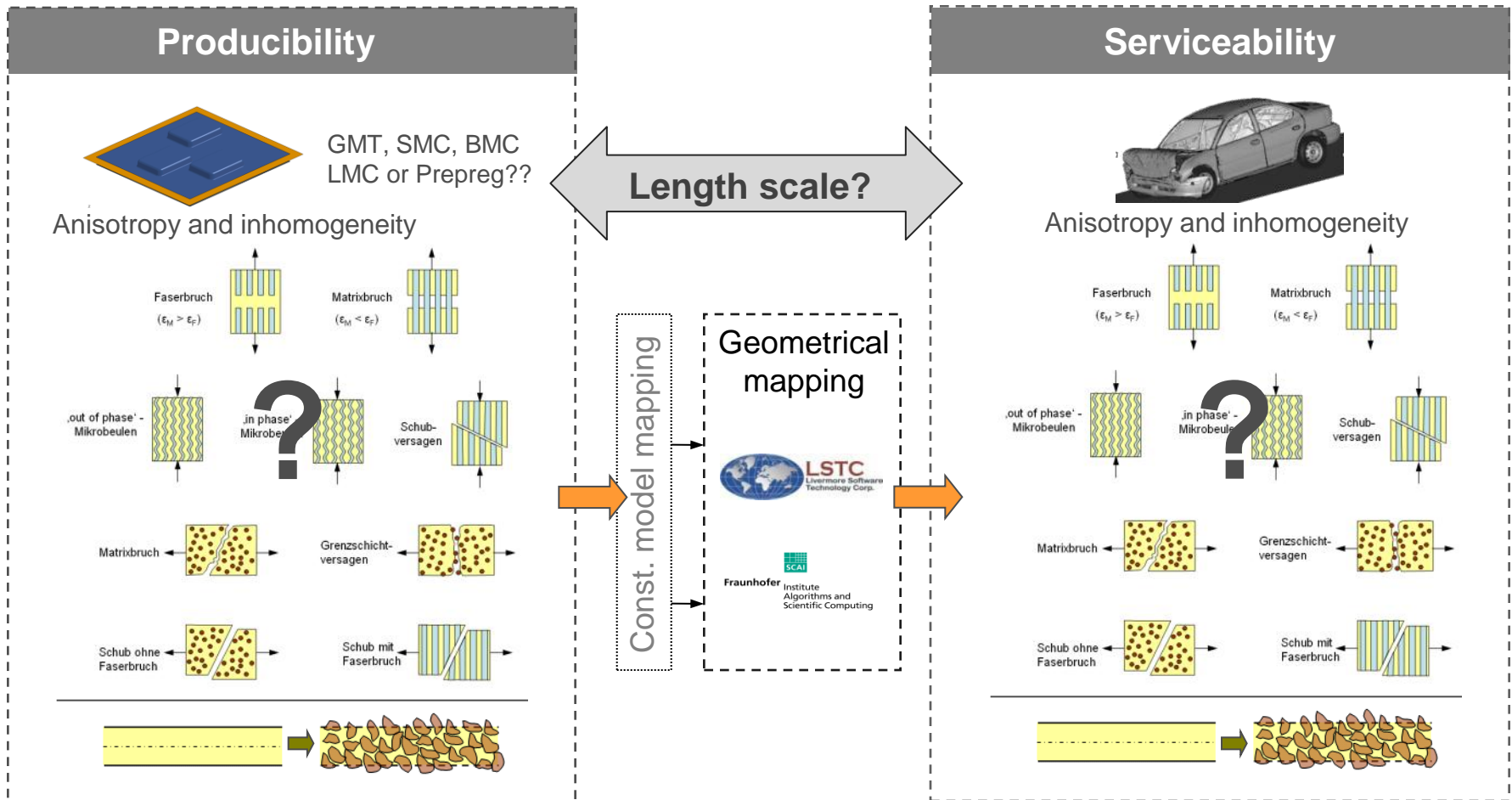
Composite process chain: Producibility2Servicability

Problem: Different applications use different modeling techniques, constitutive models, standards and validation procedures.

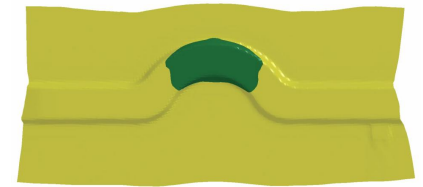
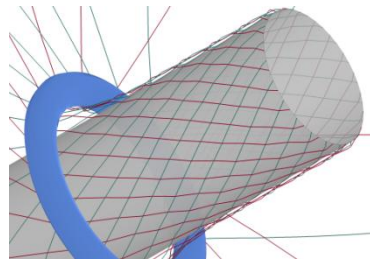


Composite process chain: Producibility2Servicability

Problem: Different applications use different modeling techniques, constitutive models, standards and validation procedures.



Producibility



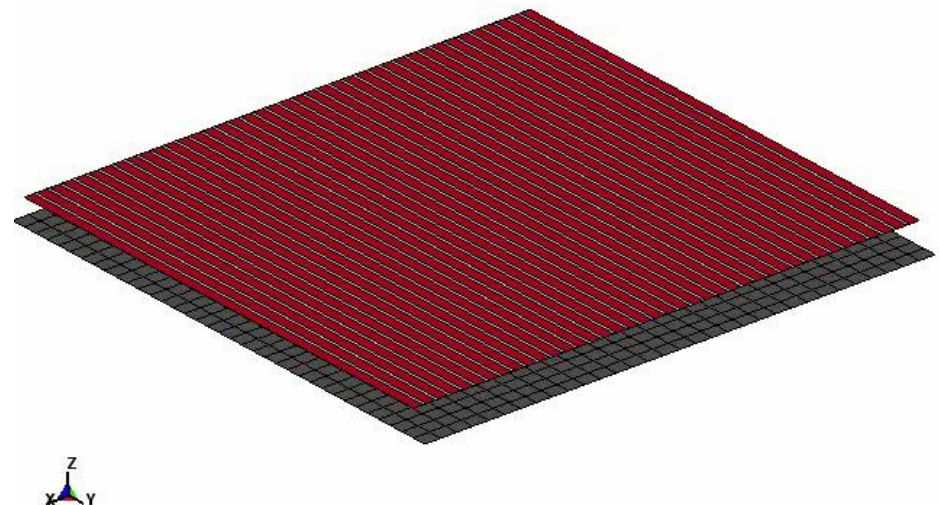
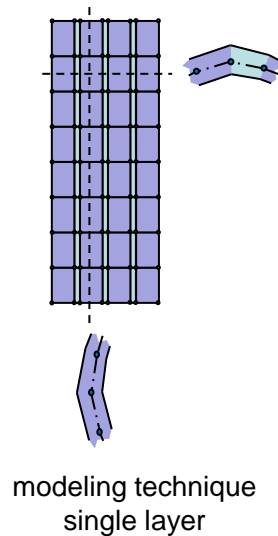
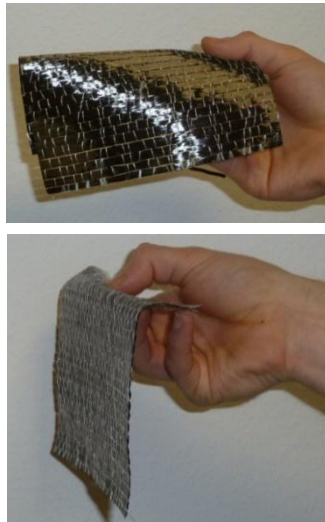
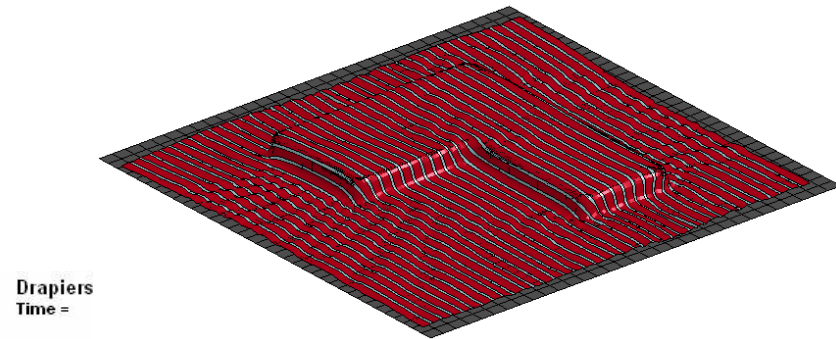
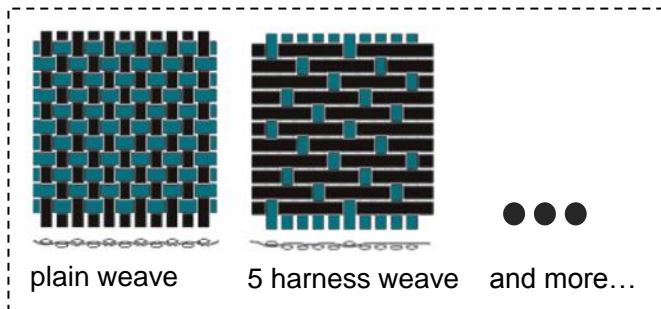


Producibility

Draping

Process simulation: Draping with strong anisotropy

Some fabrics (preforms) show extreme orthotropic behavior. Here modeling with shell elements using different constitutive models is possible:

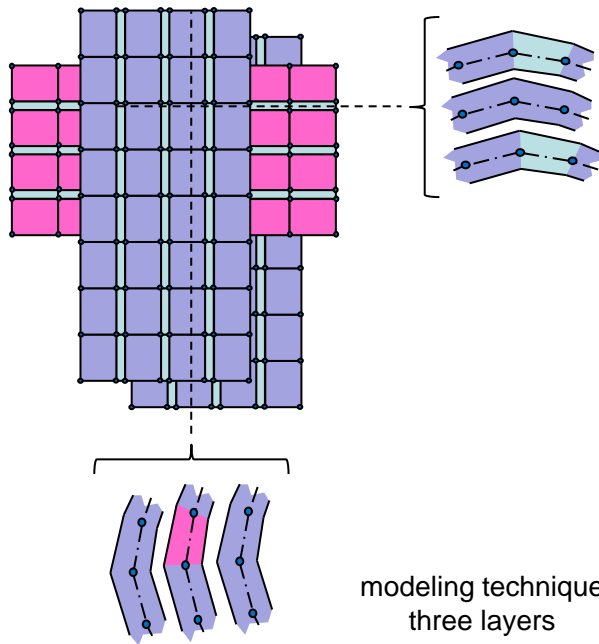


Process simulation: Draping with strong anisotropy

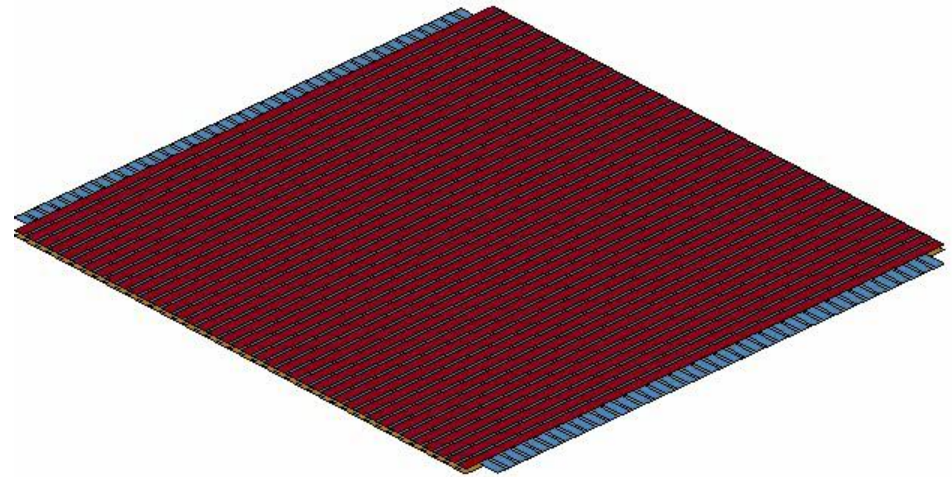
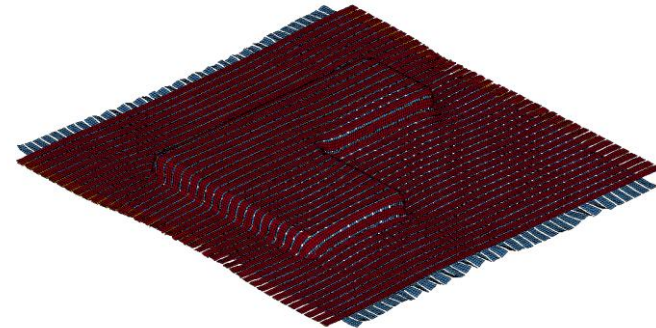
Some fabrics (preforms) show extreme orthotropic behavior.

Here modeling with shell elements using different constitutive models is possible.

For stacked preforms a similar approach in finite element modeling is of course possible: Multiple layers of shell elements.



Drapers!
Time =

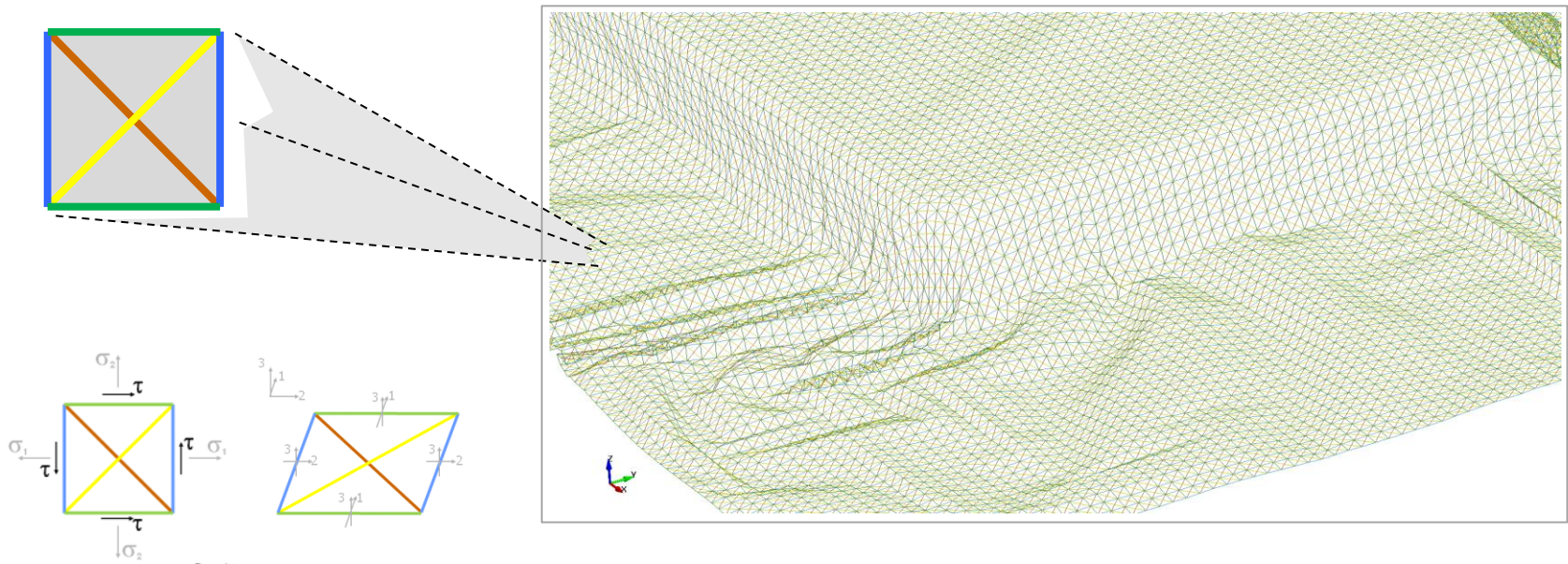


Draping: Using discrete elements for strong anisotropy

Modeling woven fabrics with beam elements:

Warp and weft direction *MAT_LINEAR_ELASTIC_DISCRETE_BEAM (MAT_066)

Diagonal behavior modeled with *MAT_CABLE_DISCRETE_BEAM (MAT_071)



This approach allows also to model positive and negative shear loading.

