

Thorough Study of Short Fiber Reinforced Composites: from Micro-CT to Structural Analysis

C. Liebold¹, Dr.-Ing. A. Haufe¹, Dr.-Ing. B. Lauterbach²

¹ DYNAmore GmbH

² Adam Opel AG

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Fachkongress Composite Simulation
Fellbach, GER



Wir leben Autos.

DYNA
MORE

AGENDA

- COMPANY PRESENTATION
- PROCESS CHAIN OVERVIEW
- EXPERIMENTAL STUDY
- MOLDFLOW AND CALIBRATION
- *MAT_157 - MATERIAL CALIBRATION AND DATA MAPPING
- RESULTS
- OUTLOOK AND CONCLUSION

COMPANY PRESENTATION



DYNAmore GmbH

Gesellschaft für
FEM-Ingenieurdienstleistungen

Stuttgart – Berlin - Dresden

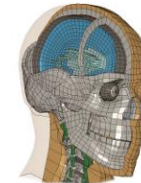
Linköping - Gothenburg - Zurich - Torino - Paris

Industriestraße 2
D-70565 Stuttgart

Tel. 07 11 - 45 96 00 - 0
Fax 07 11 - 45 96 00 - 29
e-mail: info@dynamore.de
Internet: www.dynamore.de



ARUP



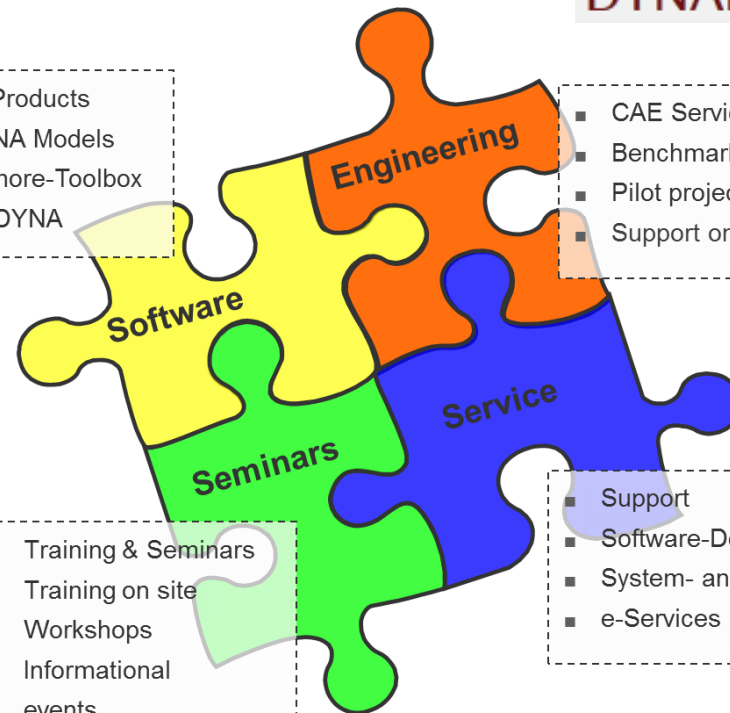
digimat

FEMZIP

DYNAFORM™

- LSTC Products
- LS-DYNA Models
- DYNAmore-Toolbox for LS-DYNA

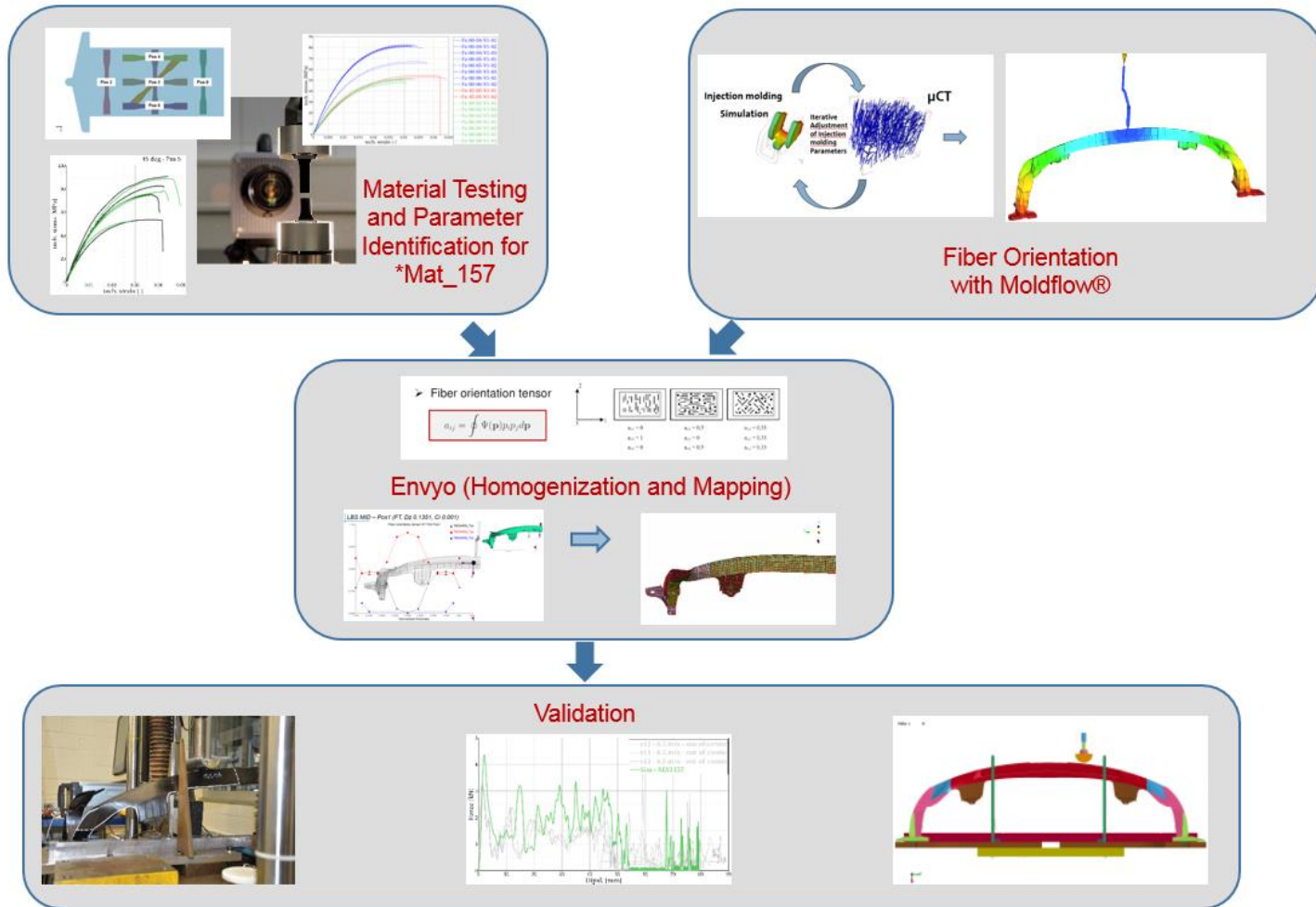
- CAE Services
- Benchmarking
- Pilot projects
- Support on site



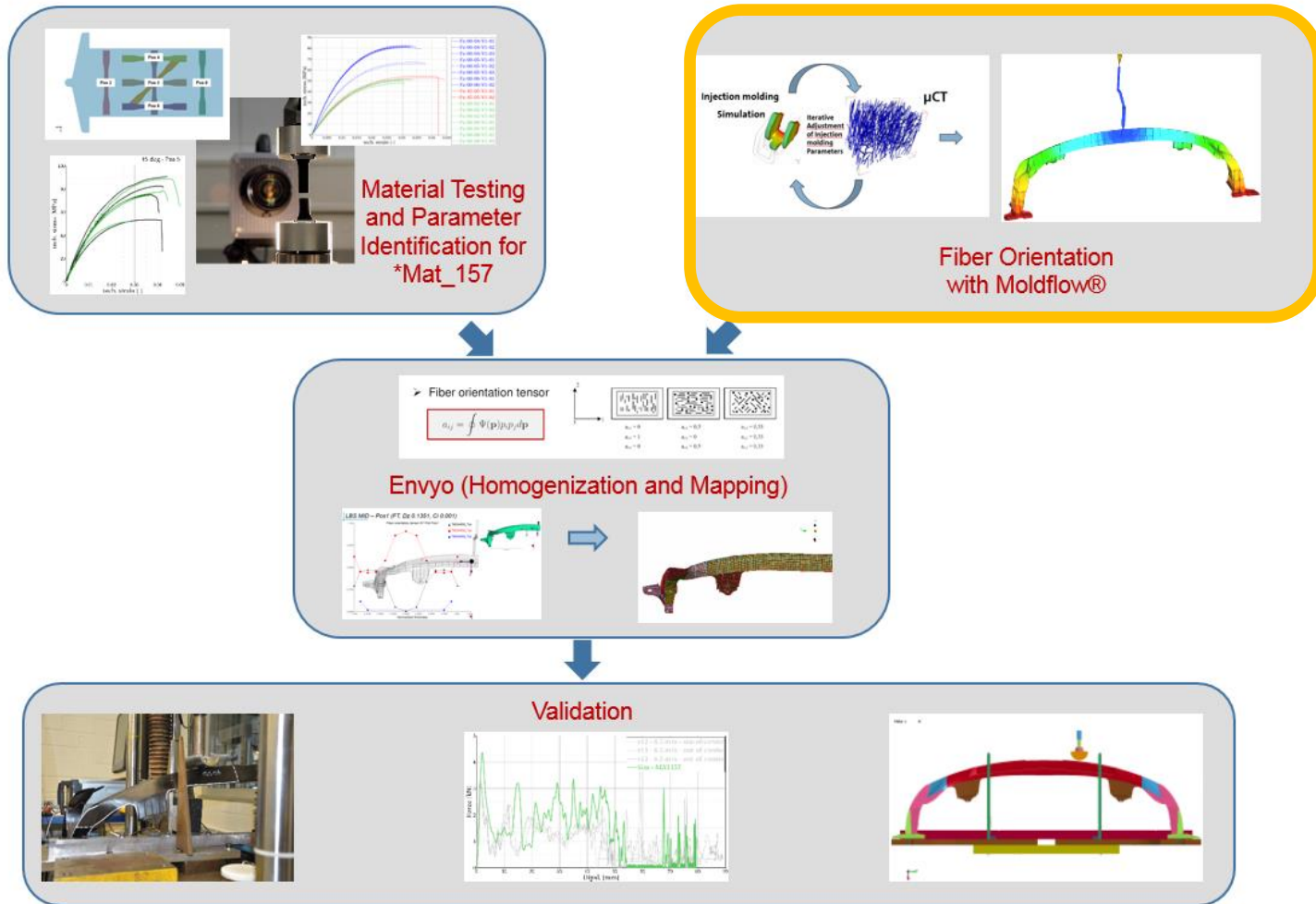
- Training & Seminars
- Training on site
- Workshops
- Informational events

- Support
- Software-Development
- System- and Processintegration
- e-Services

PROCESS CHAIN OVERVIEW



PROCESS CHAIN OVERVIEW



EXPERIMENTAL STUDY

- μ -CT – scan analysis @ 9 different positions on the plate
- μ -CT – scan analysis @ 6 different positions on the component
- position 5 chosen for Moldflow calibration
- evaluation on position 9 on the plate and on the component positions

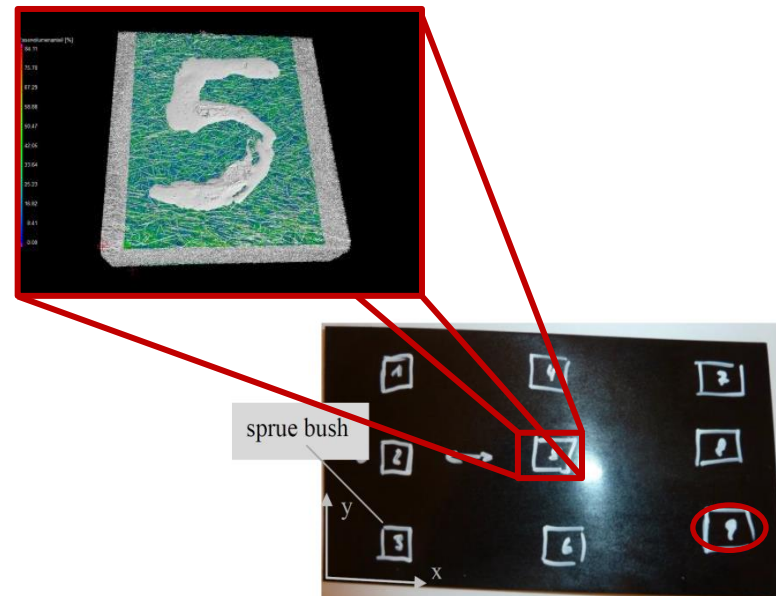


Fig. 1: Positions of specimen for CT-Scan.