Optional matrix may be represented with shell elements and elastic/plastic material.

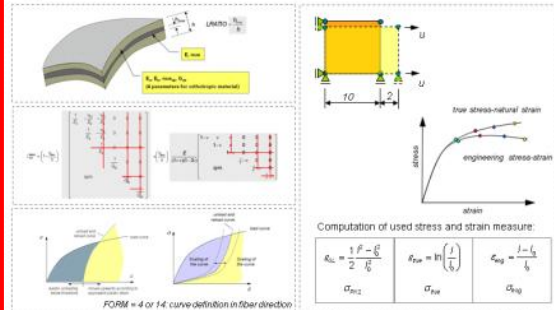
Modeling techniques on cm-scale:

Fabric materials available for draping simulation in LS-DYNA

MAT_34

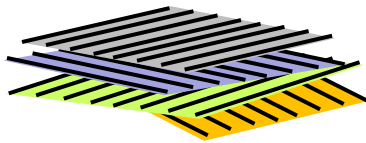
Simulation on cm-scale: MAT_FABRIC (#34)

A special membrane formulation is automatically invoked



New in R7.0: bending stiffness

New: ACMD

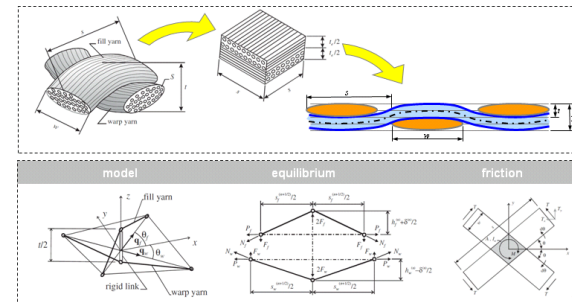


Anisotropic unidirectional layered constitutive model for draping
NEW in future release.

MAT_234

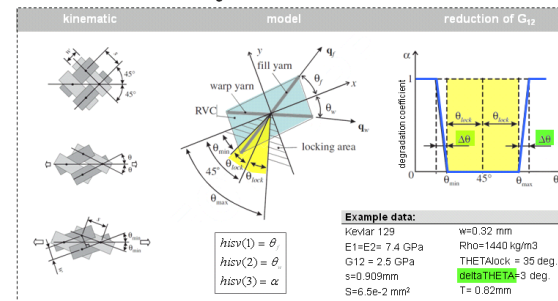
Simulation on cm-scale: MAT_VISCOELASTIC_LOOSE_FABRIC (#234)

Micro-mechanical approach:
Mathematical description of geometry and kinematic of symmetrical woven fabric



Simulation on cm-scale: MAT_VISCOELASTIC_LOOSE_FABRIC (#234)

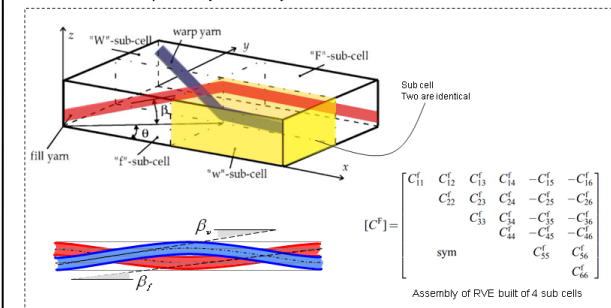
Taking locking angle through reduction factor for G_{12} into account
Visco-elastic enhancement for higher strain rates



MAT_235

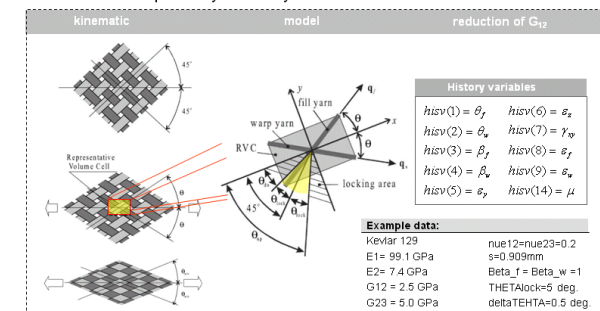
Simulation on cm-scale: MAT_MICROMECHANICS_DRY_FABRIC (#235)

Micro-mechanical approach with homogenization strategy (RVE):
Mathematical description of symmetrical woven fabric



Simulation on cm-scale: MAT_MICROMECHANICS_DRY_FABRIC (#235)

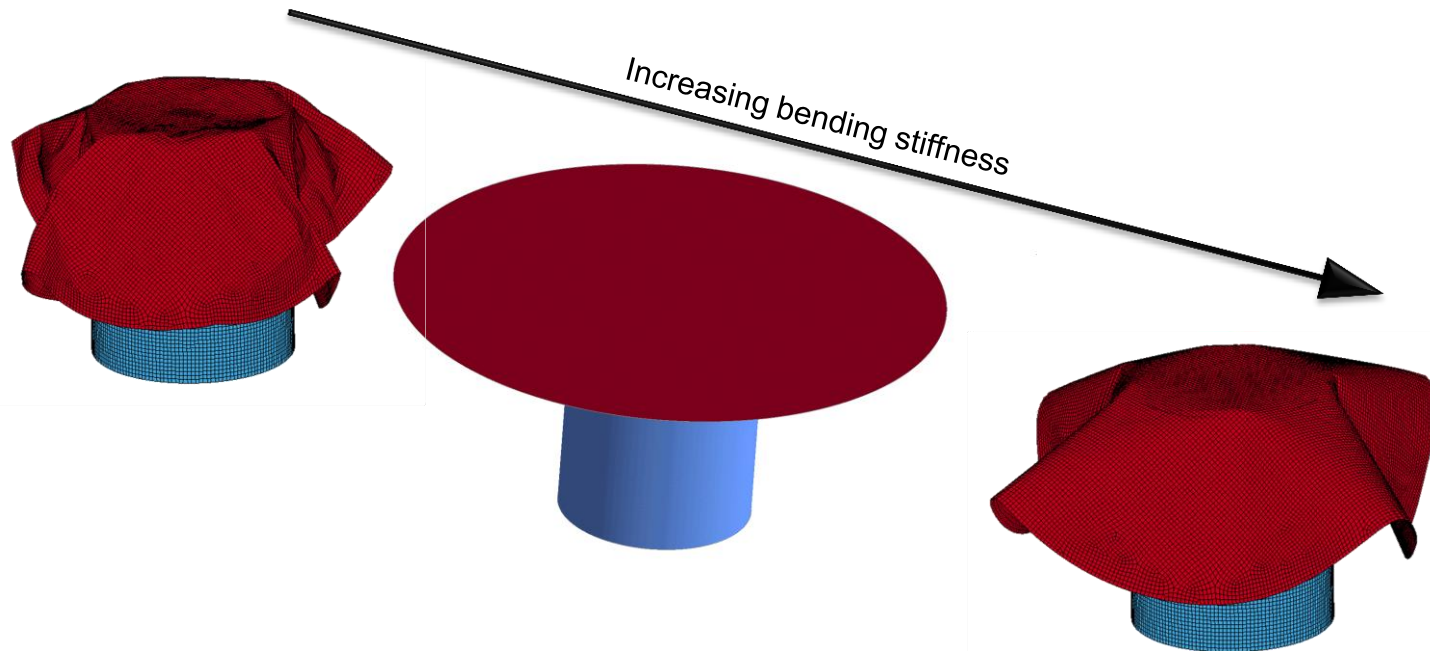
Micro-mechanical approach with homogenization strategy (RVE):
Mathematical description of symmetrical woven fabric

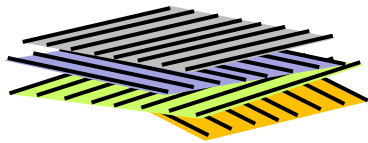


Enhancements in MAT_FABRIC (MAT34) starting with LS-DYNA R7.0

- Material describes an orthotropic material behavior
- Requires discretization with membrane elements
- Allows to add a bending resistance by defining an additional elastic coating in the material card

Example: Tablecloth with varying coating stiffness





New model for draping: ACMD

(beta status)

New anisotropic constitutive model for draping (ACMD)

- Hyperelastic, anisotropic material formulation, accounting for n discrete fiber families in *each* integration point
- Normalized initial fiber directions \vec{m}_i^0 are defined w.r.t. to material direction
- Current state of fiber \vec{m}_i is given by $\vec{m}_i = \underline{F}\vec{m}_i^0$ with length λ_i
- Response of the fibers according to a function $f(\lambda_i)$ of current length \vec{m}_i of the fiber defined by a load curve
- Stresses due to elongation of the individual fibers families are then computed as

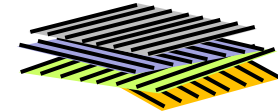
$$\underline{\sigma} = \sum_{i=1}^n \frac{1}{J} f(\lambda_i) \underline{F}(\vec{m}_i^0 \otimes \vec{m}_i^0) \underline{F}^T$$

- Interaction between neighboring fiber families can be accounted for by

$$\underline{\sigma} = \sum_{\substack{i,j \\ i \neq j}} \frac{1}{J} g(\vec{m}_i \cdot \vec{m}_j) \underline{F}(\vec{m}_i^0 \otimes \vec{m}_j^0) \underline{F}^T$$

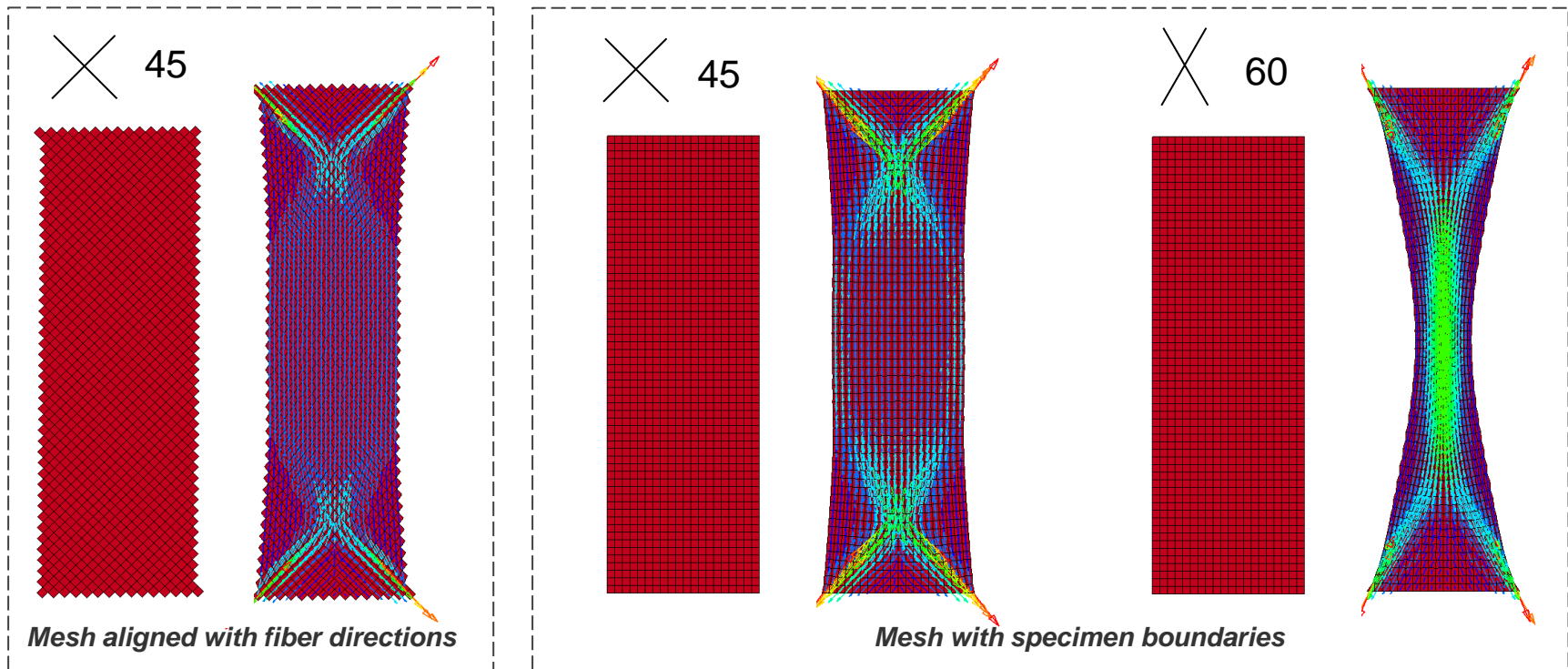
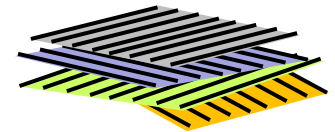
where function g can again be provided as a load curve

- For the sake of stability, a linear relation between transverse shear stresses σ_{31}, σ_{32} and the corresponding components of the bulk strain tensor is additionally assumed



Example: tensile test specimen (ACMD)

- Prescribed motion of top nodes
- Arrows indicate the principal stresses

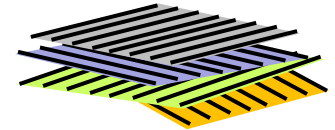


Results show that

- stress orientations are independent of element orientations
- material definition accounts correctly for anisotropic (non-orthotropic) material behavior