MOLDFLOW ANALYSIS AND CALIBRATION

■ two different Moldflow approaches were evaluated:

■ Folgar-Tucker method:

■ varied parameters:

- fiber interaction coefficient: C_i
- thickness moment of interaction (for mid-plane problems): D_z

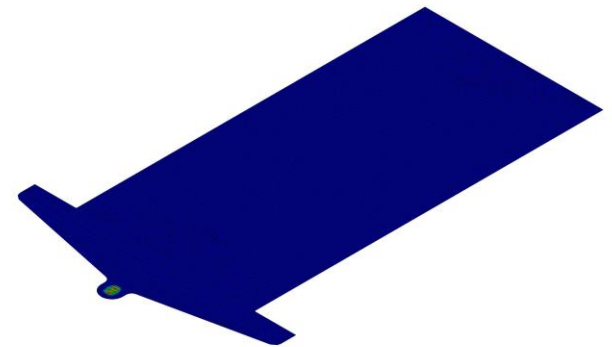
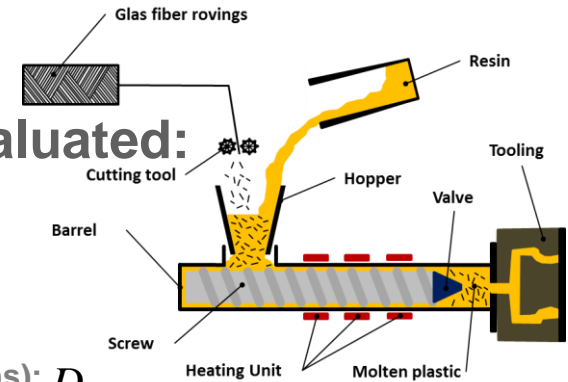
$$\frac{Da_{ij}}{Dt} = -\frac{1}{2}(\omega_{ik}a_{kj} - a_{ik}\omega_{kj}) + \frac{1}{2}\lambda(\dot{\gamma}_{ik}a_{kj} + a_{ik}\dot{\gamma}_{kj} - 2a_{ijkl}\dot{\gamma}_{kl}) + 2C_i\dot{\gamma}[\delta_{ij} - (2 + D_z)a_{ij}]$$

■ Reduced Strain Closure (RSC):

■ varied parameters:

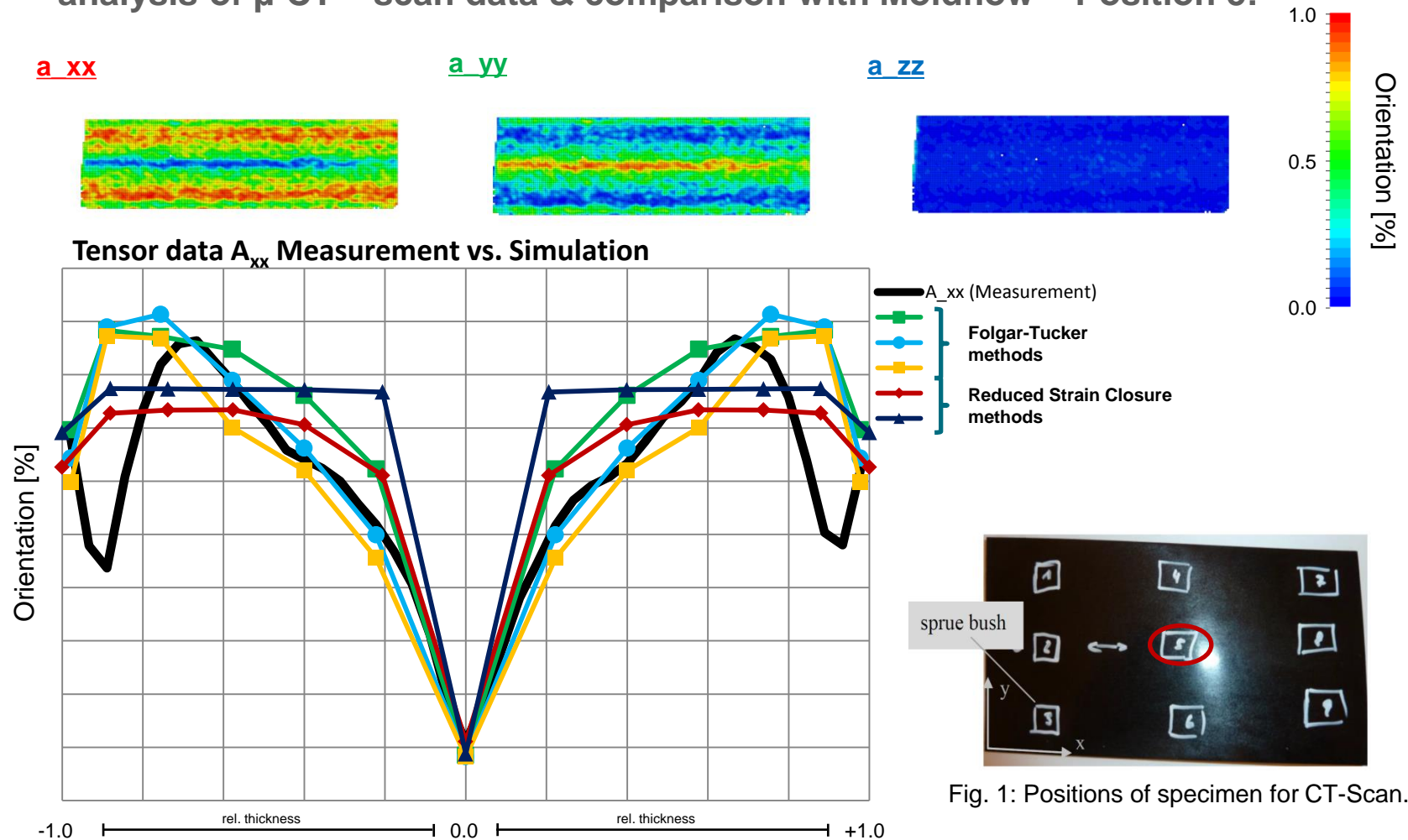
- fiber interaction coefficient: C_i
- scalar factor κ , Folgar-Tucker method: $\kappa \rightarrow 1$

$$\begin{aligned} \frac{Da_{ij}}{Dt} = & -\frac{1}{2}(\omega_{ik}a_{kj} - a_{ik}\omega_{kj}) \\ & + \frac{1}{2}\lambda(\dot{\gamma}_{ik}a_{kj} + a_{ik}\dot{\gamma}_{kj} - 2[a_{ijkl} + (1 - \kappa)(L_{ijkl} - M_{ijmn}a_{mnkl}]\dot{\gamma}_{kl}) \\ & + 2\kappa C_i\dot{\gamma}(\delta_{ij} - 3a_{ij}) \end{aligned}$$



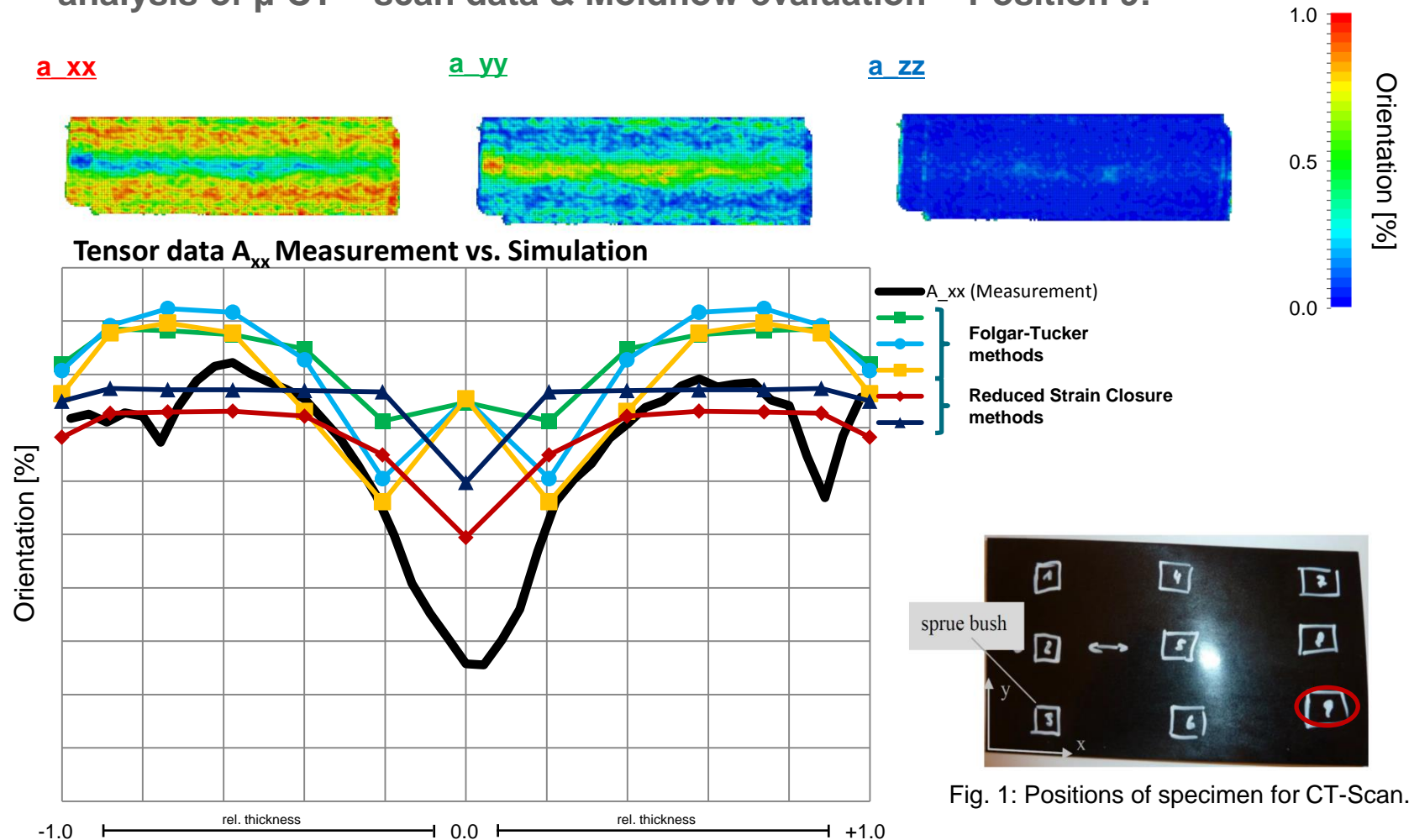
MOLDFLOW ANALYSIS AND CALIBRATION

- analysis of μ -CT – scan data & comparison with Moldflow – Position 5:



MOLDFLOW ANALYSIS AND CALIBRATION

- analysis of μ -CT – scan data & Moldflow evaluation – Position 9:



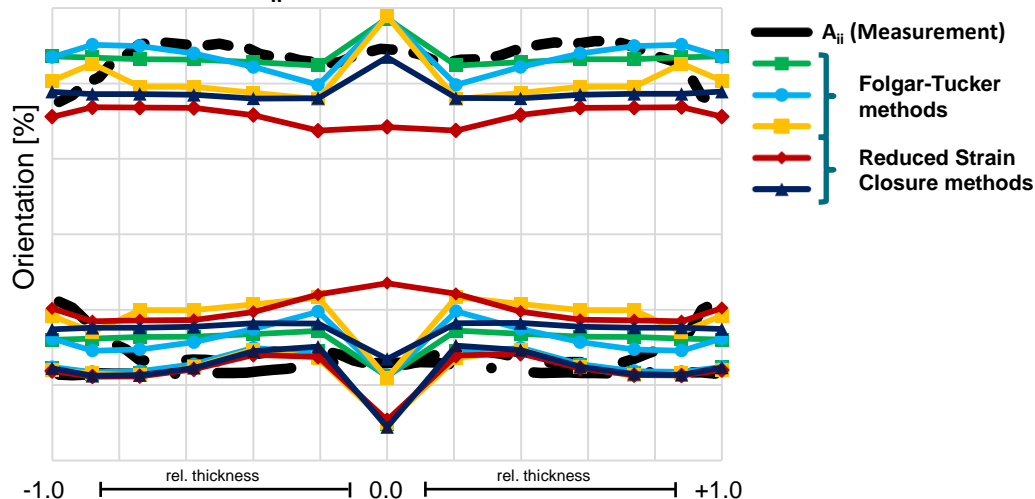
MOLDFLOW ANALYSIS AND CALIBRATION

■ analysis of μ -CT – scan data & comparison with Moldflow:

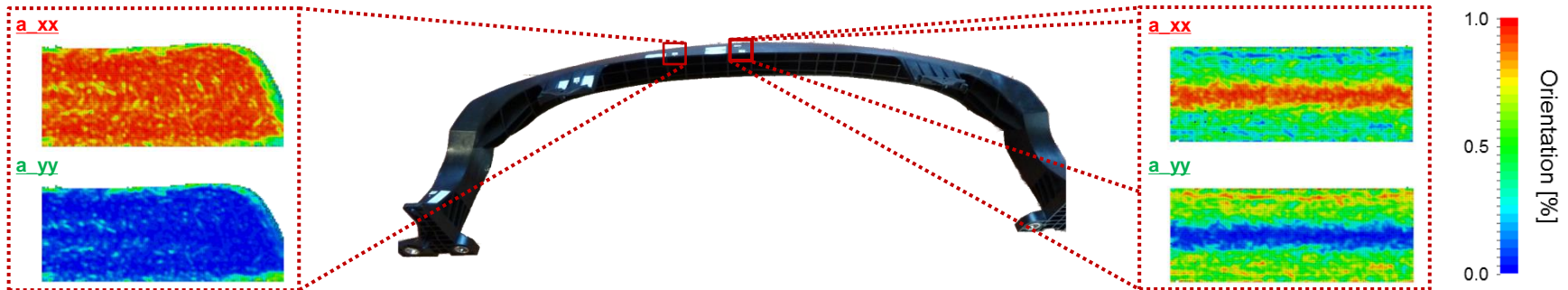
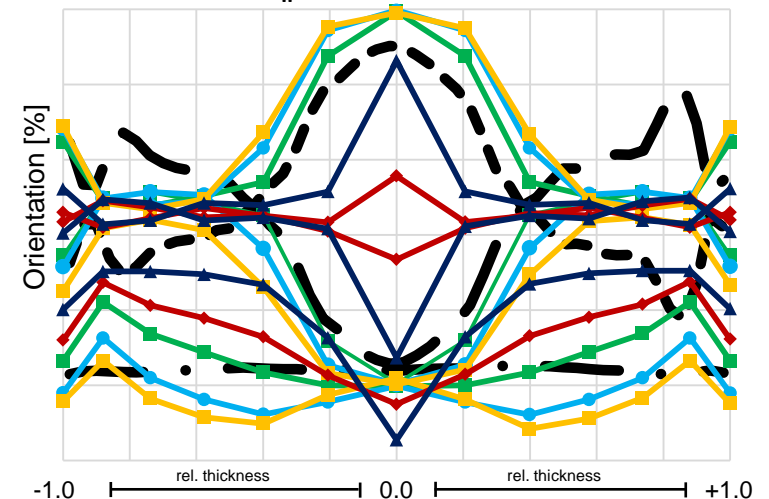
■ component position 3 :

component position 1:

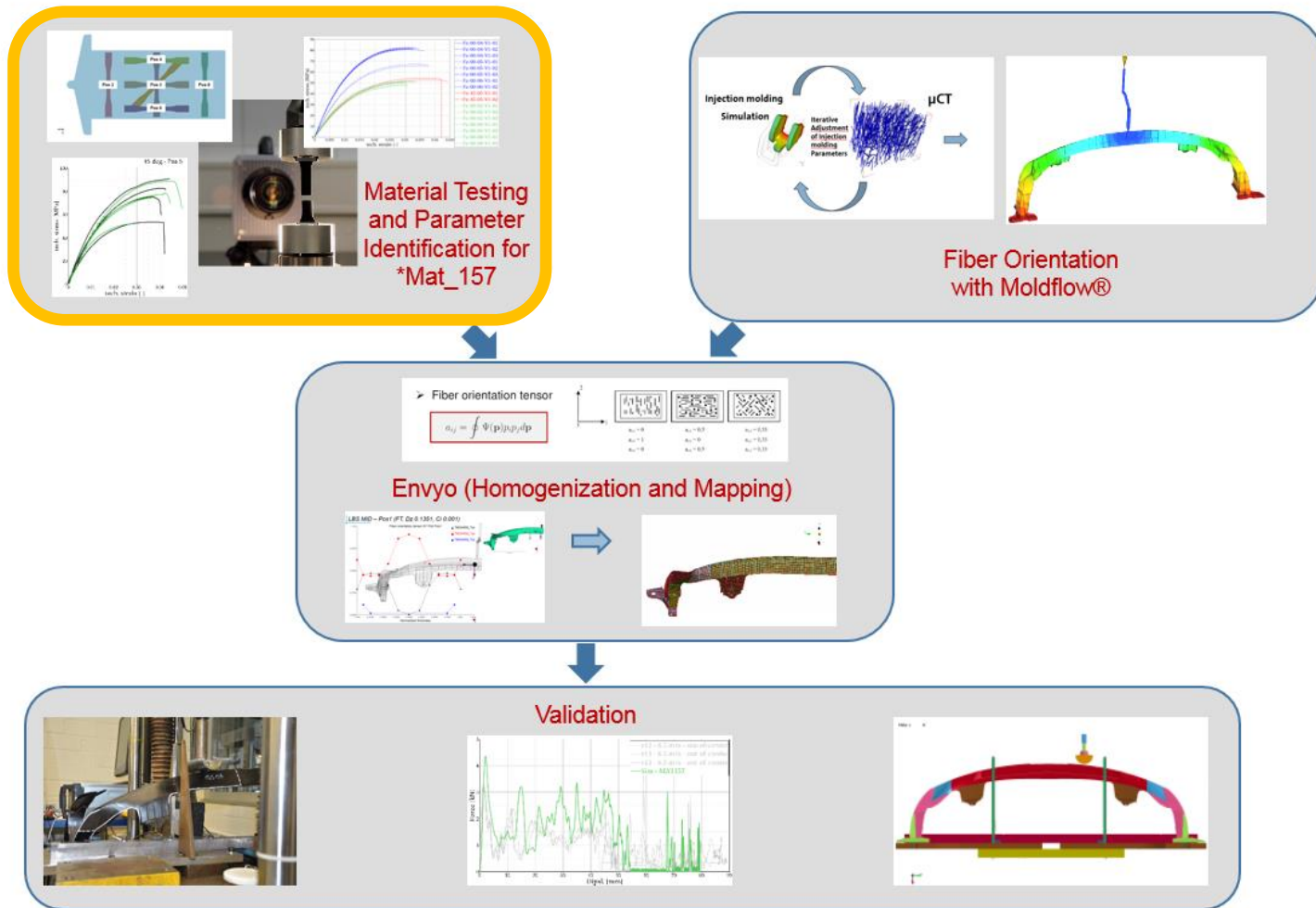
Tensor data A_{ii} vs. rel. thickness



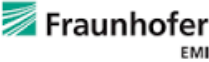
Tensor data A_{ii} vs. rel. thickness

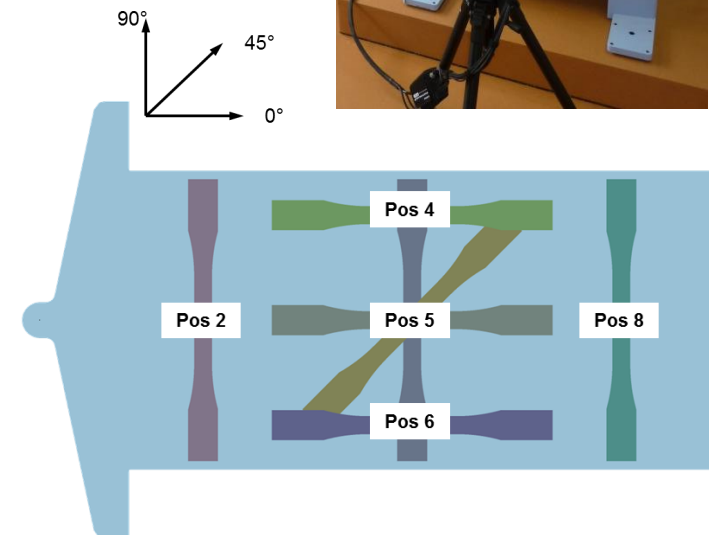


PROCESS CHAIN OVERVIEW



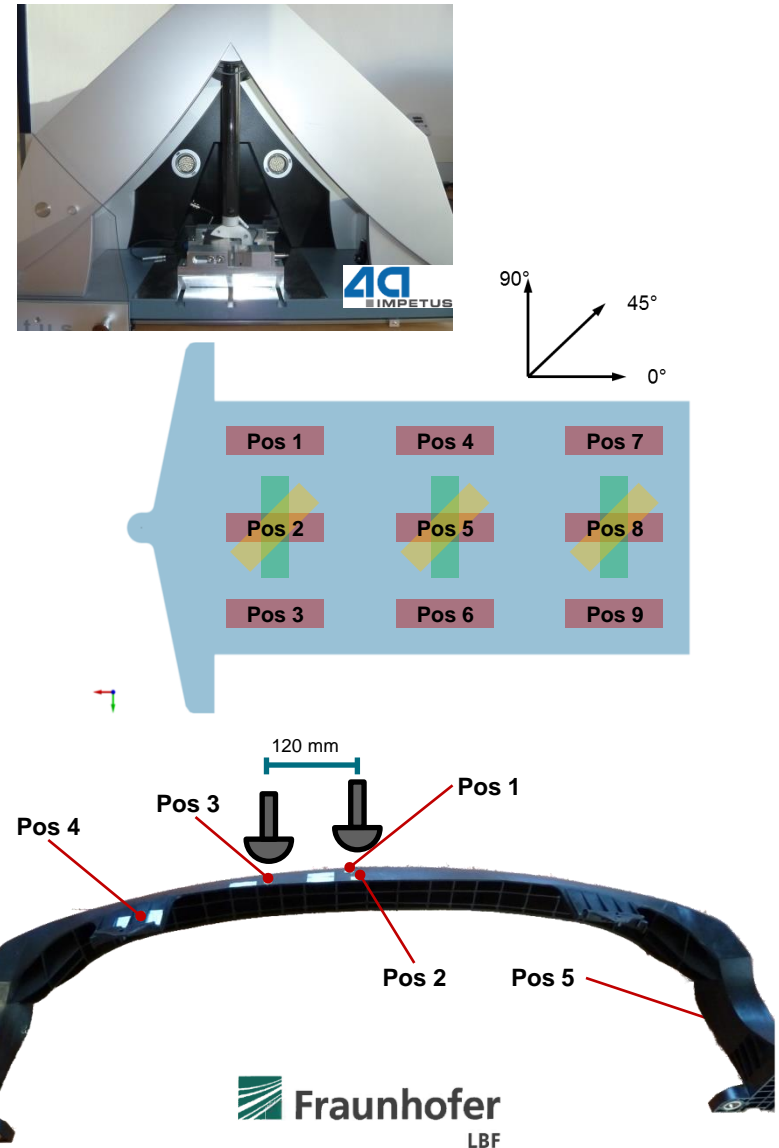
EXPERIMENTAL STUDY

- quasi-static (qs) and dynamic tensile tests
 - 5 different positions on a plate
 - 4 different strain rates:
 - 0.03 mm/s
 - 30 mm/s
 - 300 mm/s
 - 3000 mm/s
 - 3 different directions
-  Fraunhofer EMI
- position 5 from tensile specimen chosen for reverse engineering and material calibration
 - other positions used for evaluation purposes