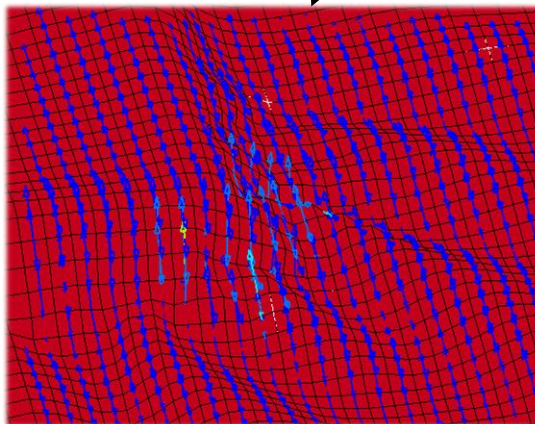
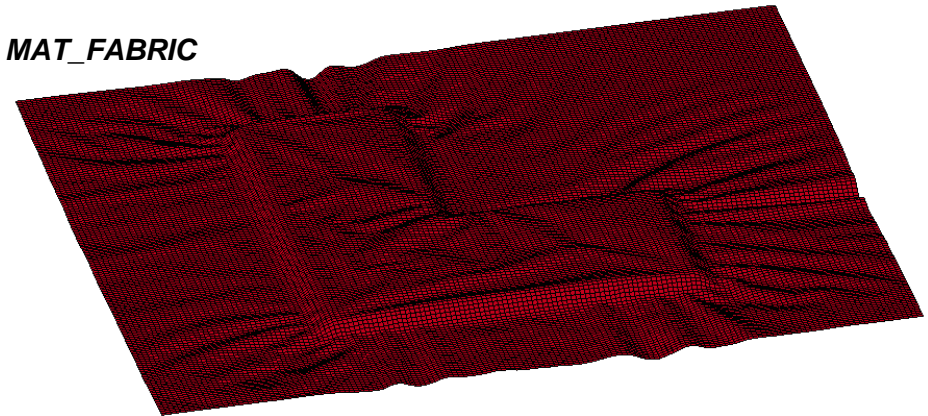
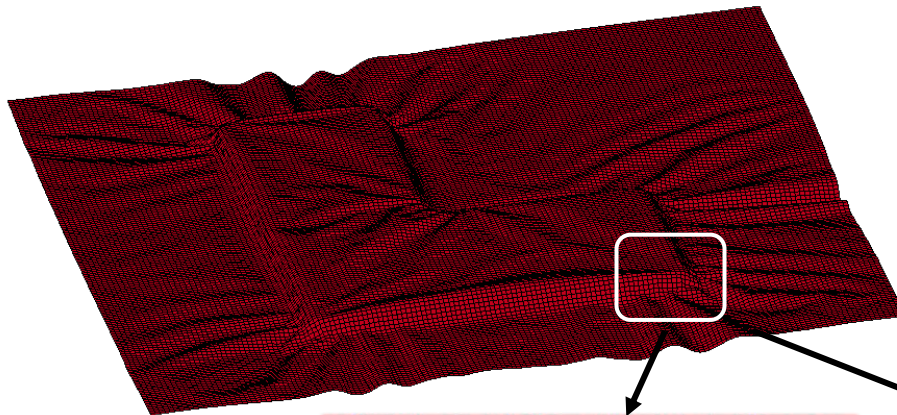
Example ACMD: Draping simulation (0 /90)

Comparison with LS-DYNA standard material MAT_FABRIC (MAT_034)

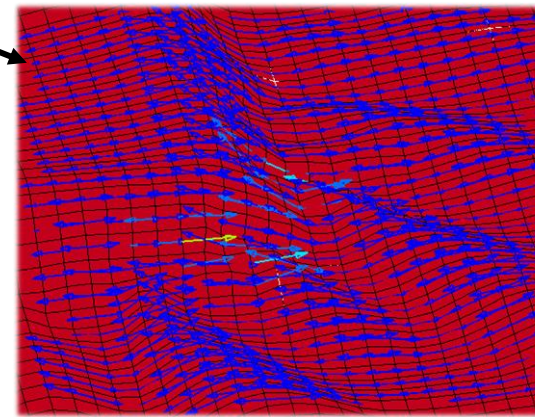


*New anisotropic
constitutive model*

MAT_FABRIC

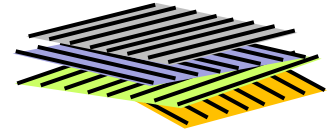


Fiber 1



Fiber 2

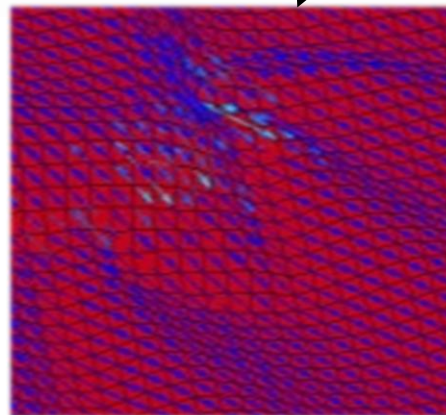
Example ACMD: Draping simulation (-45 /+45)



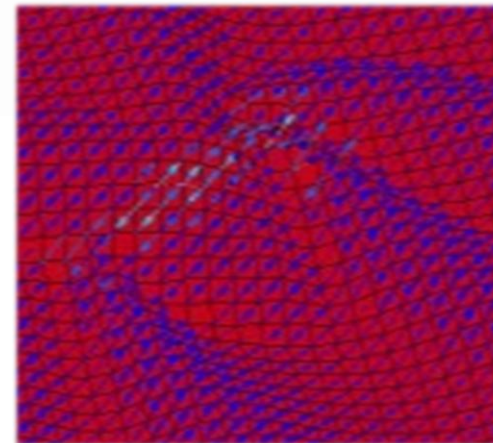
Comparison with LS-DYNA standard material MAT_FABRIC (MAT_034)

*New anisotropic
constitutive model*

MAT_FABRIC



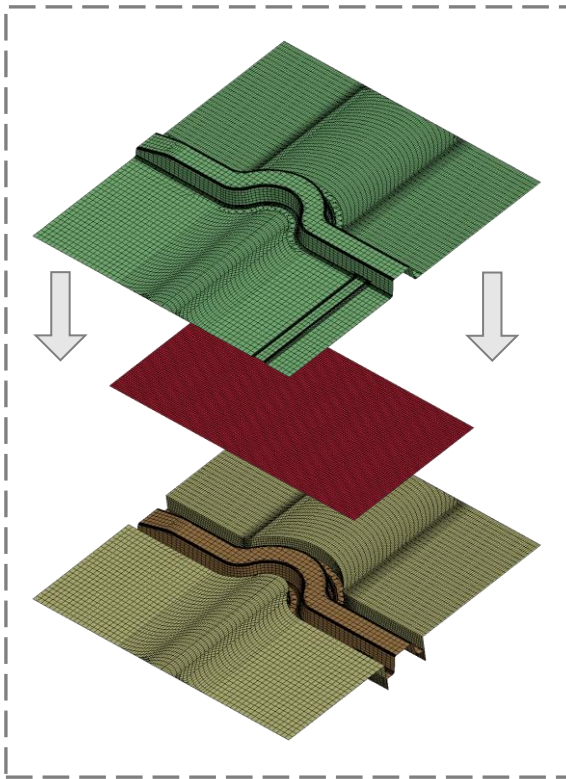
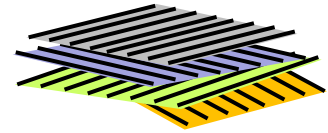
Fiber 1



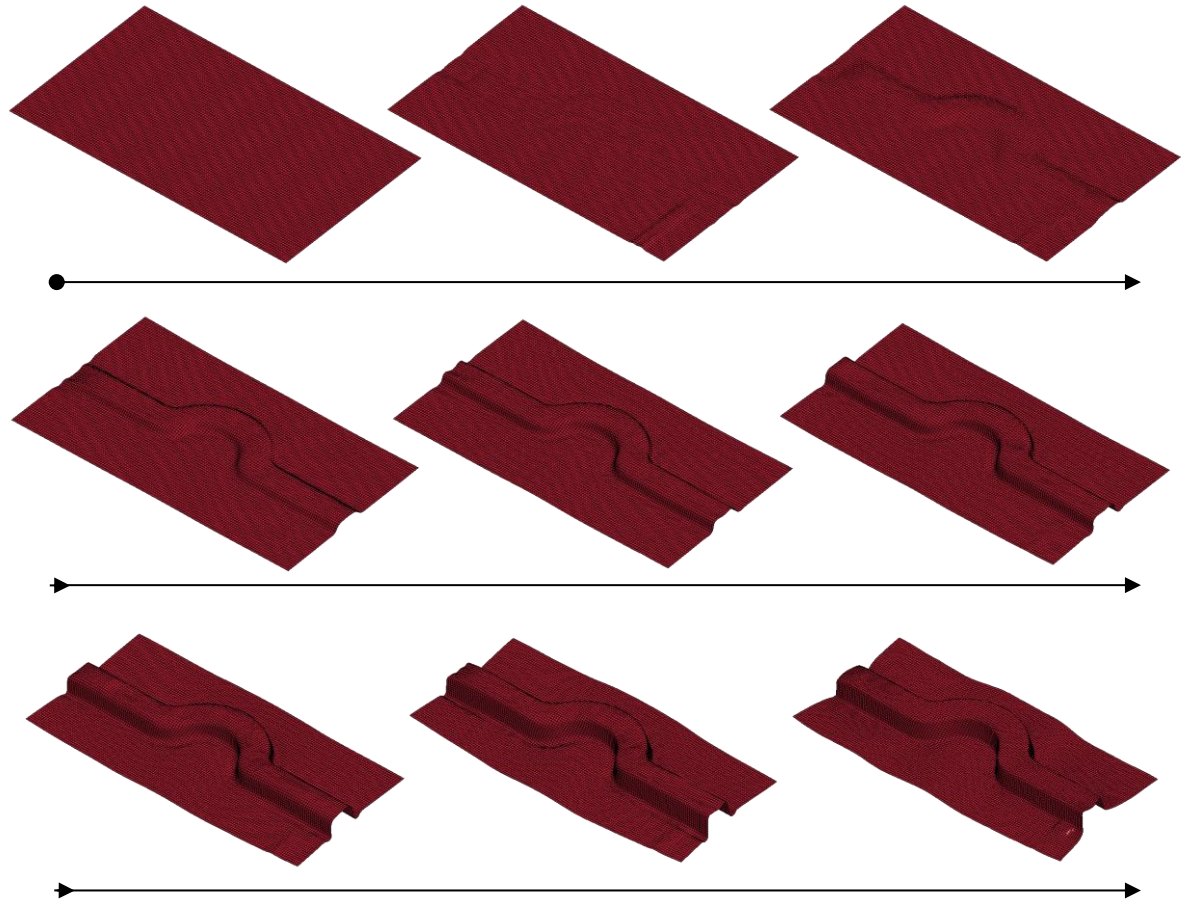
Fiber 2

Draping example: Rail

Process simulation

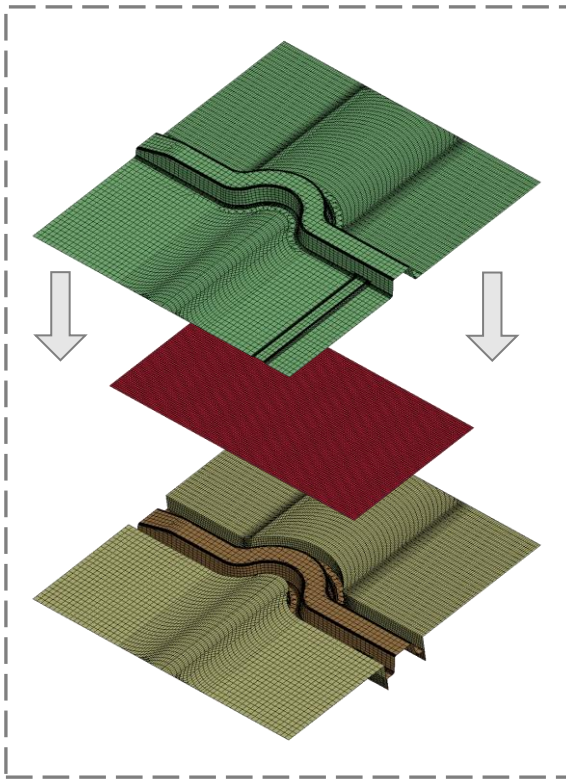
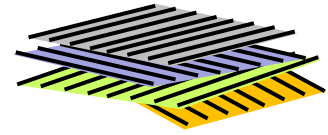


[geometry provided by Benteler-SGL]

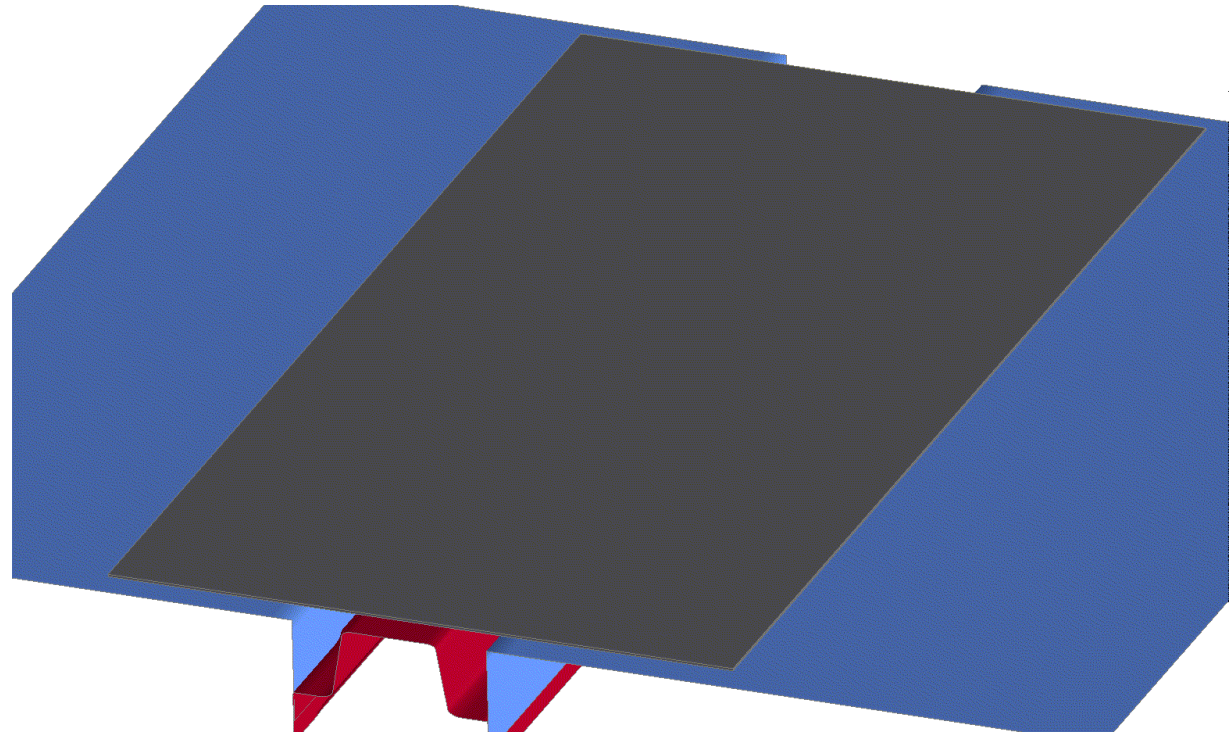


Draping example: Rail

Process simulation

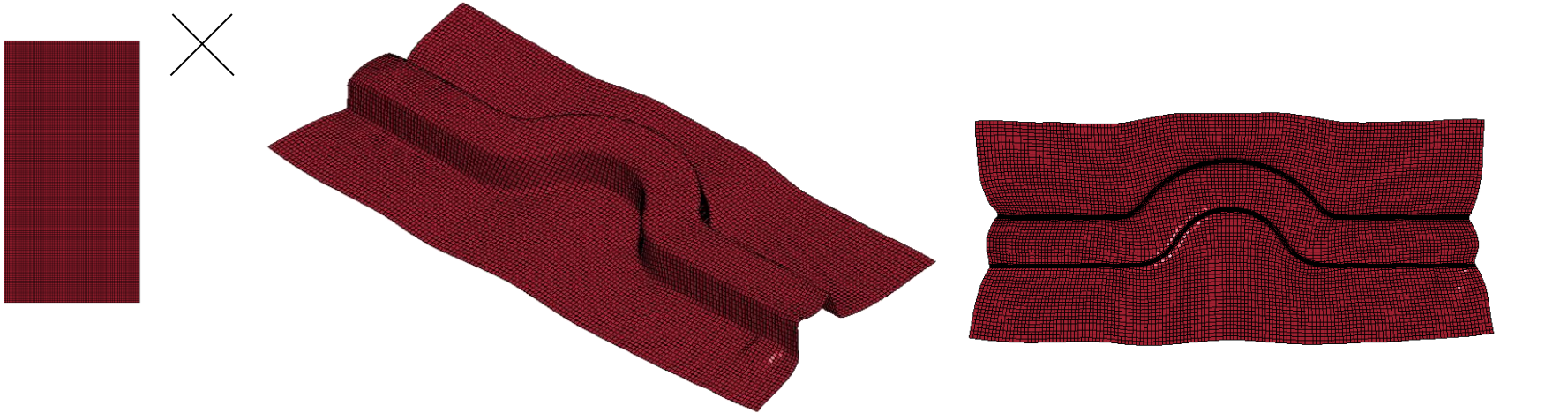


[geometry provided by Benteler-SGL]