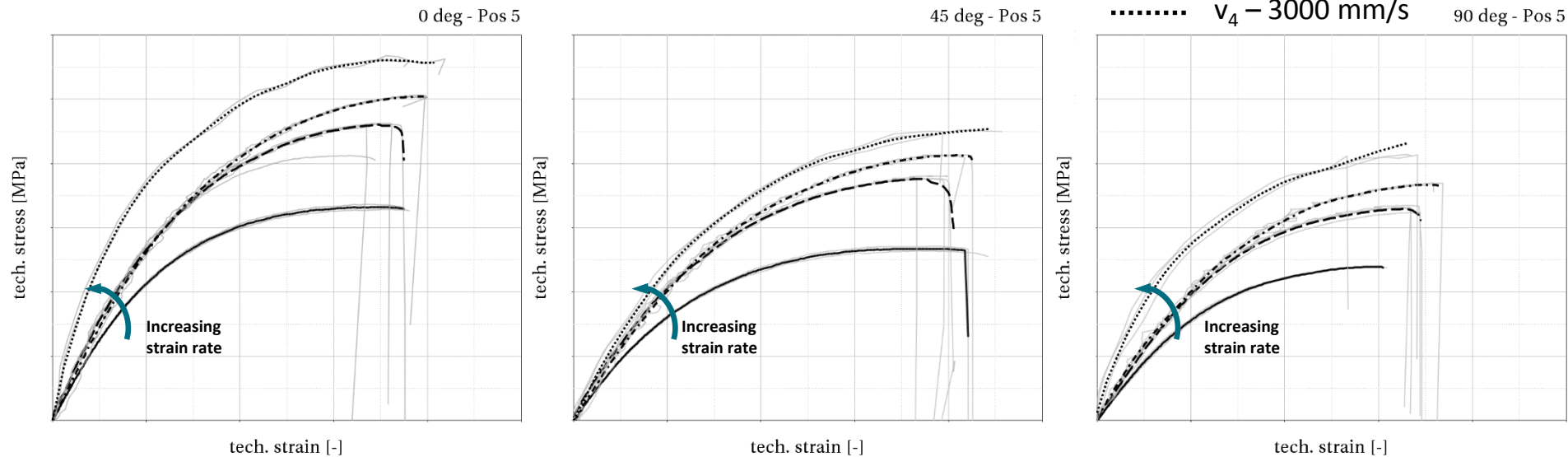
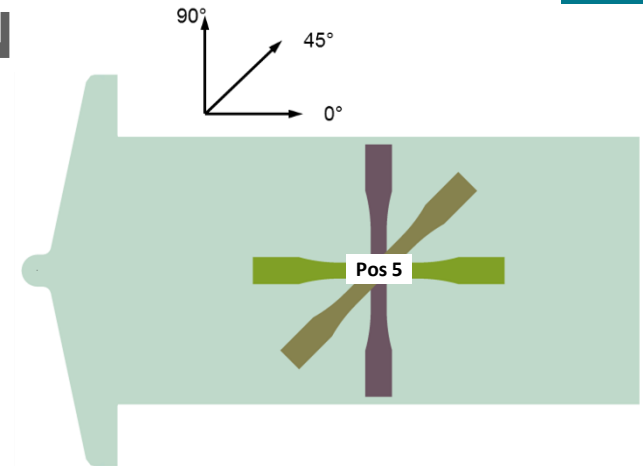
EXPERIMENTAL STUDY

- three point bending tests
 - 9 different positions
 - 3 different strain rates
 - 3 different directions
- qs and dynamic component tests
 - 5 different impact velocities
 - 2 different impact positions
- bending tests and component crushing used for validation
 - accuracy, calculation time, testing and modeling requirements for calibration



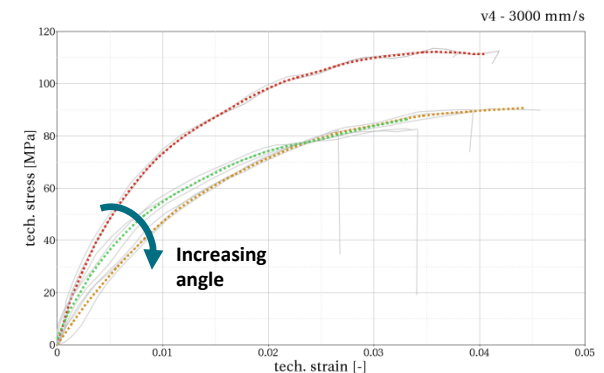
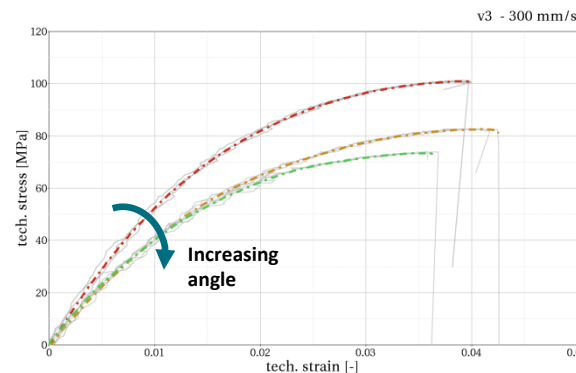
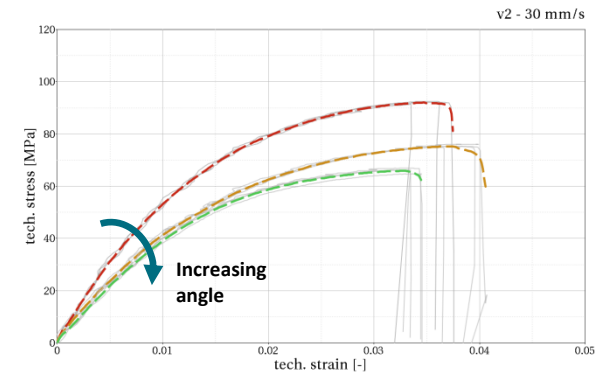
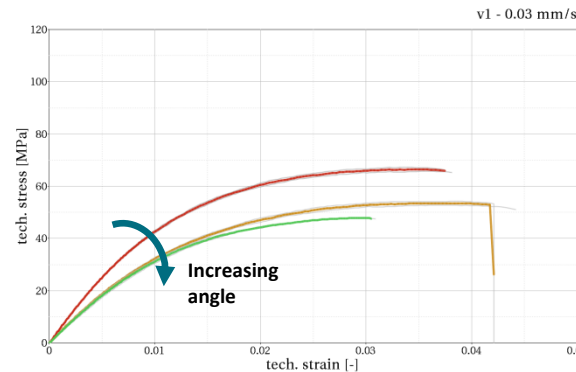
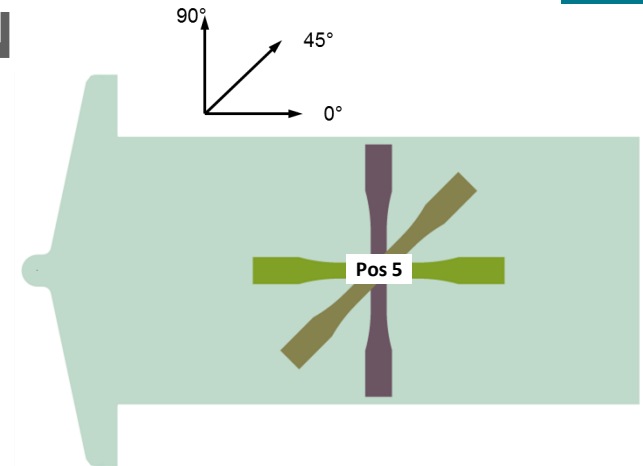
*MAT_157 MATERIAL CALIBRATION

- Experimental results – tensile specimen position 5
 - a high degree of visco-elasticity is observed



*MAT_157 MATERIAL CALIBRATION

- Experimental results – tensile specimen position 5
 - a high degree of visco-elasticity is observed
 - intersection 45° and 90° curve at highest strain rate



— 0 deg
— 45 deg
— 90 deg

*MAT_157 MATERIAL CALIBRATION

■ *MAT_ANISOTROPIC_ELASIC_PLASTIC (*MAT_157)

| | | | | | | | | |
|--------|-----|-----|------|------------------|------------------|-----|------|------------------|
| CARD 1 | mid | ro | sigy | lc ^{ss} | qr1 | cr1 | qr2 | cr2 |
| CARD 2 | c11 | c12 | c13 | c14 | c15 | c16 | c22 | c23 |
| CARD 3 | c24 | c25 | c26 | c33 | c34 | c35 | c36 | c44 |
| CARD 4 | c45 | c46 | c55 | c56 | c66 | r00 | r45 | r90 |
| CARD 5 | s11 | s22 | s33 | s12 | a ^{opt} | vp | | macf |
| CARD 6 | xp | yp | zp | a1 | a2 | a3 | | |
| CARD 7 | v1 | v2 | v3 | d1 | d2 | d3 | beta | i ^{his} |

- $IHS = a_3 \times 8 + a_2 \times 4 + a_1 \times 2 + a_0$, $a_i \in 0, 1$
- AOPT = 0, initialize orientation and stiffness tensor using history variables using *INITIAL_STRESS_SHELL
- No damage and failure model included -> use of *MAT_ADD_EROSION

*MAT_157 MATERIAL CALIBRATION

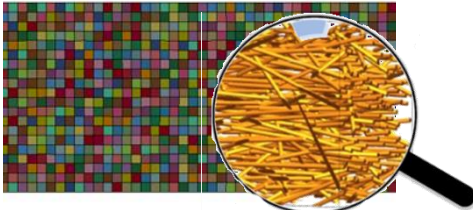
■ *INITIAL_STRESS_SHELL

| CARD 1 | eid | nplane | nthick | nhisv | ntensor | large | nthint | nthhsv |
|--------|---------------|---------------|---------------|---------------|---------------|---------------|---------------|---------------|
| CARD 2 | t | sigxx | sigyy | sigzz | sigxy | sigyz | sigzx | eps |
| CARD 3 | hisv1= q_1 | hisv2= q_2 | #3= C_{11} | #4= C_{12} | #5= C_{13} | #6= C_{14} | #7= C_{15} | #8= C_{16} |
| CARD 4 | #9= C_{22} | #10= C_{23} | #11= C_{24} | #12= C_{25} | #13= C_{26} | #14= C_{33} | #15= C_{34} | #16= C_{35} |
| CARD 5 | #17= C_{36} | #18= C_{44} | #19= C_{45} | #20= C_{46} | #21= C_{55} | #22= C_{56} | #23= C_{66} | #24=TBID |

- example for shells , IHIS=11 ($a_3 = 1$, $a_1 = 1$, $a_0 = 1$)
 \rightarrow NHISV=2+21+1=24

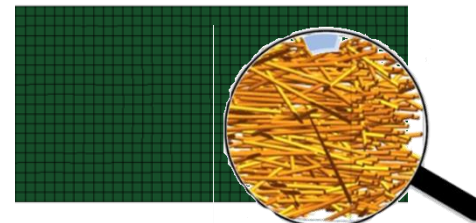
| flag | description | variables | number |
|-------|-------------------------------|--------------------------|--------|
| a_0 | material directions | q_1, q_2 | 2 |
| a_1 | anisotropic elastic stiffness | C_{ij} | 21 |
| a_2 | anisotropic plasticity | r_{00}, r_{45}, r_{90} | 3 |
| a_3 | hardening curve | LCSS | 1 |