Draping example: S-Rail

Fiber angle $\pm 45^\circ$, final state



Fiber angle $\pm 60^\circ$, final state





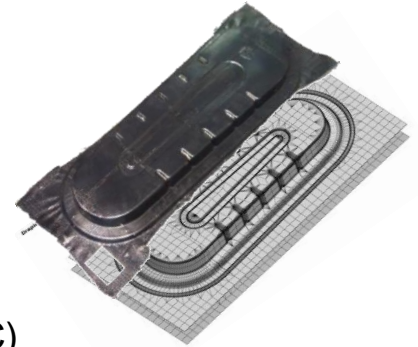
Producibility

Organo sheet

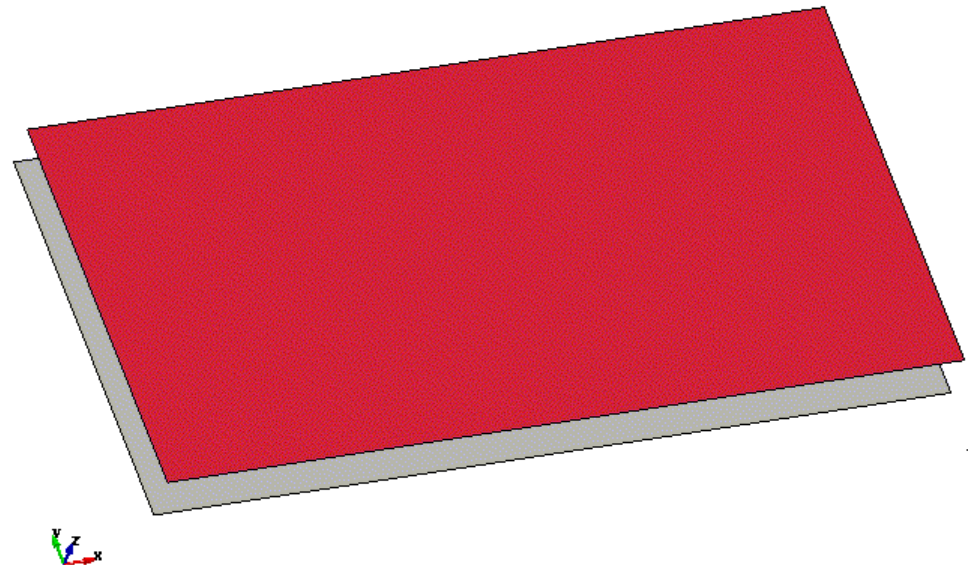
Process simulation: Organo sheet

- Single layer of woven fabric that is coated on both sides with PA6, $t=1.5\text{mm}$
- The forming process is done at 250-300 °C.

Modeling: Layered shell with *PART_COMPOSITE defining plastic material for PA6 at the outsides (*MAT_PLASTIC_KINEMATIC) and orthotropic material for woven fabric (*MAT_ORTHOTROPIC_ELASTIC,

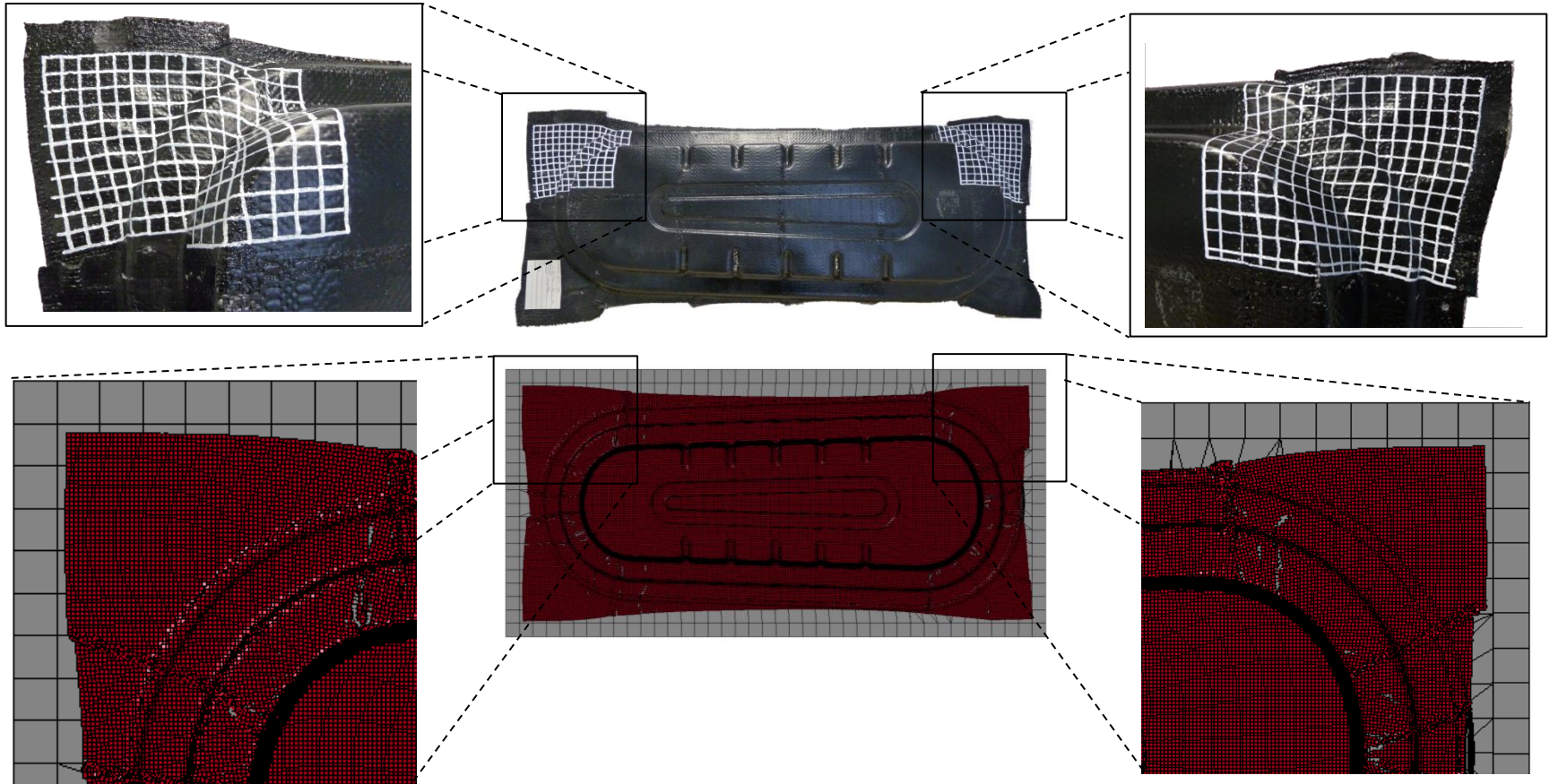


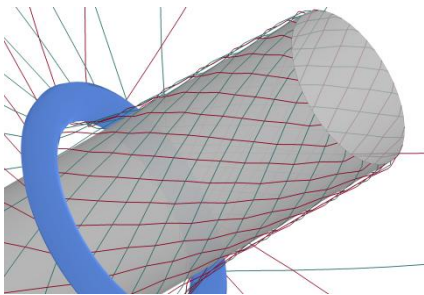
Drapersimulation
Time = 0, #nodes=107222, #elem=108799



Process simulation: Organo sheet

Optical comparison of fiber directions (aligned with mesh)



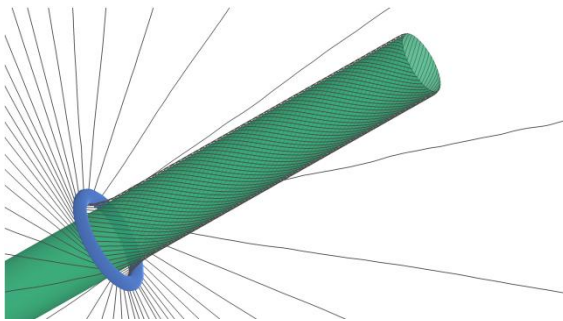


Producibility

Braiding

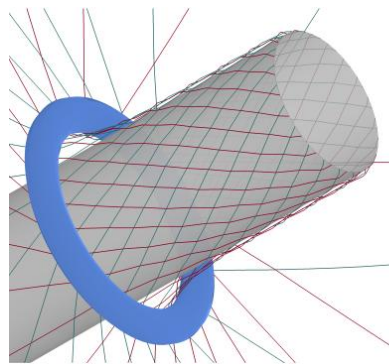
T-Pult: First steps into the process simulation

Filament winding simulation:



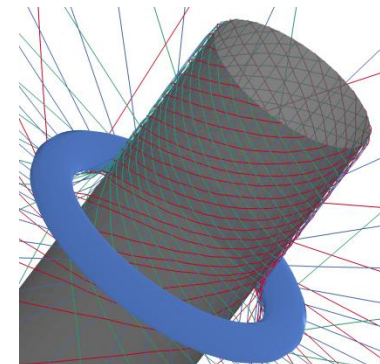
- 21 yarns
- 21543 Beam elements, 1 part
- Simple rotation of the fibers and pushing of the braiding core through the braiding ring
- Simple filament winding

Simple braiding simulation:



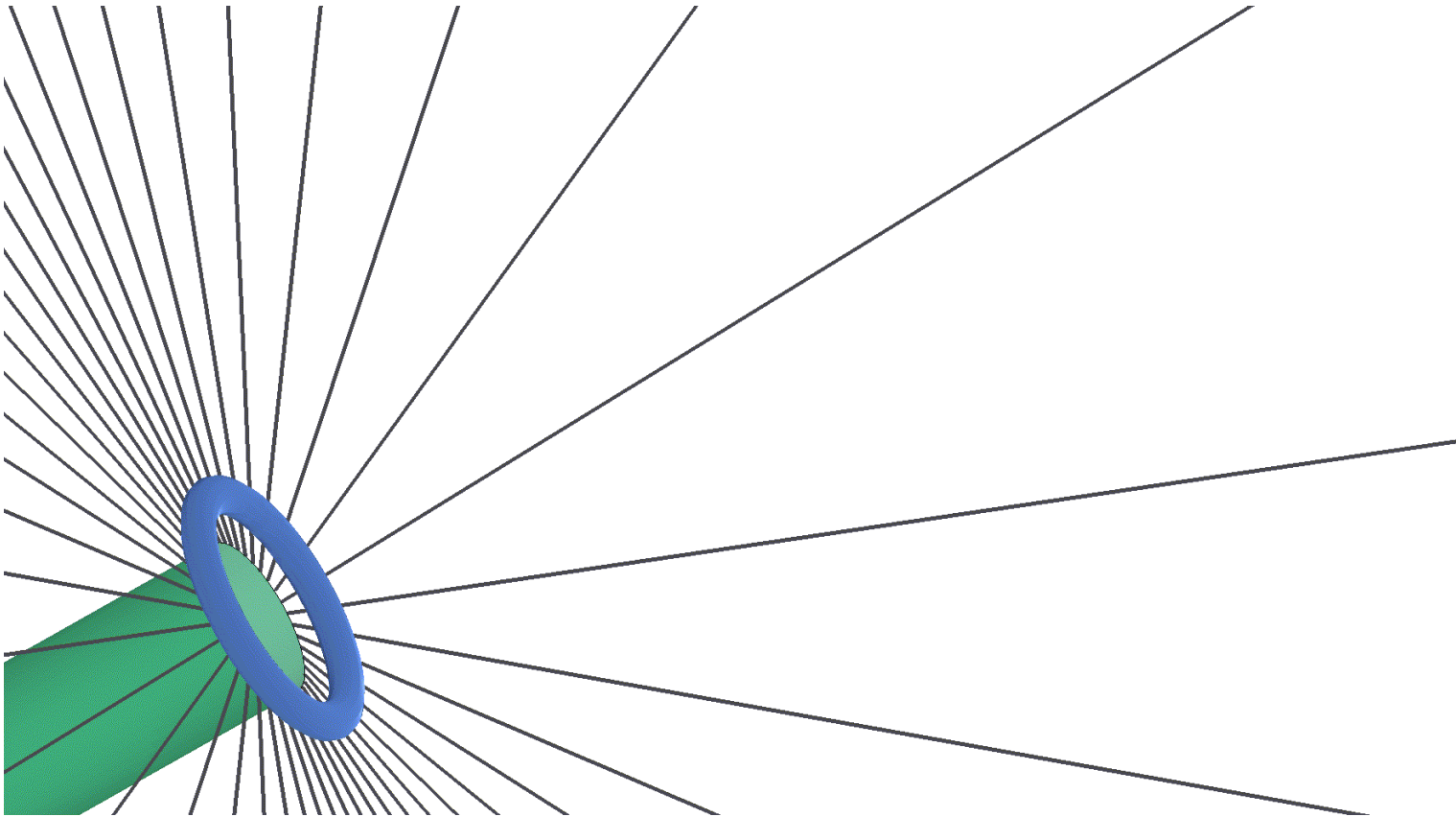
- 42 yarns
- 86172 Beam elements, 2 parts
- Fibers are rotated and then moved up- and down to create the braiding-pattern
- Braiding core is pushed through the braiding ring

Braiding simulation with UD reinforcement:

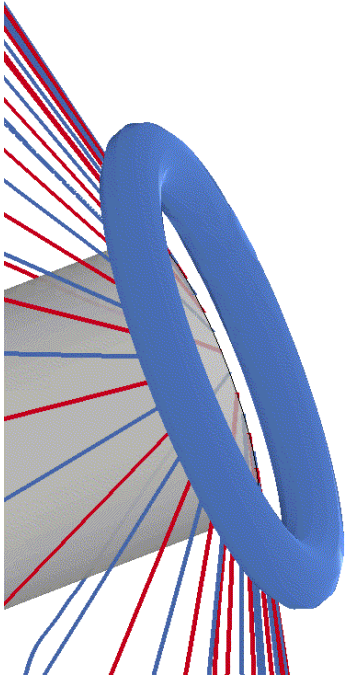


- 84 yarns
- 174348 Beam elements, 3 parts
- Half the elements used as UD – reinforcement parts
- Fibers are rotated and then moved up- and down to create the braiding-pattern
- Braiding core is pushed through the braiding ring

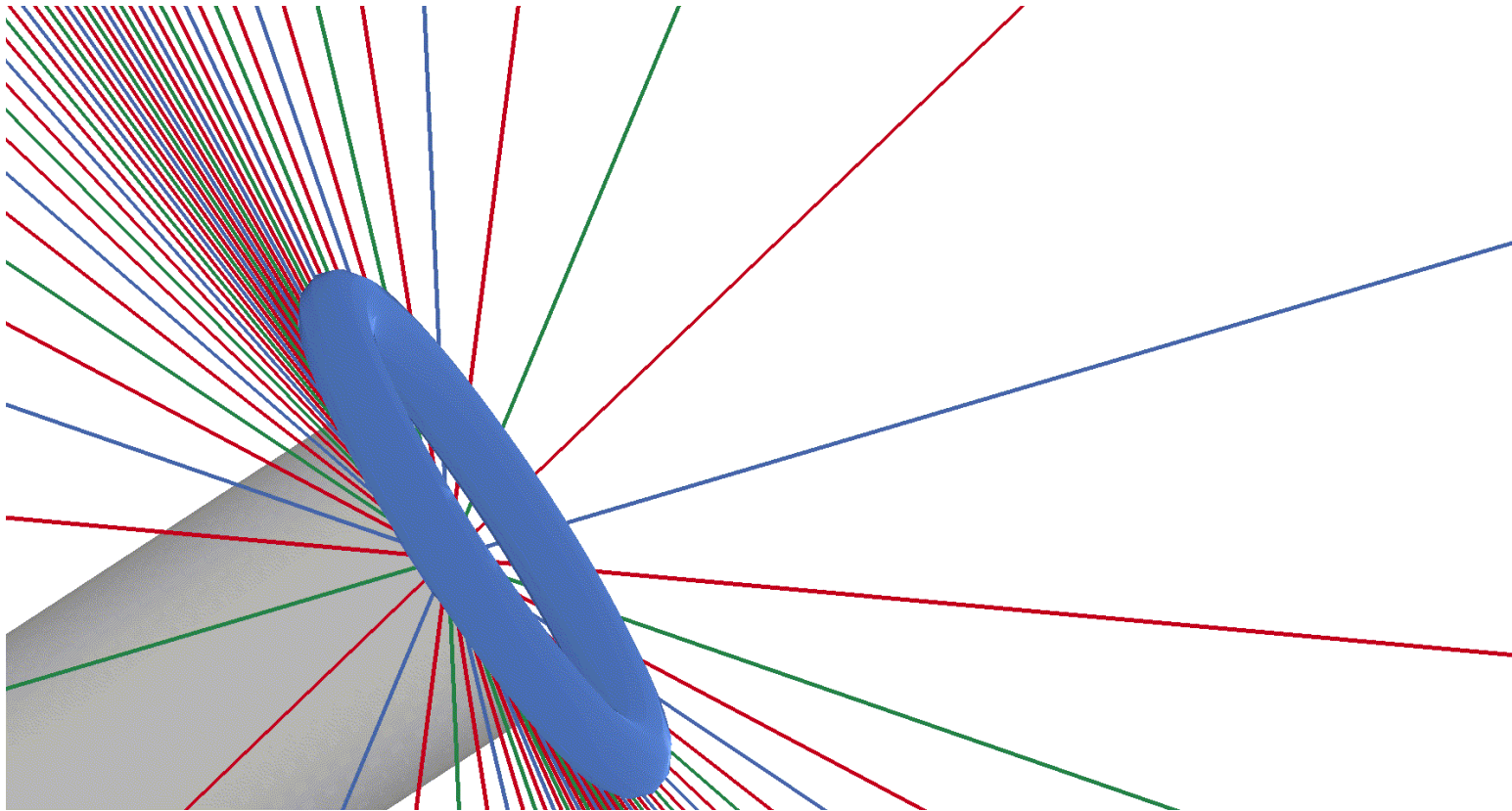
Process simulation: Filament winding

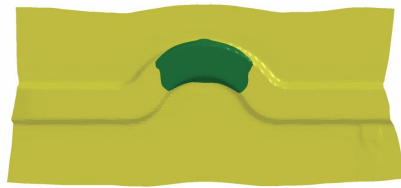


Process simulation: Simple braiding



Process simulation: Braiding with UD reinforcement



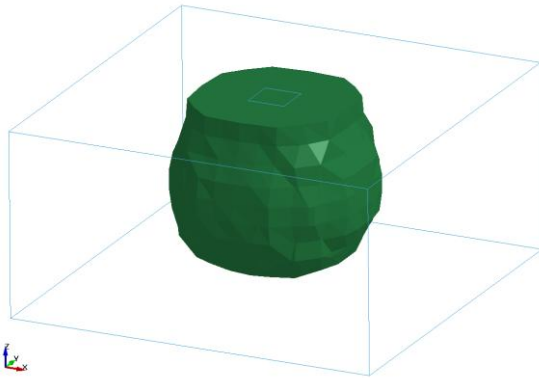


Producibility

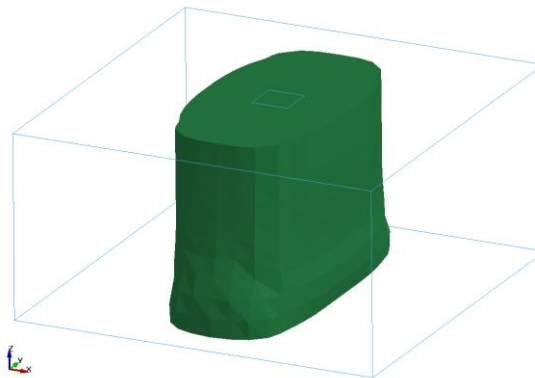
RTM

Proof of concept 1: Injection of Resin with ALE-feature

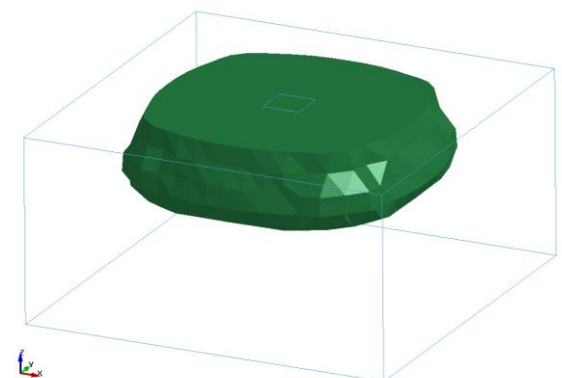
- Infiltration is a 3D flow problem through a porous media
- Porosity depends on the packing density of the fibers
- Fiber orientation results in an anisotropic porosity distribution in the domain
- Flow through porous media can be modeled in LS-DYNA using the `CONSTRAINED_LAGRANGE_IN_SOLID` keyword



same porosity in all directions



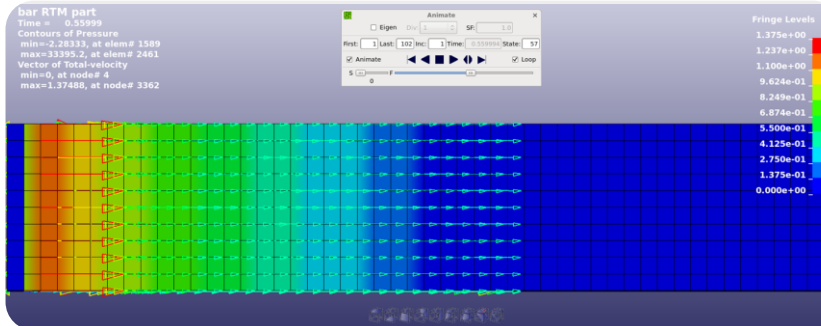
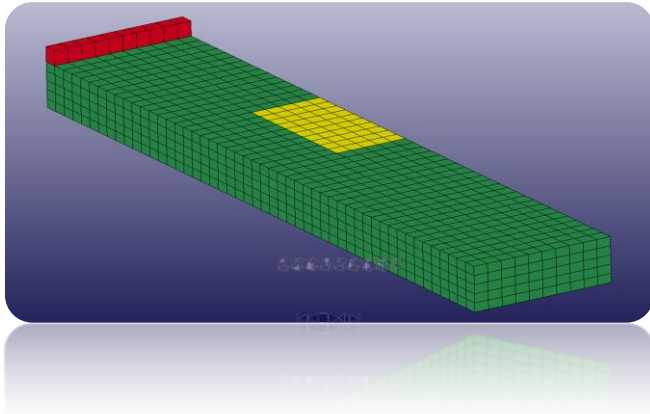
low porosity in x-direction



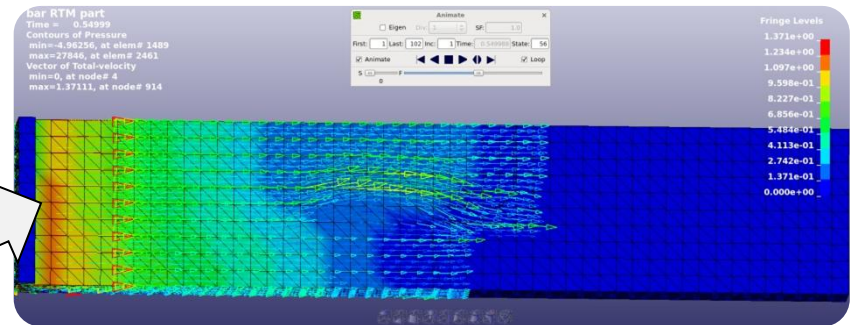
low porosity in z-direction

Proof of concept 2: Injection of Resin with ALE-feature

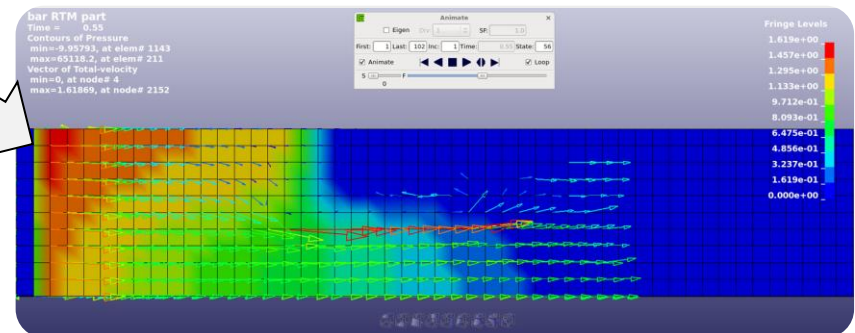
- Box with an inclusion
- Inflow defined at red elements
- Main material (green) and inclusion (yellow) have same/different viscous coefficients.