In material card



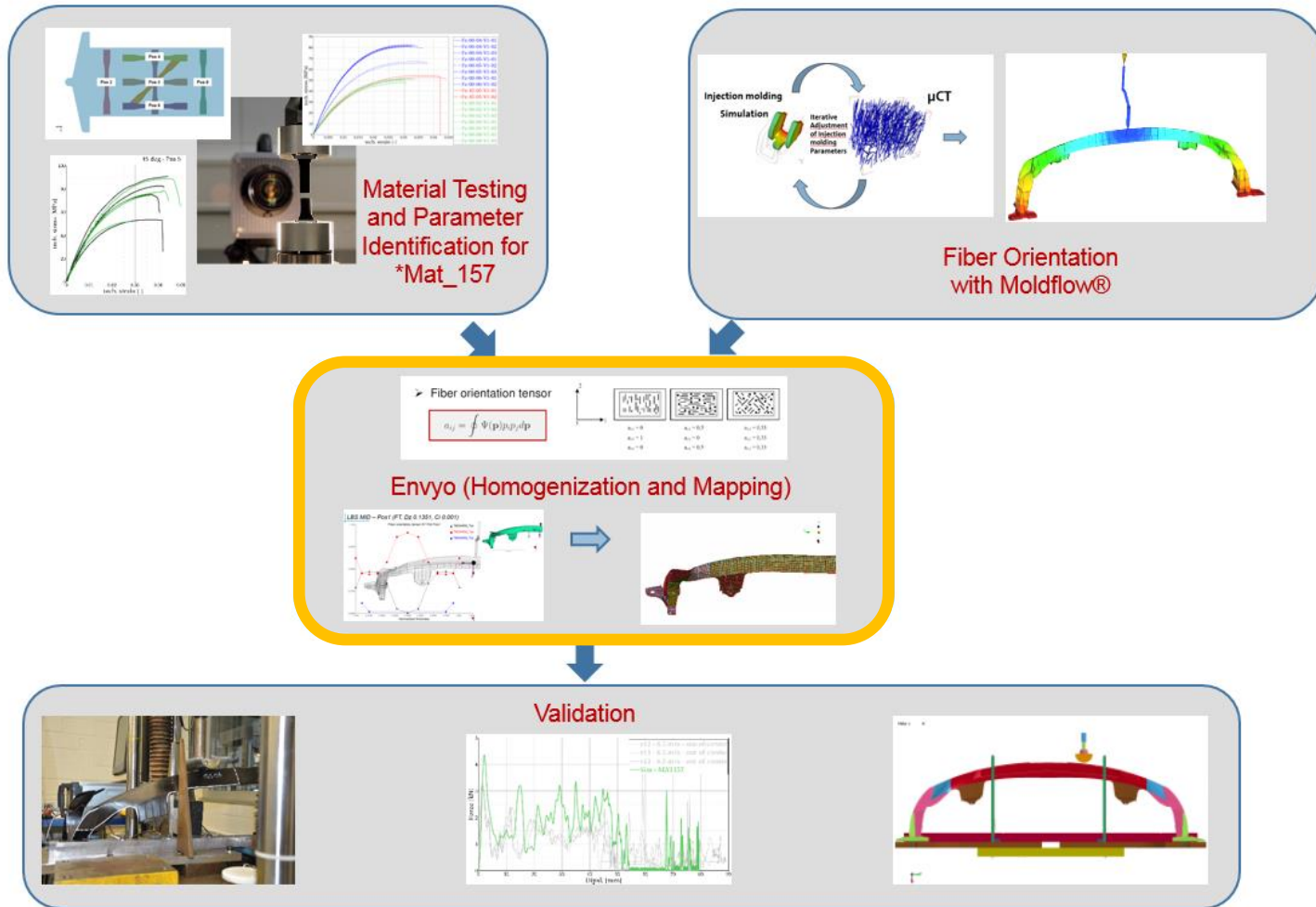
Needs individual part definition for every element

With *INITIAL_STRESS_SOLID



Only one part definition for whole component.

PROCESS CHAIN OVERVIEW



*MAT_157 MATERIAL CALIBRATION

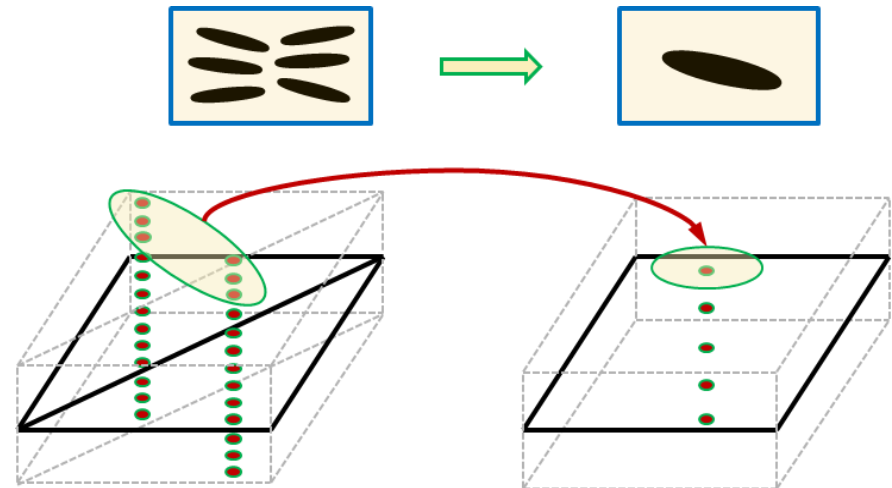
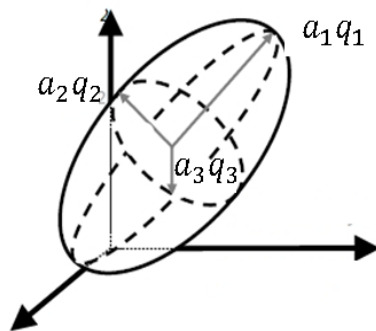
■ Data mapping using Envyo®:

■ Input:

- unit systems for mesh transformation and scaling
- source and target files, moldflow® *.xml - file
- fiber and matrix elastic properties
- target thickness, element type and number of through-thickness integration points
- geometrical parameters (inclusion shape, aspect ratio)

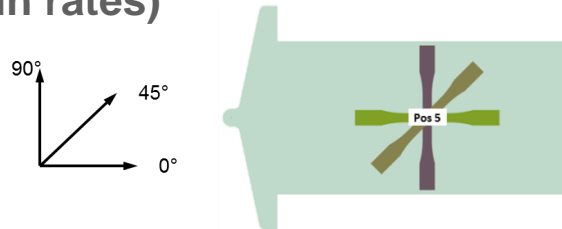
fiber-orientation tensor 2nd order α :

- eigenvectors q_i (main fiber directions)
- eigenvalues a_i (orientation probability)

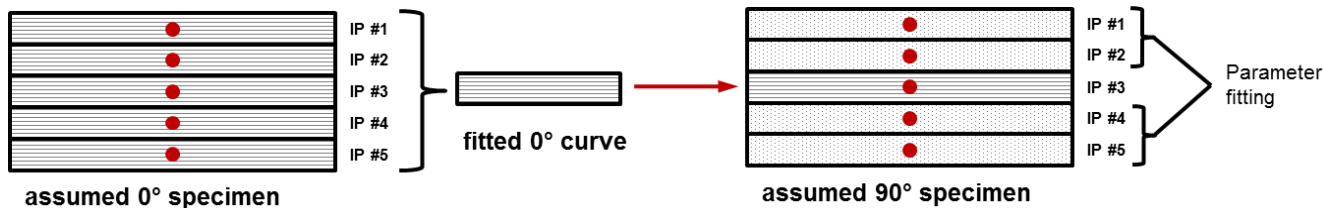


*MAT_157 MATERIAL CALIBRATION

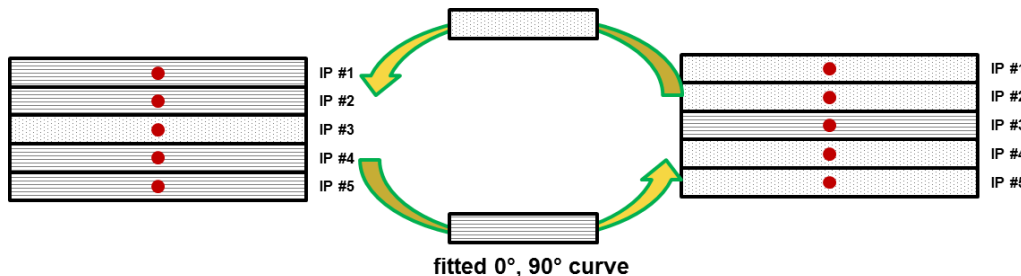
- Evaluate stiffness parameters of mapping input on experimental data (multi-directions at multiple strain rates)



- Derive plasticity curve for 0° specimen ignoring the skin-core effect and use it for the 90° specimen as an input.

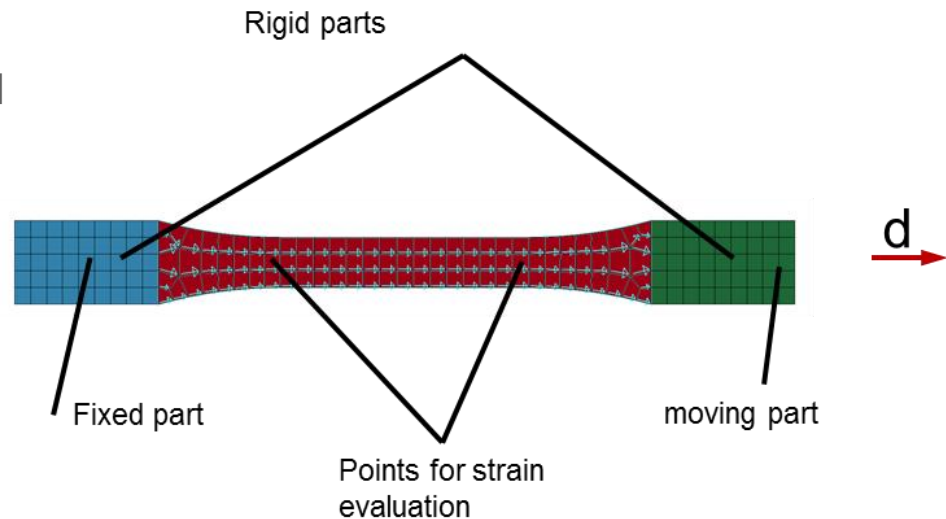
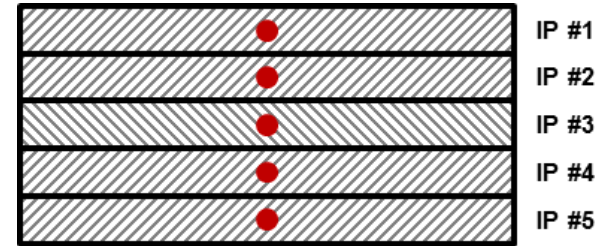


- Perform reverse engineering until results are satisfactory.



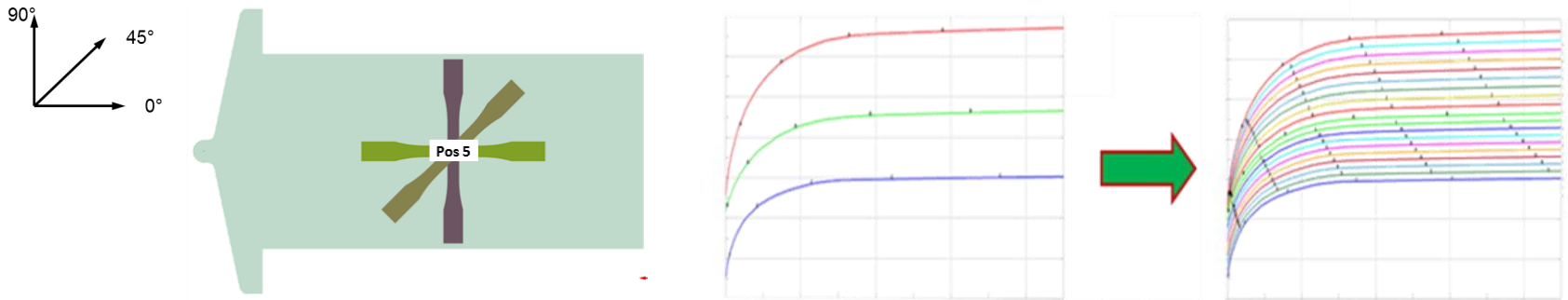
*MAT_157 MATERIAL CALIBRATION

- Repeat for multiple strain rates.
- Fit 45° curve independently.
- For proper data mapping, plasticity curves may not intersect.
- Finally, perform parameter fitting for damage and failure using *MAT_ADD_EROSION.
 - 0° failure is stress based
 - 90° failure is strain based
 - Evaluate on 45° results



*MAT_157 MATERIAL CALIBRATION

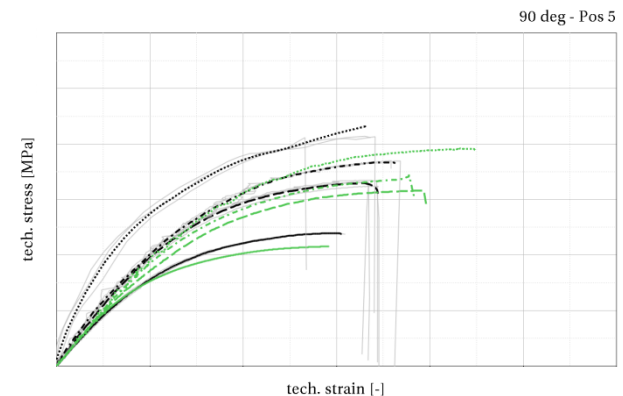
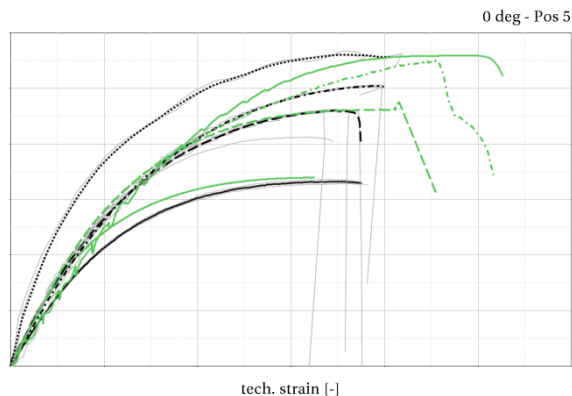
- Estimate remaining plasticity curves using linear interpolation.



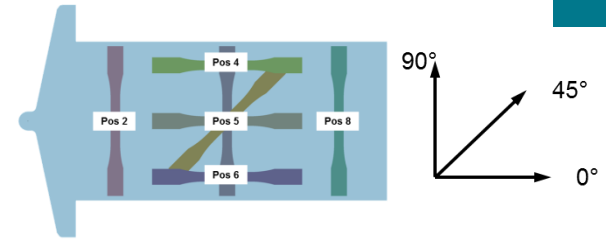
- Compare simulations and experimental results – pos 5.

— $v_1 - 0.03 \text{ mm/s}$
- - - $v_2 - 30 \text{ mm/s}$
- . - $v_3 - 300 \text{ mm/s}$
..... $v_4 - 3000 \text{ mm/s}$

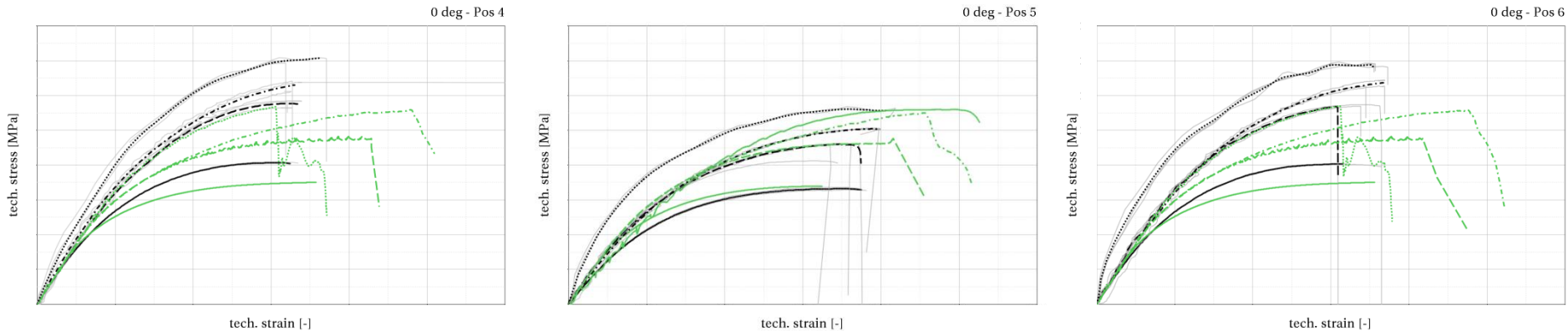
— experiment
— simulation



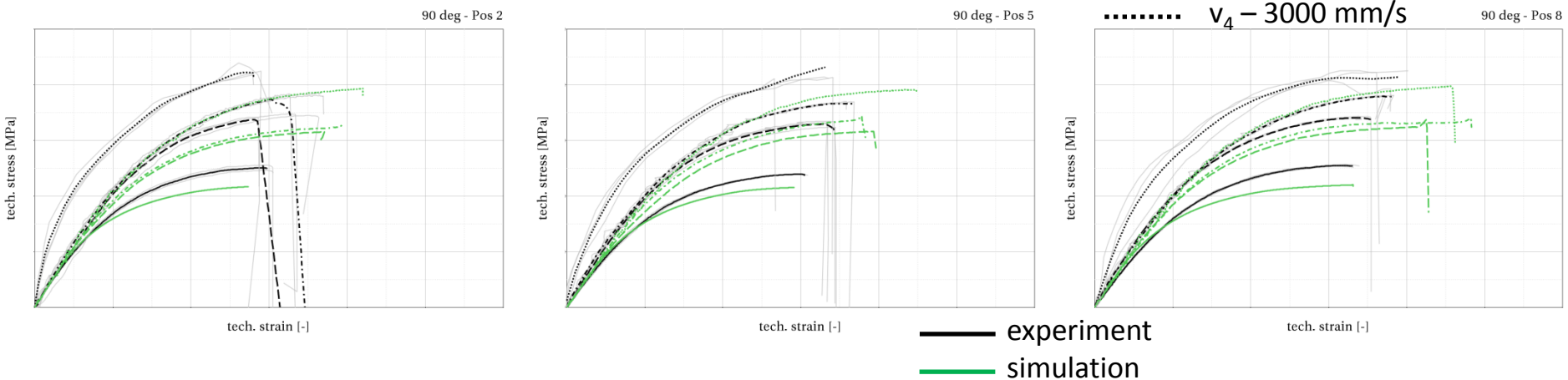
RESULTS TENSILE SPECIMEN



0° results, pos. 4, pos. 5 & pos. 6

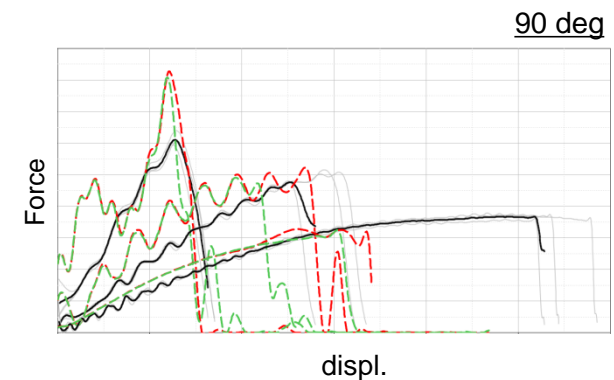
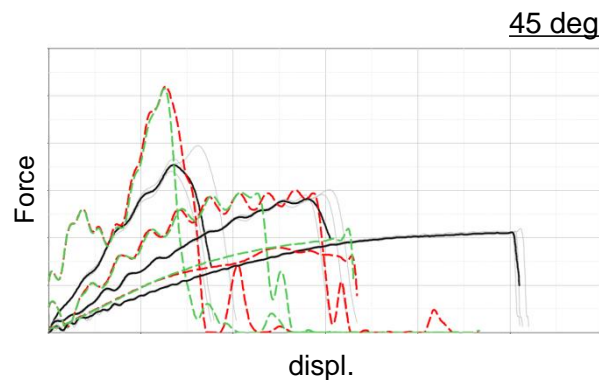
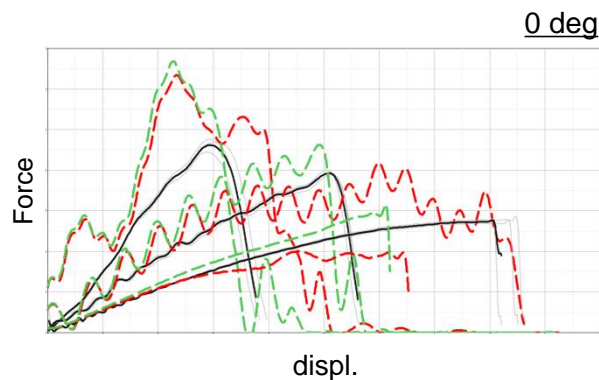
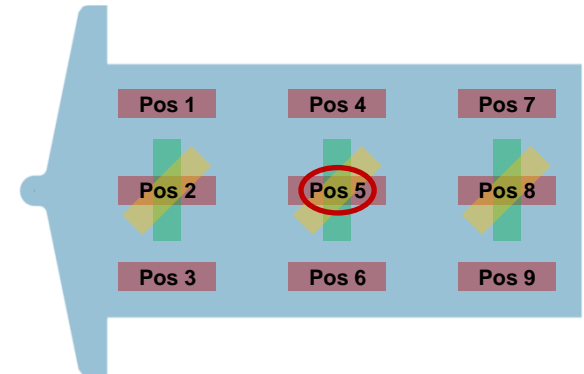
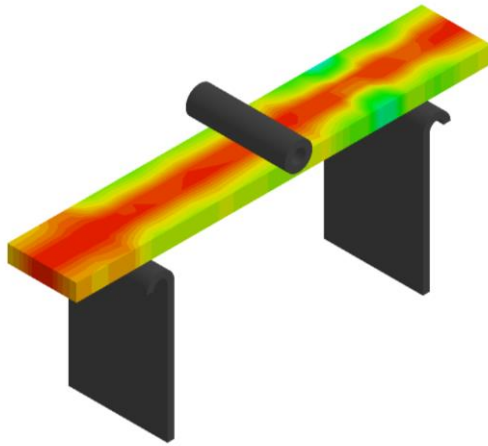