Same porosity coefficients



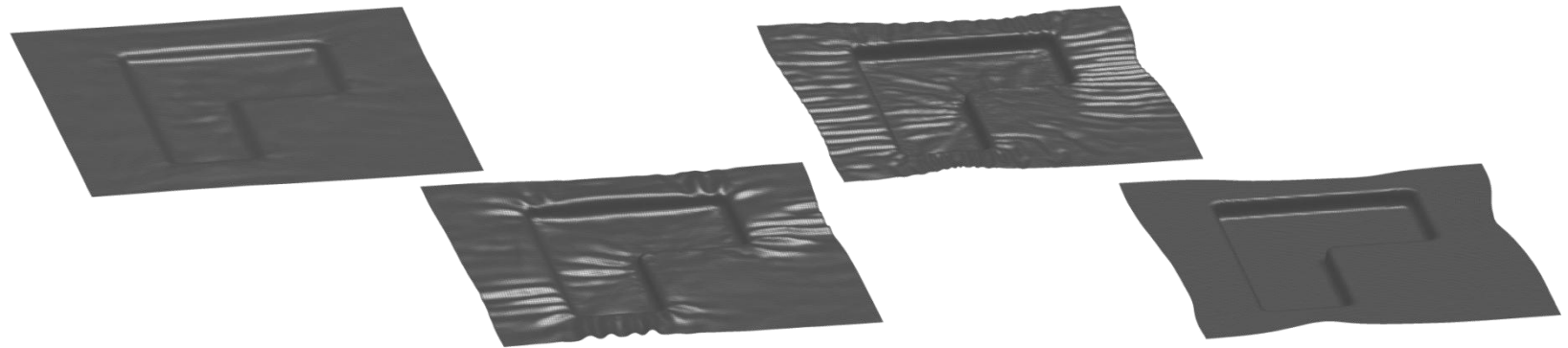
Inclusion has higher porosity



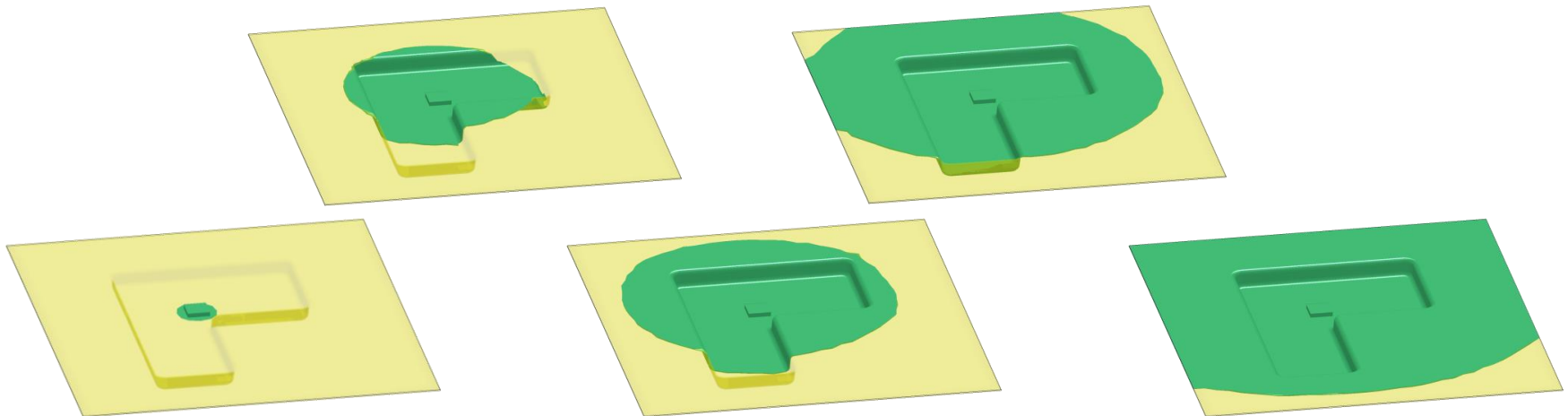
Main material has higher porosity

Example: L-Shape

Draping

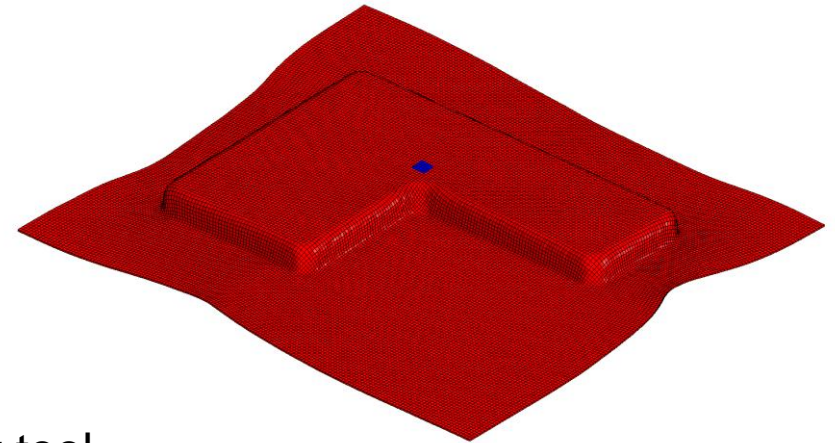
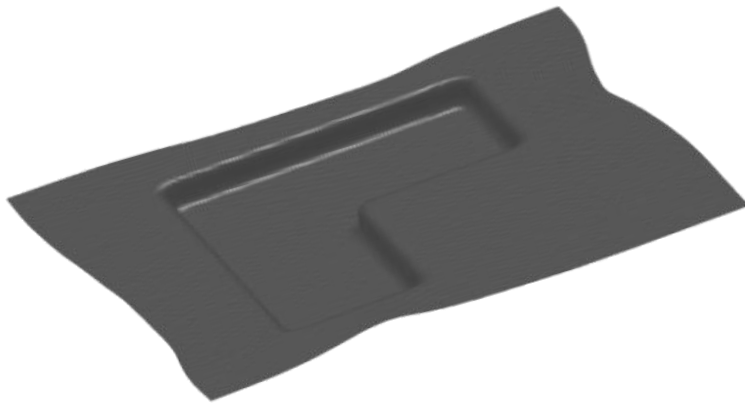


Infiltration – visualized on cavity defined by tool

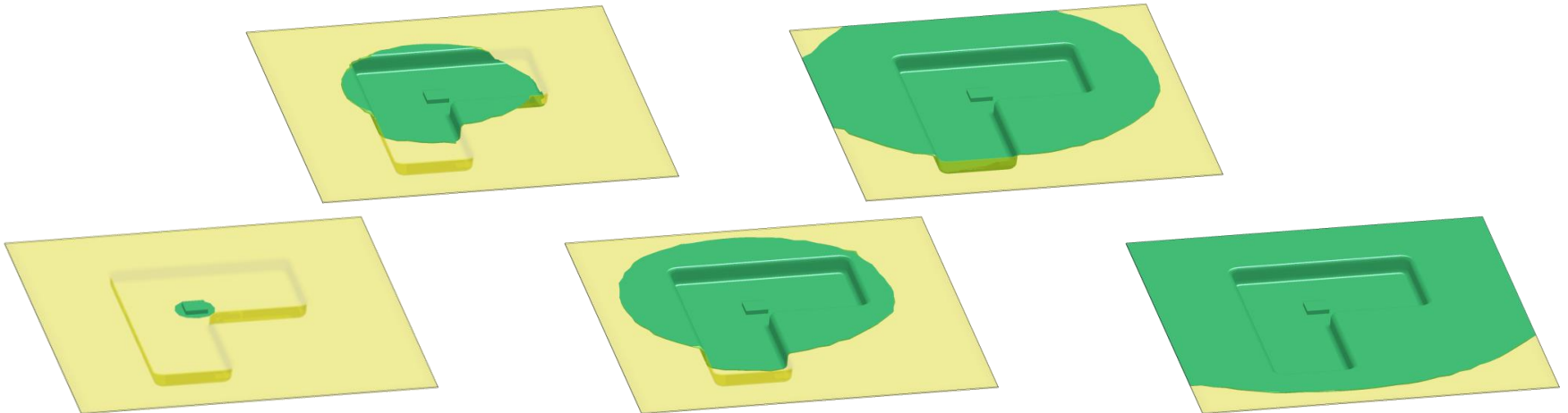


Example: L-Shape

Infiltration – visualized on cavity defined by fabric



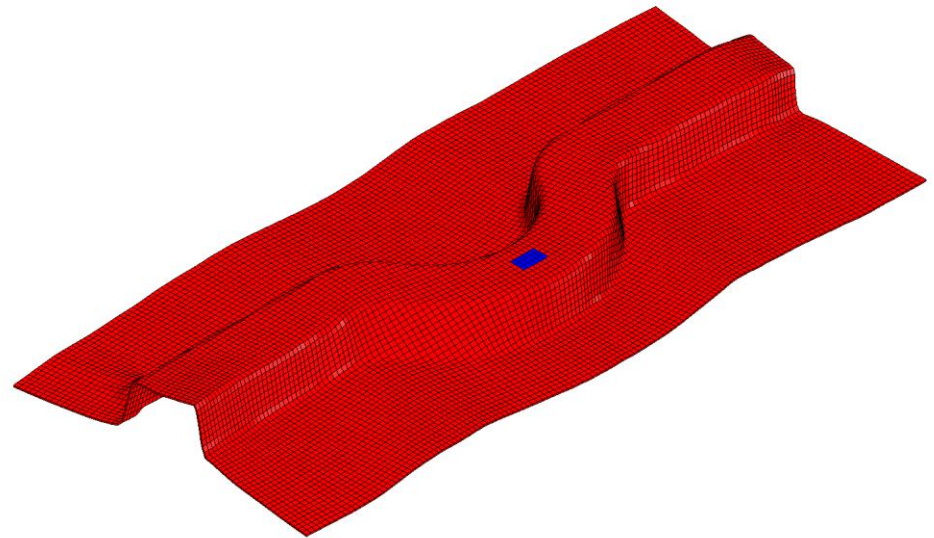
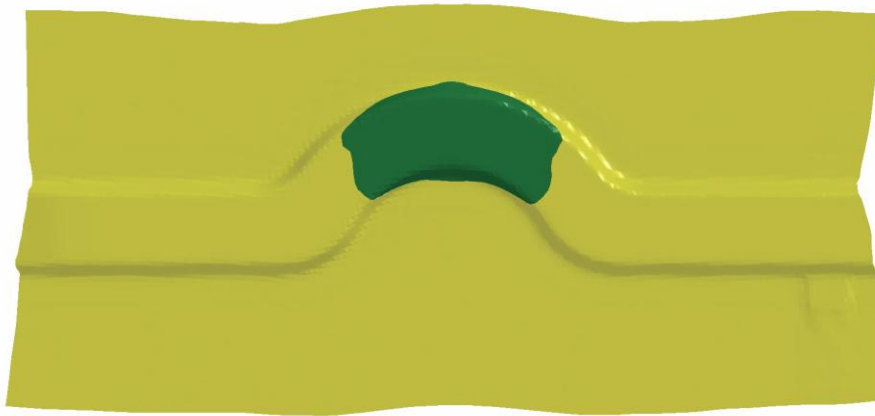
Infiltration – visualized on cavity defined by tool



Injection of resin in draped rail-geometry

- Mesh obtained from draping simulation
- Flow induced by pressure inlet
- Isotropic porosity
- One injection point for resin is considered (blue)

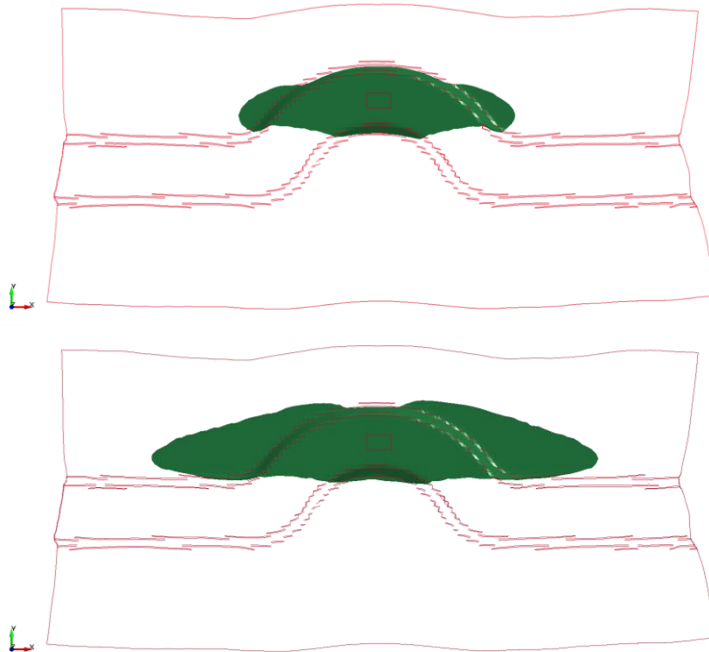
RTM Simulation SRail Geometry



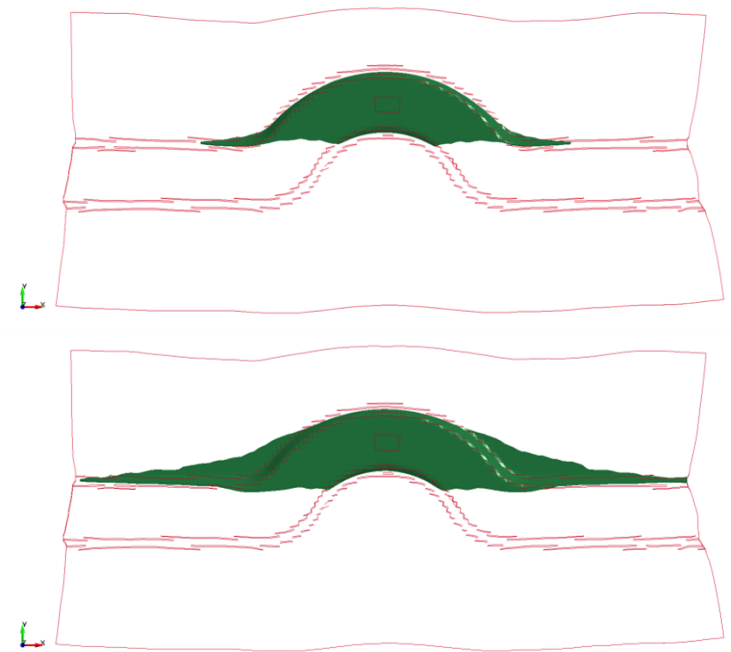
Injection of resin in draped rail-geometry

- LS-DYNA allows to define the porosity with respect to the element coordinate system:
 - Easy to specify a porosity in thickness direction even for curved geometries
 - Important if the geometry results from a previous draping simulation

High porosity in global x-direction



High porosity in element x-direction



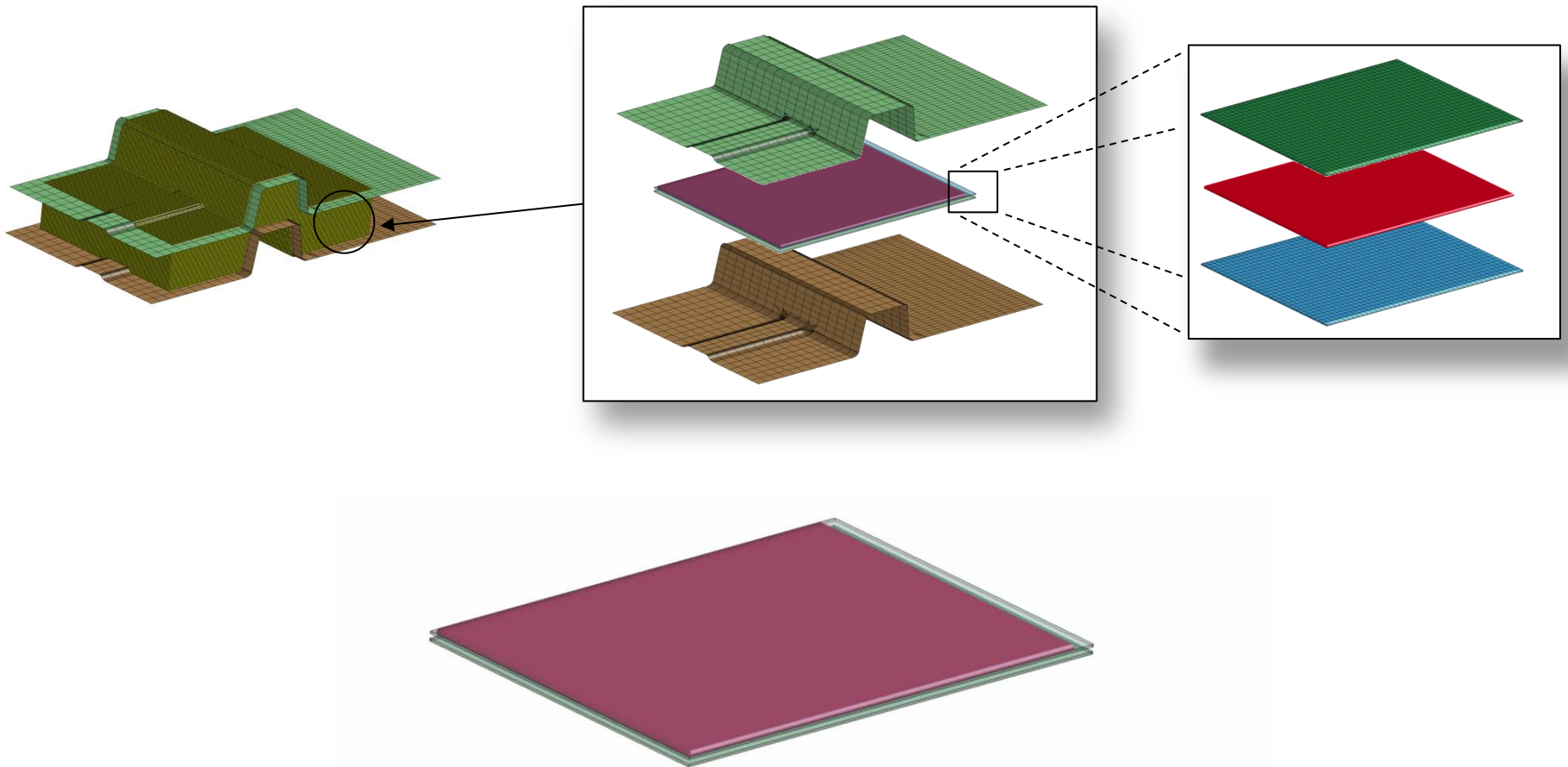


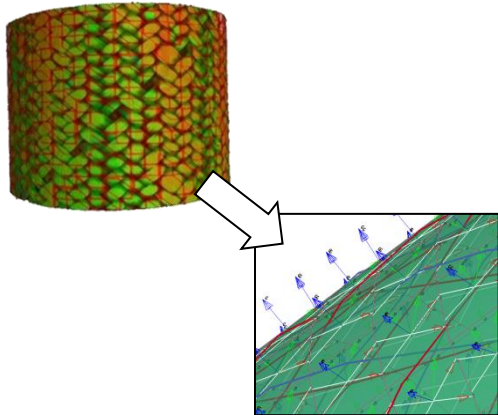
Producibility

Wet moulding

A first proof of concept for wet moulding

Cut-out from rail geometry

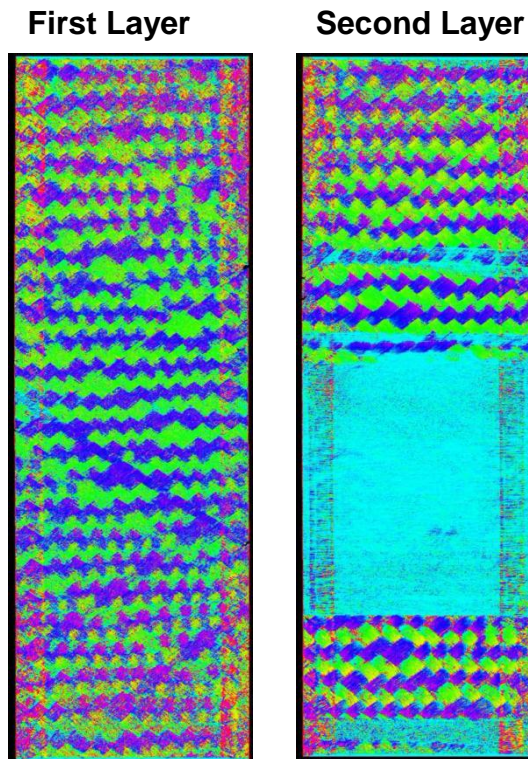
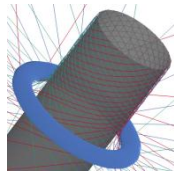




Orientations from measurement


Alternative: CT-data of braided tube for model setup

- transfer of fiber orientation-tensors onto a LS-DYNA gained by mesh by CT measurement
- Three different mesh sizes considered so far: Coarse, Mean, Fine
- Example-part: 3-layered braided tube with 0-deg reinforcement fibers

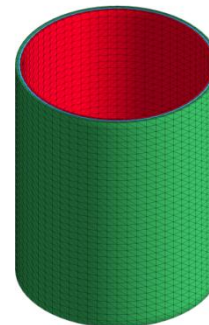


	Num. of Elements	Layers	Element-Size
Coarse Mesh	38420	1	0,3 - 1,25 mm
Mean Mesh	150039	2	0,15 - 0,62 mm
Fine Mesh	15078400	4	0,075 - 0,1 mm

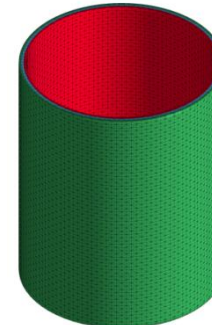
Transfer of
orientation data



Coarse Mesh



Mean Mesh

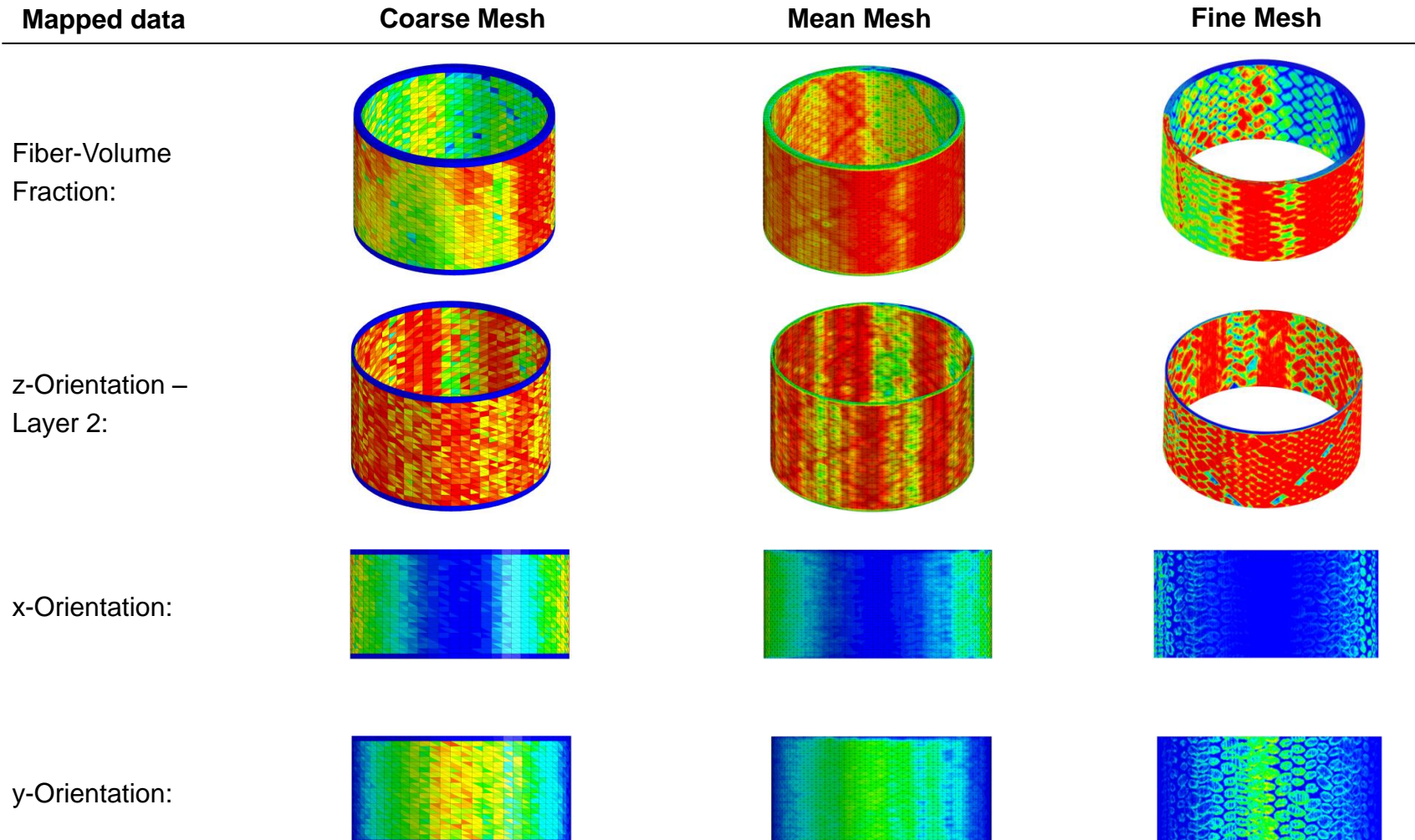


Fine Mesh



[H. Finckh, ITV Denckendorf // Th. Günter, Volume Graphics]

Alternative: CT-data of braided tube for model setup



Alternative: CT-data of braided tube for model setup

Next steps: Homogenization

Fiber Orientation Tensor:

$$[1] \quad a_{ij} = \frac{1}{n} \sum_{k=1}^n a_{ij}^k = \frac{1}{n} \left(\sum_{k=1}^n p_i^k p_j^k \right) = \begin{pmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{pmatrix}$$

Number of fibers/Volume

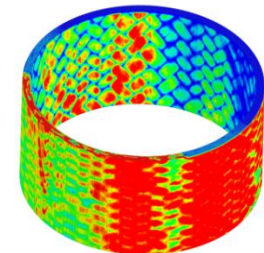
Orientation of a single fiber: $p = \begin{pmatrix} \sin \theta \cos \phi \\ \sin \theta \sin \phi \\ \cos \theta \end{pmatrix}$

Polar coordinates: $\begin{cases} r = \sqrt{x^2 + y^2 + z^2} \\ \theta = \arccos \left(\frac{z}{\sqrt{x^2 + y^2 + z^2}} \right) \\ \phi = \arctan \left(\frac{y}{x} \right) \end{cases}$

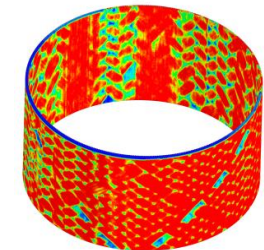
Mapped data

Fine Mesh

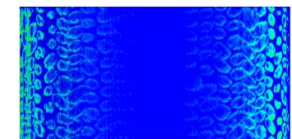
Fiber-Volume Fraction:



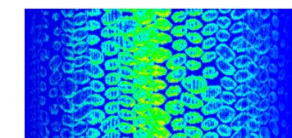
z-Orientation – Layer 2:



x-Orientation:



y-Orientation:



[Kastner et.al.: Pipeline zur dreidimensionalen Auswertung und Visualisierung der Faserverteilung in glasfaserverstärkten Kunststoffbauteilen aus μ -Röntgen-Computertomographiedaten, DACH-Jahrestagung St. Gallen, 2008]

Transfer CT-data to LS-DYNA model

Next steps: Homogenization

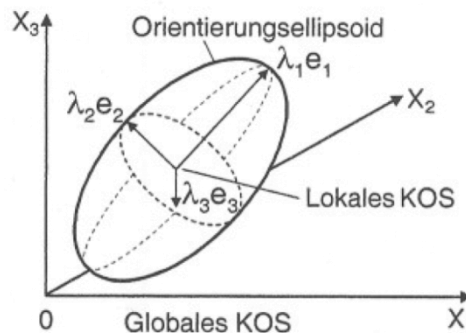
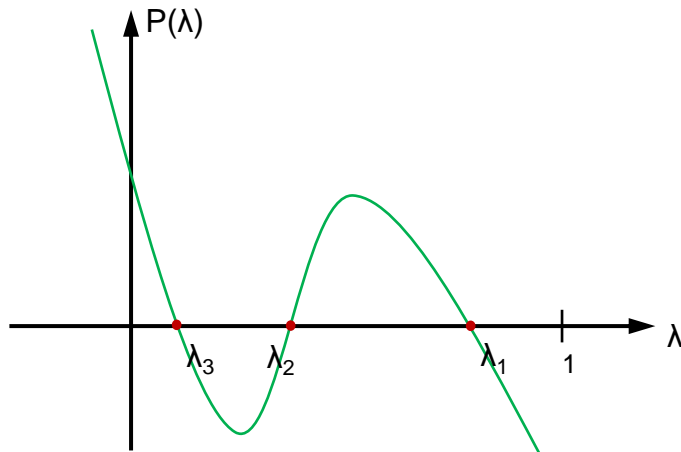
Get Eigenvalues: $\det(\mathbf{A} - \lambda \mathbf{E}) = 0$

\swarrow
 Eigenvectors
 (Fiber main directions)

$$\mathbf{A} = \begin{pmatrix} a_{11} & a_{12} & a_{13} \\ a_{12} & a_{22} & a_{23} \\ a_{13} & a_{23} & a_{33} \end{pmatrix}$$

where $k = 1$, $\text{trace}(\mathbf{A}) = 1$ $P(\lambda) = -\lambda^3 + k\lambda^2 + l\lambda + m$

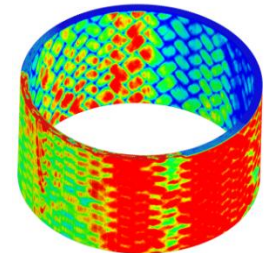
$\mathbf{A} - \lambda_i \mathbf{E} \Rightarrow \mathbf{e}_i$ $\mathbf{e}_i \rightarrow$ Eigenvectors \triangleq Fiber Main directions
 λ_i – probability for fibers being aligned along this axis



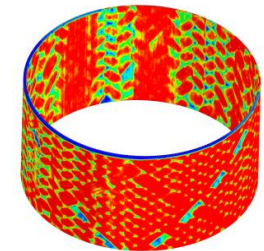
Mapped data

Fine Mesh

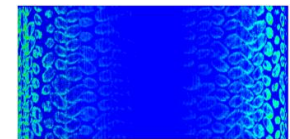
Fiber-Volume
Fraction:



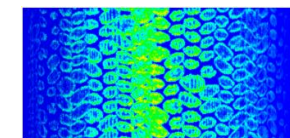
z-Orientation –
Layer 2:

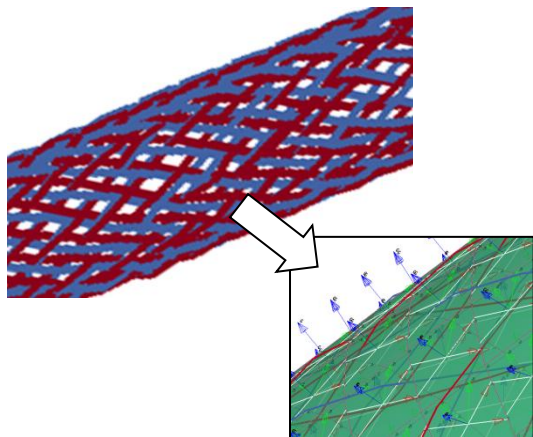


x-Orientation:



y-Orientation:

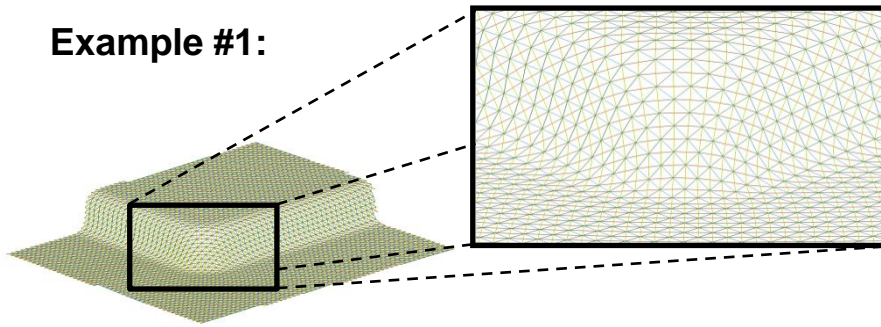




Mapping of orientations

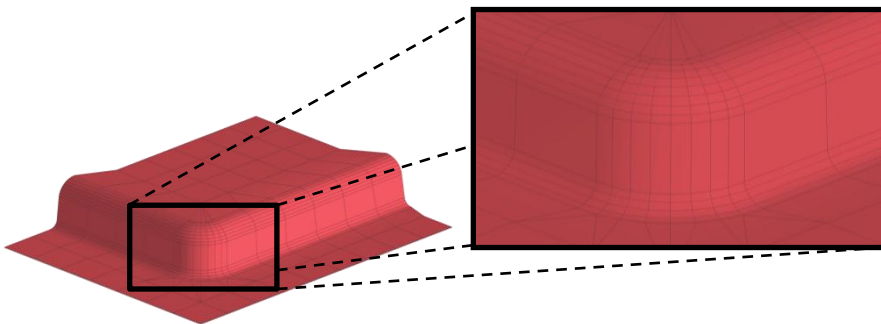
Mapping of material directions on different target meshes