90° results, pos. 2, pos. 5 & pos. 8



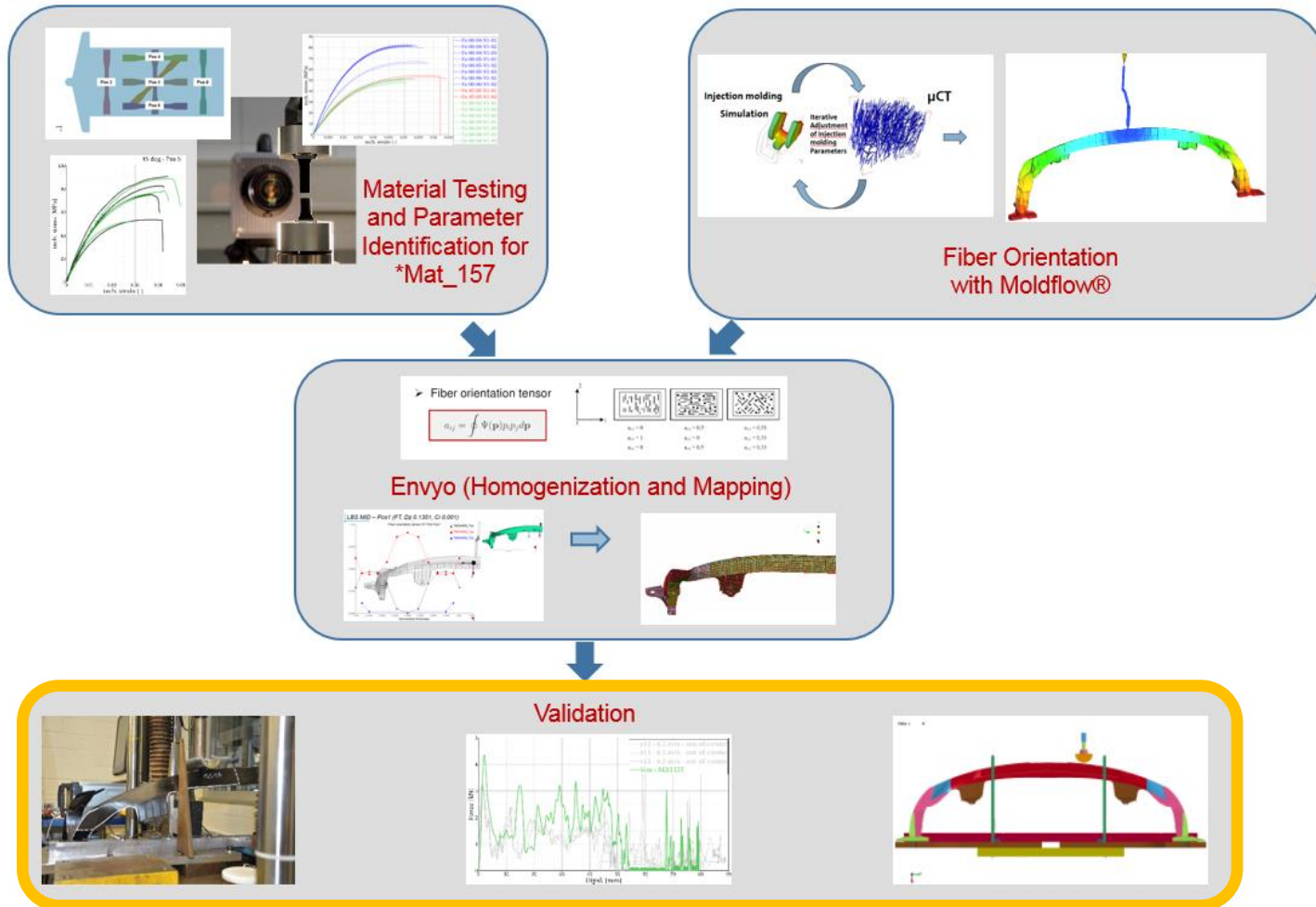
RESULTS TENSILE SPECIMEN

- Evaluate on three-point bending tests

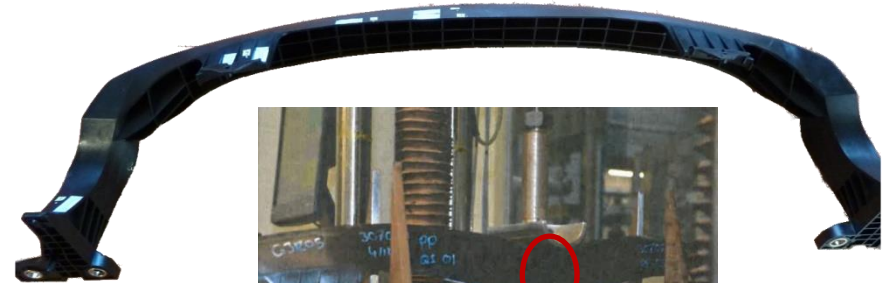


- Experiment
- *MAT_157 – simulation - ETYP 16
- *MAT_157 – simulation - ETYP 2

PROCESS CHAIN OVERVIEW

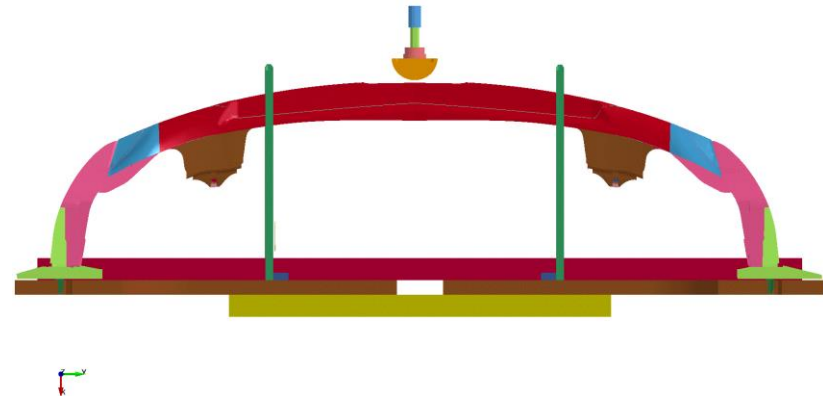
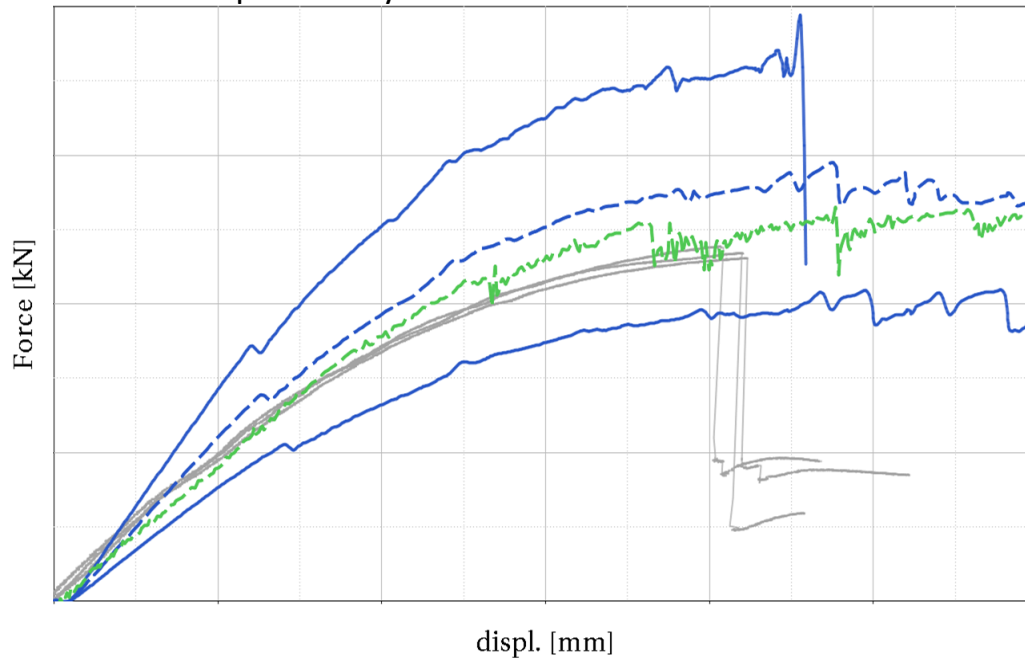


RESULTS COMPONENT



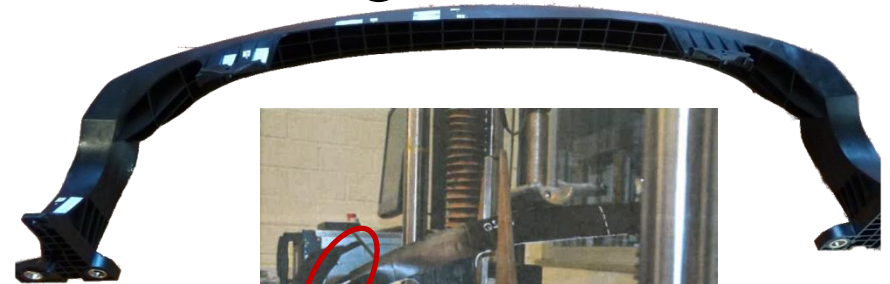
- qs – center position
 - breakage under the impactor
 - failure turned off for simulation

— experiment
— *MAT_024 – 0°, 90° & average
— implicit analysis



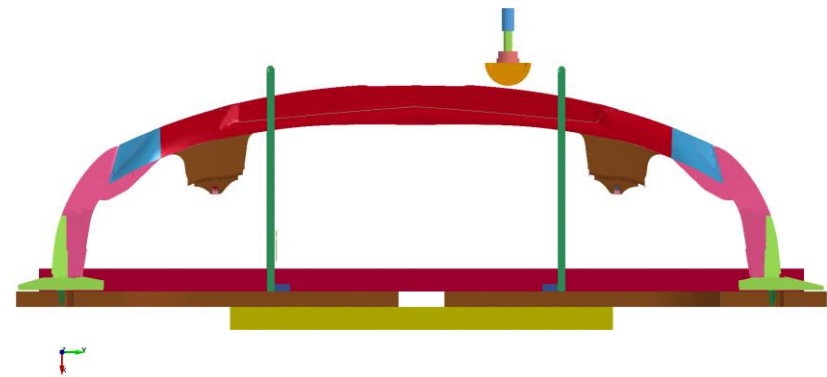
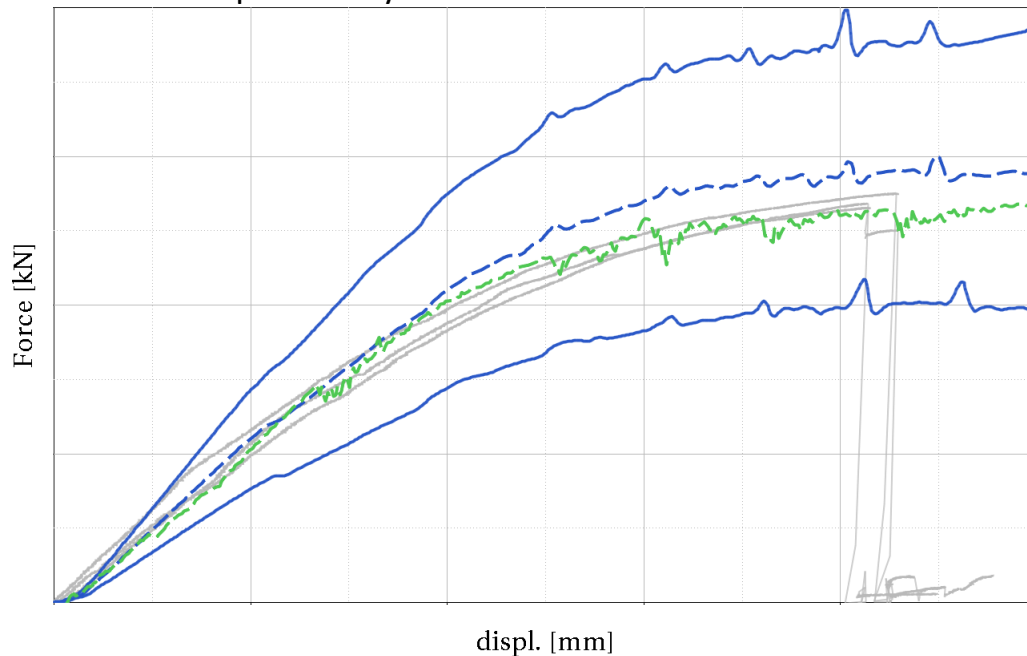
RESULTS COMPONENT

Fraunhofer
LBF



- qs – out-of-center position
 - breakage on the outside
 - failure turned off for simulation

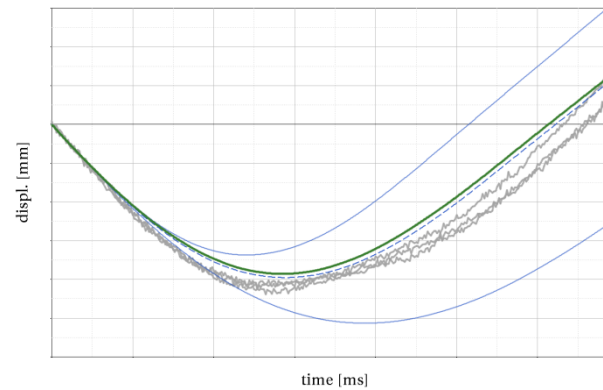
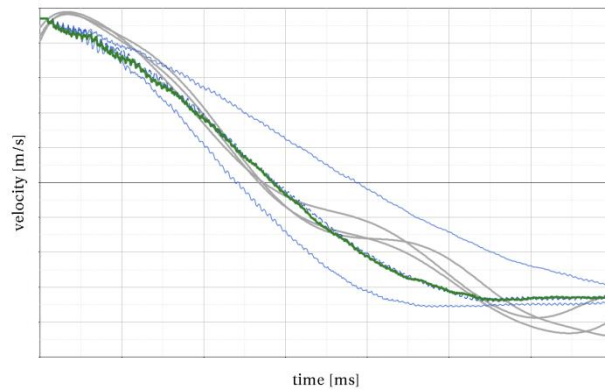
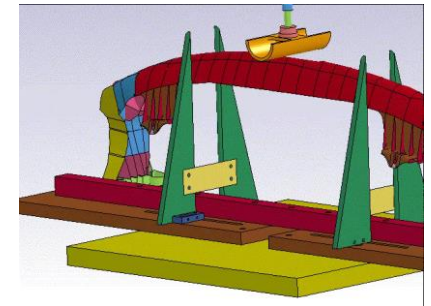
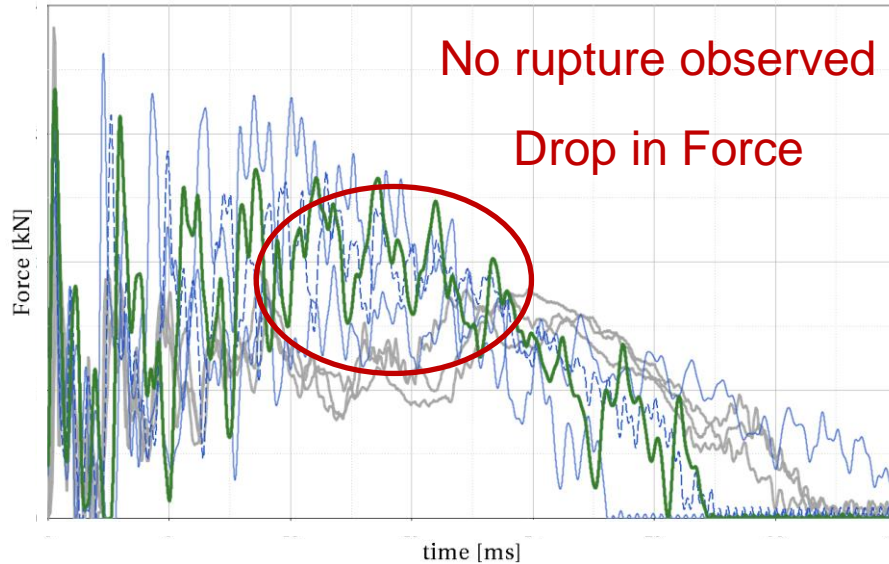
— experiment
— *MAT_024 – 0°, 90° & average
— implicit analysis