Example #1:



Source Mesh:

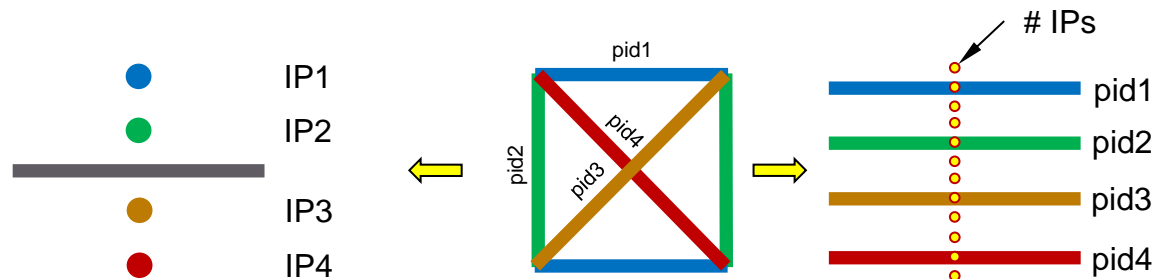
- four Parts
- 10461 Beam Elements
- avg. length: 1.65 – 3.30 mm



Target Mesh:

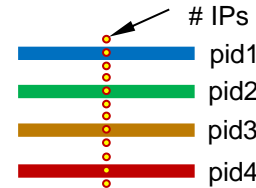
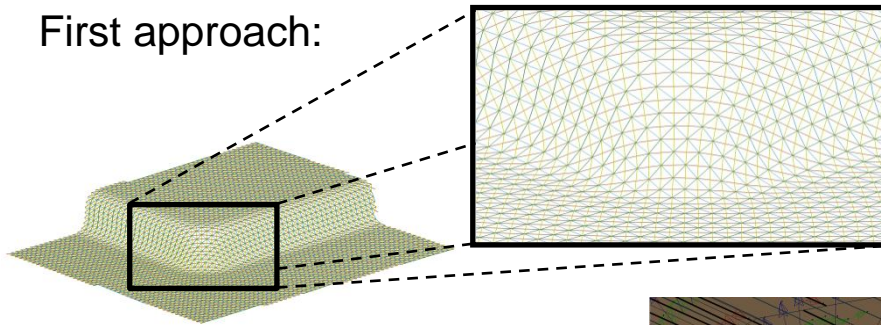
- one or four Parts
- 4x 300 Shell Elements
- avg. length: 1.80 – 18.40 mm

Homogenization strategy:

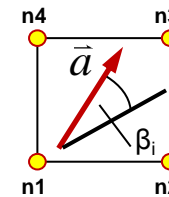


Mapping of material directions on different target meshes

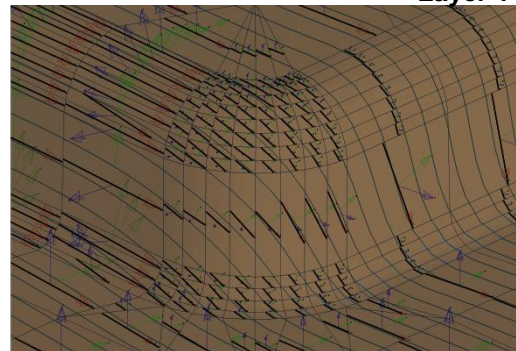
First approach:



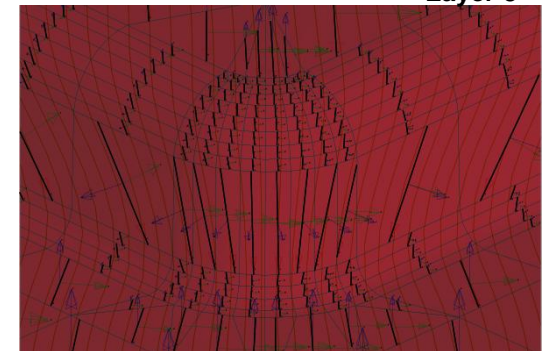
AOPT = 2



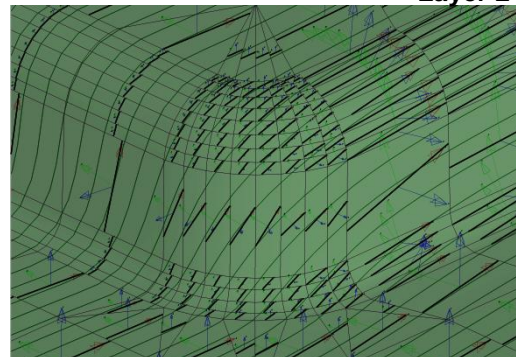
Layer 1



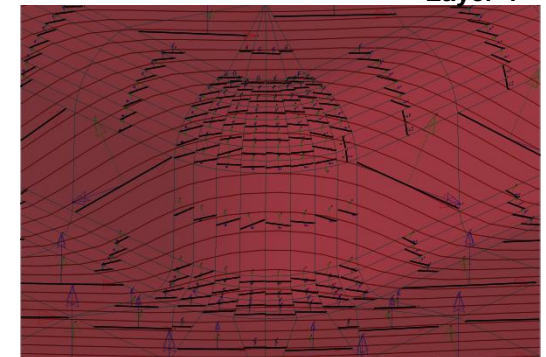
Layer 3



Layer 2



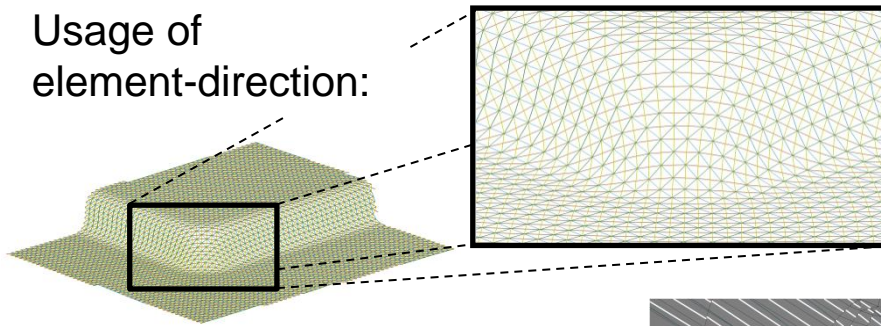
Layer 4



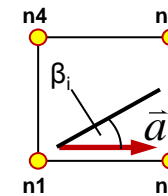
- Vector \vec{a} is given directly by the orientations of the beam elements
- *ELEMENT_SHELL_-COMPOSITE or *PART_COMPOSITE
- Main disadvantage:
 - Each element get's an assigned material card -> 300 elements eq. 300 diff. material cards
 - good as a first tryout, but not relevant for any kind of simulation

Mapping of material directions on different target meshes

Usage of
element-direction:

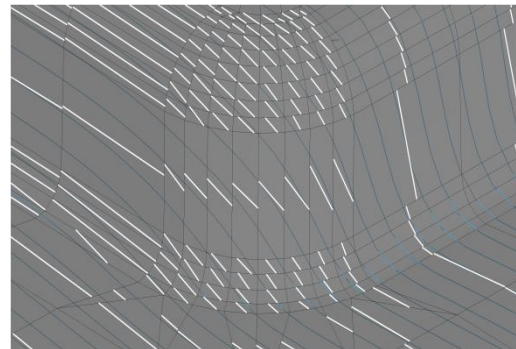


AOPT = 0

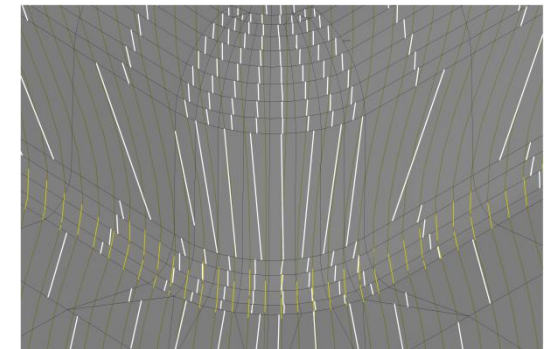


- Vector \vec{a} is given directly by the element orientation
- *ELEMENT_SHELL_-COMPOSITE or *PART_COMPOSITE
- Identification of β_i is a little bit more complicated than writing fiber orientation directly into the material card
- Only one material card per part!
Relevant for crash simulations...

IP - 1



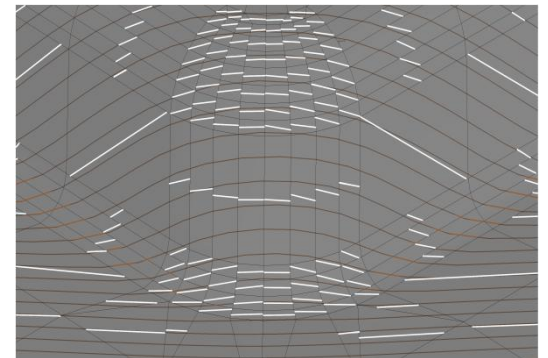
IP - 3



IP - 2

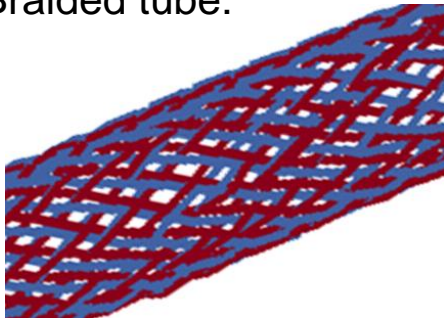


IP - 4

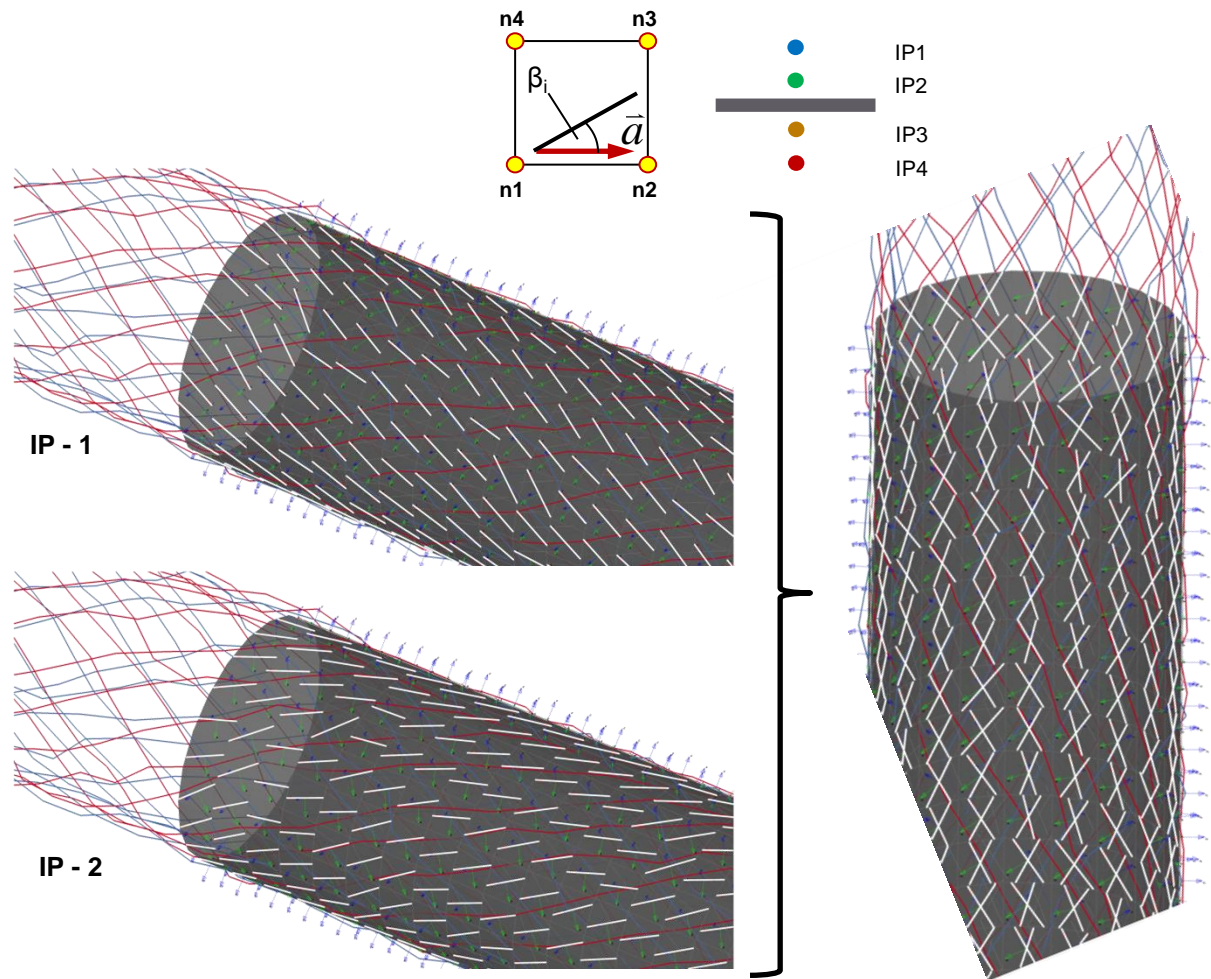


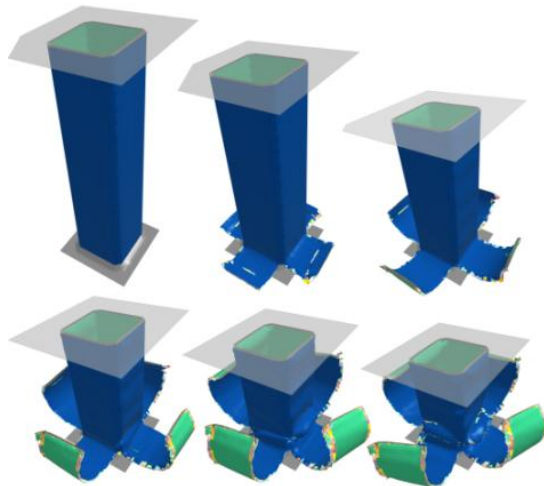
Mapping of material directions on different target meshes

Braided tube:



- Vector \vec{a} is given directly by the element orientation
- *ELEMENT_SHELL_-COMPOSITE or *PART_COMPOSITE
- Identification of β_i is a little bit more complicated than writing fiber orientation directly into the material card
- Only one material card per part!
Relevant for crash simulations...





Serviceability
Crashworthiness

Skipped!!

Summary

- Solutions to simulate various different production techniques have been presented.
- Main target is the prediction of constitutive properties (matrix/fiber) during the process and in the final product
- Mapping towards coarser meshes for subsequent servicability simulations (i.e. crashworthiness) has been addressed

Open issues/not discussed:

- Modeling techniques and calibration in crashworthiness
- Assessment of predictiveness of such models
- This will be the target of future work: ARENA2036, T-PULT, Swim-RTM,

The present work was partially supported by the German Federal Ministry of Education and Research within the cooperative project „*T-Pult*“ by grant #02PJ2186.

FIN