RESULTS COMPONENT

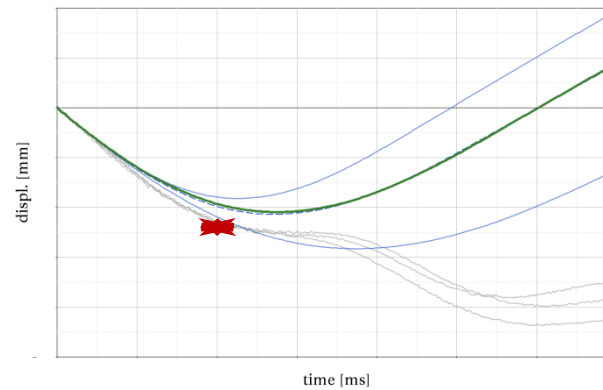
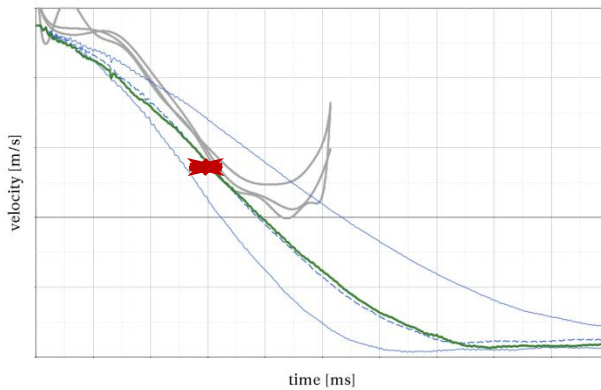
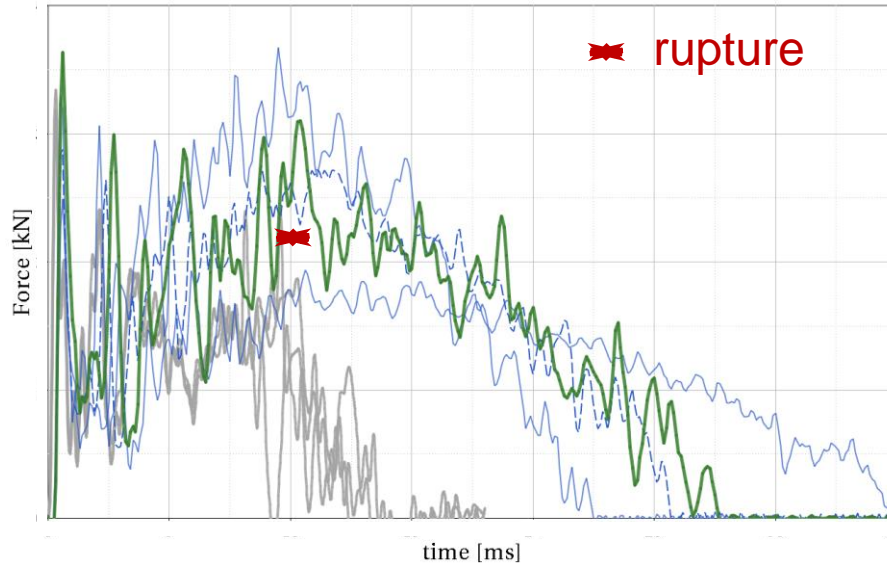
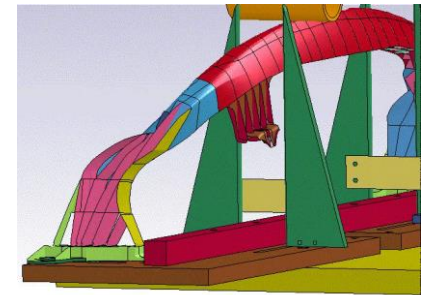
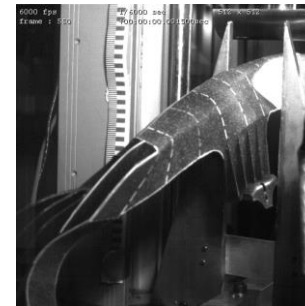


■ 5.5 – center position



— experiment
— *MAT_024 – 0°, 90° & average
— Simulation

RESULTS COMPONENT



— experiment
 — *MAT_024 – 0°, 90° & average
 — Simulation

CONCLUSION AND OUTLOOK

- A method to consider anisotropy induced through an injection molding process in fiber reinforced plastic components has been introduced.
- Results from Moldflow[®] simulations can be used for homogenization and calibration of the material model *MAT_157 in LS-DYNA, using the mapping software Envyo[®].
- The developed strategy has been evaluated of dumbbell specimen and on component level, with satisfying results for stiffness, displacement and velocity output.
- Further investigation will be made, using the newly introduced anisotropic failure criteria Tsai-Wu and Tsai-Hill within the *MAT_157 material model.

CONCLUSION AND OUTLOOK

■ *MAT_ANISOTROPIC_ELASIC_PLASTIC (*MAT_157)

| | | | | | | | | |
|--------|-----------|-----------|------------|------------------|-------------|-------------|------|---------------|
| CARD 1 | mid | ro | sigy | lc ^{ss} | qr1 | cr1 | qr2 | cr2 |
| CARD 2 | c11 | c12 | c13 | c14 | c15 | c16 | c22 | c23 |
| CARD 3 | c24 | c25 | c26 | c33 | c34 | c35 | c36 | c44 |
| CARD 4 | c45 | c46 | c55 | c56 | c66 | r00 | r45 | r90 |
| CARD 5 | s11 | s22 | s33 | s12 | aopt | vp | | macf |
| CARD 6 | xp | yp | zp | a1 | a2 | a3 | | EXTRA |
| CARD 7 | v1 | v2 | v3 | d1 | d2 | d3 | beta | ihis |
| CARD 8 | XT | XC | YT | YC | SXY | FF12 | | NCFAIL |
| CARD 9 | ZT | ZC | SYZ | SZX | FF23 | FF31 | | |

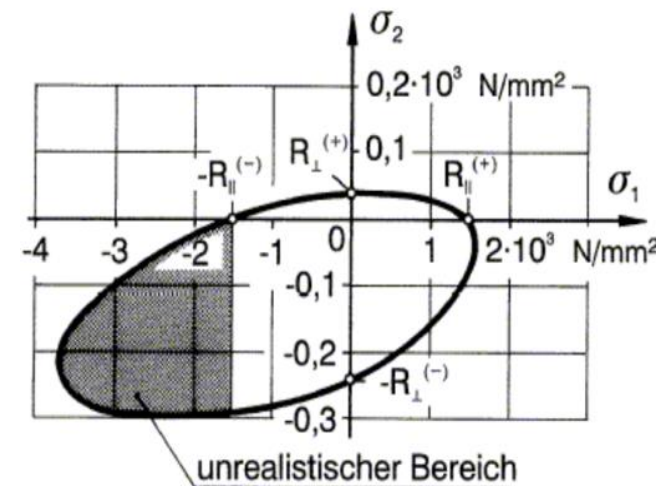
- **EXTRA** = 1 / 2 – triggers the usage of the Tsai-Wu or Tsai-Hill failure criterion
- Failure stresses can be defined strain rate dependent

CONCLUSION AND OUTLOOK

- **EXTRA** = 1 - Tsai-Wu failure criterion

$$\begin{aligned} & \left(\frac{1}{X_T} - \frac{1}{X_C} \right) \sigma_{aa} + \left(\frac{1}{Y_T} - \frac{1}{Y_C} \right) \sigma_{bb} + \left(\frac{1}{Z_T} - \frac{1}{Z_C} \right) \sigma_{cc} \\ & + \frac{1}{X_T \cdot X_C} \sigma_{aa}^2 + \frac{1}{Y_T \cdot Y_C} \sigma_{bb}^2 + \frac{1}{Z_T \cdot Z_C} \sigma_{cc}^2 + \frac{1}{S_{XY}^2} \sigma_{ab}^2 + \frac{1}{S_{YZ}^2} \sigma_{bc}^2 + \frac{1}{S_{ZX}^2} \sigma_{ca}^2 \\ & + 2 \cdot F_{12} \cdot \sigma_{aa} \cdot \sigma_{bb} + 2 \cdot F_{23} \cdot \sigma_{bb} \cdot \sigma_{cc} + 2 \cdot F_{31} \cdot \sigma_{cc} \cdot \sigma_{aa} < 1 \end{aligned}$$

with: $F_{12} = FF12 \cdot \sqrt{\frac{1}{X_T \cdot X_C \cdot Y_T \cdot Y_C}}$, $F_{23} = FF23 \cdot \sqrt{\frac{1}{Y_T \cdot Y_C \cdot Z_T \cdot Z_C}}$, $F_{31} = FF31 \cdot \sqrt{\frac{1}{Z_T \cdot Z_C \cdot X_T \cdot X_C}}$



CONCLUSION AND OUTLOOK

- **EXTRA** = 2 - Tsai-Hill failure criterion

$$(G + H) \cdot \sigma_{aa}^2 + (F + H) \cdot \sigma_{bb}^2 + (F + G) \cdot \sigma_{cc}^2 - 2H\sigma_{aa}\sigma_{bb} - 2F\sigma_{bb}\sigma_{cc} - 2G\sigma_{cc}\sigma_{aa} \\ + 2N\sigma_{ab}^2 + 2L\sigma_{bc}^2 + 2M\sigma_{ca}^2 < 1$$

$$\text{with: } G + H = \frac{1}{X_i^2}, \quad F + H = \frac{1}{Y_i^2}, \quad F + G = \frac{1}{Z_i^2}, \quad 2N = \frac{1}{SXY^2}, \quad 2L = \frac{1}{SYZ^2}, \quad 2M = \frac{1}{SZX^2}$$

$$H = 0.5 \cdot \left(\frac{1}{X_i^2} + \frac{1}{Y_i^2} - \frac{1}{Z_i^2} \right), \quad F = 0.5 \cdot \left(\frac{1}{Y_i^2} + \frac{1}{Z_i^2} - \frac{1}{X_i^2} \right), \quad G = 0.5 \cdot \left(\frac{1}{X_i^2} + \frac{1}{Z_i^2} - \frac{1}{Y_i^2} \right)$$

$$X_i = \begin{cases} XT & \text{if } \sigma_{aa} > 0 \\ XC & \text{if } \sigma_{aa} < 0 \end{cases}, \quad Y_i = \begin{cases} YT & \text{if } \sigma_{bb} > 0 \\ YC & \text{if } \sigma_{bb} < 0 \end{cases}, \quad Z_i = \begin{cases} ZT & \text{if } \sigma_{cc} > 0 \\ ZC & \text{if } \sigma_{cc} < 0 \end{cases}$$

